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GPU기반 AI 어플리케이션 개발하기

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Deploy algorithms (signal/deep learning,...) to embedded GPUs

DENSO TEN Uses MATLAB to Develop Mobile Cyber-Physical System

DENSO TEN is developing mobility solutions using a cyber-physical system. The system consists of edge computers on vehicles and cloud AI. Mobility data collected from VCU and edge computers will be analyzed in the cloud to derive solutions for mobility problems.

Key Outcomes/Results

- DENSO TEN used MATLAB to develop and deploy a production-ready system that spanned hardware and cloud applications without manual recoding
- MATLAB enabled DENSO TEN to easily implement complex algorithms that utilized AI, image processing, probability calculations, and statistics
- MATLAB Production Server enabled DENSO TEN to run sophisticated analytics in a centralized location on the cloud



Mobility solution powered by edge devices and a centralized cloud to analyze and predict traffic flow.

"The superiority of MATLAB in data processing and visualization and its ability to consistently realize the entire process from conception to implementation is a major attraction and is the reason why we chose MATLAB for this project."

- Natsuki Yokoyama, DENSO TEN

Drass Develops Deep Learning System for Real-Time Object Detection in Maritime Environments

Challenge

Help ship operators monitor sea environments and detect objects, obstacles, and other ships

Solution

Create an object-detection deep learning model that can be deployed on ships and run in real time

Results

- Data labeling automated
- Development time reduced
- Flexible and reproducible framework established



First day of object detection tests with optronic system prototype.

"From data annotation to choosing, training, testing, and fine-tuning our deep learning model, MATLAB had all the tools we needed—and GPU Coder enabled us to rapidly deploy to our NVIDIA GPUs even though we had limited GPU experience."

- Valerio Imbriolo, Drass Group

Types of GPUs









Desktop GPUs (and Cloud GPUs)

Power Consumption: 300W~ vs 15~75W





Embedded GPUs Industrial module: <u>10-year Operating Lifetime</u>

CUDA code generation

- Generate optimized CUDA code from MATLAB and Simulink for deep learning, embedded vision, and autonomous systems
- Generated CUDA is <u>portable</u> across NVIDIA desktop GPUs
- Prototype algorithms on modern GPUs including the Nvidia Data Center GPUs and Jetson AGX Orin
- Accelerate computationally intensive portions of your MATLAB code and Simulink models using generated CUDA code



Why Use CUDA code generation ?

Pains: Hand code

- Cannot code in CUDA
- Time consuming
- Manual Coding Errors
- Multiple implementations
- Expensive



Solution: GPU Coder

- Automatically convert to CUDA
- Get to CUDA faster
- Eliminate manual coding errors
- Maintain Single "Truth"
- Stay within MATLAB/Simulink at a higher level



What is CUDA?

Run Hello World on GPU



For example, if you could do this ... Linear Algebra routine, SAXPY example



Automatic compilation from a highly extensible language to a high performance language

Two Application examples

1) Fog Rectification



2) Anomaly Detection





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Time





Code Profiling using GPU Performance Analyzer



R2023a



Visualize code metrics and identify optimization and tuning opportunities

- Profile and understand GPU and CPU activities, events, and performance metrics in a chronological timeline plot
- Use the profiling info to analyze and optimize the performance of the generated CUDA





Bidirectional Traceability

(7)

Understand how GPU Coder maps the MATLAB algorithm to CUDA kernels

fog_rectification.m fog_rectification.cu [422]	fog_recti	ification.m [1] fog_rectification.cu
<pre>1 function [out] = fog rectification(input) %#codegen</pre>	A 75	53 // Changing the precision level of input image to d
2	75	54 cudaMemcpy(*gpu input, input, 921600ULL, cudaMemcpyH
3 % Copyright 2017-2019 The MathWorks, Inc.	75	fog rectification kernel1<< <dim3(1800u, 1u),="" 1u,="" dim<="" td=""></dim3(1800u,>
4	75	56 *gpu input, *b gpu input, *gpu restoreOut);
5 coder.gpu.kernelfun;	75	57 // Dark channel Estimation from input
6	75	58 // diff_im is used as input and output variable for
7 % restoreOut is used to store the output of restoration	- 75	59 fog_rectification_kernel2<< <dim3(600u, 1u),="" 1u,="" dim3<="" td=""></dim3(600u,>
<pre>8 restoreOut = zeros(size(input), 'double');</pre>	76	<pre>60 *b_gpu_input, *gpu_diff_im, *gpu_darkChannel);</pre>
9	76	61 // 2D convolution mask for Anisotropic diffusion
10 % Changing the precision level of input image to double	76	62 // Refine dark channel using Anisotropic diffusion.
11 1nput = double(1nput)./255;	76	63 for (idx = 0; idx < 3; idx++) {
12 12 WW Bank shared Estimation from input	76	<pre>64 fog_rectification_kernel3<<<dim3(605u, 1u),="" 1u,="" di<="" pre=""></dim3(605u,></pre>
13 % Dark channel Estimation from input	- 76	65 *gpu_expanded);
14 darkchannel = min(input, , 3);	. 📕 76	<pre>66 fog_rectification_kernel4<<<dim3(600u, 1u),="" 1u,="" di<="" pre=""></dim3(600u,></pre>
15 16 % diff im is used as input and output vanishle for anis	76	<pre>67 [*gpu_diff_im, *gpu_expanded);</pre>
10 % ultr_im is used as input and output variable for anis	76	68 cudaMemcpyToSymbol(const_b, b, 72ULL, 0ULL, cudaMe
$\frac{17}{10} \text{ min} = 0.9 \text{ udrkChallel};$	76	<pre>69</pre>
10 10 10 10 10 10 10 10 10 10 10 10 10 1	7	<pre>70</pre>
20 % 2D convolution mask for Anisotronic diffusion		
$21 \text{ hN} = \begin{bmatrix} 0 & 0.625 & 0 & 1250 & 0 & 0.625 \\ 0 & 0.625 & 0.625 \\ 0 & 0.625 & 0.625 \\ 0 &$	11	/2 // Reduction with min
22 hN = [0.0025 0.1250 0.0025], 0.1250 0.2500 0.1250], 0.002	11	// Parallel element-wise math to compute
22 111 - double(1117)	11	/4 // Restoration with inverse Koschmieder's law
24 %% Refine dark channel using Anisotronic diffusion.		75 Tog_rectification_kernei6<< <dim3(6000, 10),="" 10,="" dim3<="" td=""></dim3(6000,>
25 for $t = 1$:num iter		/6 "gpu_uitt_im, "gpu_uarkchannel);
<pre>26 diff im = conv2(diff im.hN.'same');</pre>	77	$\frac{10g}{10g} = \frac{10g}{10g} = $
27 end	77	70 fog nostification konnolg///dim2(1900) 10 10 dim
28	70	$\frac{100}{3}$
29 %% Reduction with min	75	81 //
<pre>30 diff im = min(darkChannel,diff im);</pre>	75	82 // Stretching performs the histogram stretching of
31	78	<pre>ki // im is the input color image and n is cdf limit.</pre>
<pre>32 diff_im = 0.6*diff_im ;</pre>	78	84 // out is the contrast stretched image and cdf is t
33 Ctrl	- 78	85 // density function and T is the stretching fun€trlo -
34 0/0/ - 11 1 1 1 1	78	86 (

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GPU Coder for Image Processing and Computer Vision





Fog removal

4x speedup





Frangi filter

3x speedup





Distance transform 8x speedup





Stereo disparity

50x speedup





Ray tracing

18x speedup





SURF feature extraction

700x speedup



Optimizations for Generated CUDA Code

- Accelerated library support
 - cuFFT, cuBLAS, cuSolver, Thrust, cuDNN, & TensorRT
- Data Transfer Minimization
 - Analyzes data dependency between the CPU and GPU partitions to determine minimum set of locations where data must be copied between CPU and GPU using cudaMemcpy



Example 2: Anomaly Detection



Example 2: Anomaly Detection Try the New Desktop 🔎 🔔 Jayden님 🎙 **a** ? Search Documentation VNC Viewer: Connection Details % J Section Break 👌 Profiler 5 VNC server: 10.42.0.1 🔄 Run and Advance Nev 🕜 Analyze Run Run Step Stor Section 🛛 🔁 Run to End Options.. Load.. Save As... ANALYZE SECTION RUN \triangleleft - 0 () Curr About... Cancel Connect 1-JetsonAnomalDetect 231126\tb nutsDet HSP.m 🗑 🗙 Workspace targetFunction.m × + ... Size Name 🔺 train_SqueezeNet.m 8/31... Script 3 KB clear all, close all, clc; 1 <u>^</u> tb workflow.m 2/14... Script 3 KB 2 tb_nutsDet_HSP_Jd.m 8/31... Script 1 KB 3 %% Datastore preparation tb_nutsDet_HSP.m 6/5/... Script 4 KB % Create image datastore to access to images 4 tb nutsDet HSP.asv 9/1/... Edit... 3 KB outputFolder = fullfile(pwd, 'images'); % define output folder 5/2/... Script 1 KB 魡 tb_gpu_predict.m imds = imageDatastore(outputFolder); 9/1/... Fun... 2 KB 🖄 targetFunction.m numel(imds.Files);] targetFunction.elf 6/5/... ELF ... 1.78 ... 8 README.md 9/5/... MD ... 7 KB 9 % Visualize images 🖄 readFunctionTrain.m 5/2/... Fun... 1 KB 10 🕙 Quantize.m 9/1/... Script 1 KB figure output0.png 6/5/... PNG... 147 KB montage(imds.Files(1:2), 'ThumbnailSize', [200 200]); 11 🖄 ocv2mat.m 5/2/... Fun... 1 KB 12 💫 NutAnomalyDet 사용가이드 202... 9/5/... Ado... 192 KE 13 %% Classifier test mvSqueezenet.mat 7/22... MAT...4.86 ... 14 mvNDNet Preprocess.m 5/2/... Fun... 2 KB 15 % Read image MyNDNet Postprocess.m 5/2/... Fun... 2 KB 16 [img info] = readimage(imds, 1); mat2ocv.m 5/2/... Fun... 1 KB 17 imshow(img) main_nutsCam.cpp 6/5/... C++...4 KB 18 main_nutsCam.asv 11/2... Edit... 4 KB % Load pretrained network 19 JetsonAnomalvDetection 231126...11/2... Co... 14.1... 🖄 gpu_predict.m 8/31... Fun... 1 KB 20 load('mySqueezenet') 🔄 changelnitializer.m 5/2/... Fun... 1 KB 21 Weights = convnet.Layers(67).Weights; CAMheatmap_squeezenet.m 5/2/... Fun... 2 KB 22 🚞 traininglmages 11/2... Folder ÷ 23 % Convert image data format (MATLAB Compatible > OpenCV) 🕀 🚞 images 11/2... Folder 24 img2 = mat2ocv(img); 2/15... Folder 🕀 🚞 codegen 25 26 % Apply algorithms using user-defined function 27 out = targetFunction(img2, Weights, 1); 28 29 % Convert image data format (OpenCV > MATLAB Compatible) 30 sz = [240 320 3]; 31 out? - ocu?mat(out cz). () Command Window Available Digital Pins : 7 11 12 13 15 16 18 19 21 22 23 24 26 29 31 32 33 35 36 37 38 40 Code generation successful: View report ### Launching the executable on the target... Executable launched successfully with process ID 6880. Displaying the simple runtime log for the executable ... main_nutsCam.cpp (C++ Source) \sim Note: For the complete log, run the following command in the MATLAB command window: system(hwobj,'cat /home/orin/remoteBuildDir/MATLAB ws/R2024a/C/GpuDemo/JetsonAnomalDetect 231126/targetFunction.log') No details available >> clear $f_{\underline{x}} >>$ matlab: open('C:\GpuDemo\JetsonAnomalDetect_231126\codegen\exe\targetFunction\html\report.mldatx'); Zoom: 110% UTF-8 CRLF script Ln 19 Col 26

OK, but what about Simulink?

Two Application examples

3) Sobel Edge Detection





4) Highway Lane Following Model





Example 3: Tuning Parameters using External Mode



NVIDIA Peripheral Support – block library







Lane and Vehicle Detection









Run Simulation on Desktop GPU





Speed up MATLAB Function blocks



Run Simulation on Desktop GPU



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Generate CUDA Code and Run on Jetson







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Generate CUDA Code and Run on Jetson





MATLAB EXPO



R2022b

Generate CUDA Enabled ROS and ROS2 Node from MATLAB



Shipping Examples

https://www.mathworks.com/help/gpucoder/examples.html



Key Takeaways

GPU Coder generates CUDA code from MATLAB & Simulink

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Accelerate MATLAB & Simulink simulations



Deploy algorithms (signal/deep learning,...) to embedded GPUs

DEMO Booth





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