

# HL Mando

November 13–14, 2024 | Online

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## An AI-Powered Predictive Maintenance Platform for Testing Autonomous Vehicle Components

Seongil, Lee *HL Mando*

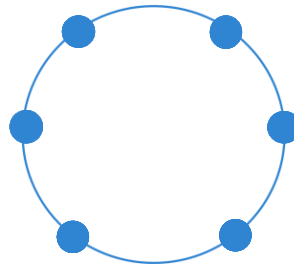
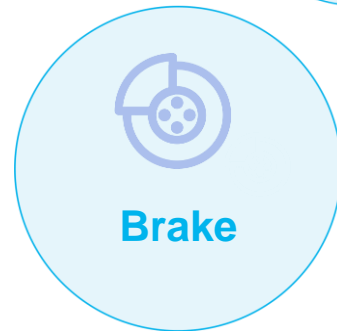


MATLAB EXPO



# HL Mando in a glimpse

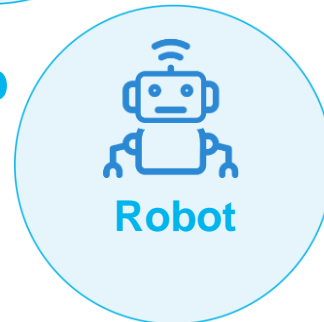
## Automotive Chassis Parts



ADAS, Lidar, Radar etc.

**HL Klemove**

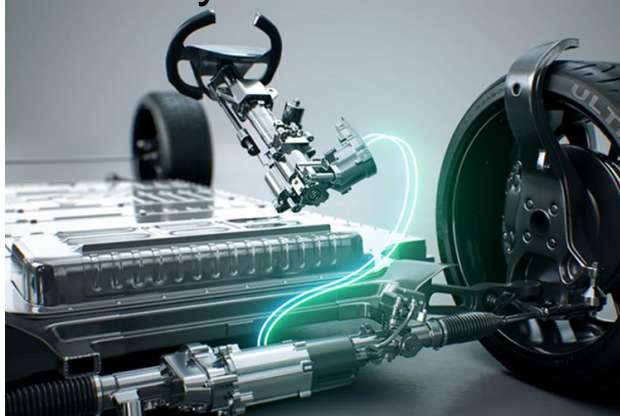
## Mobility Solution Tech. Group



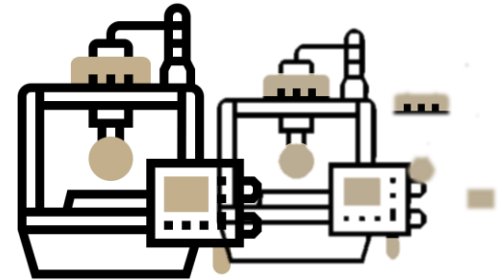
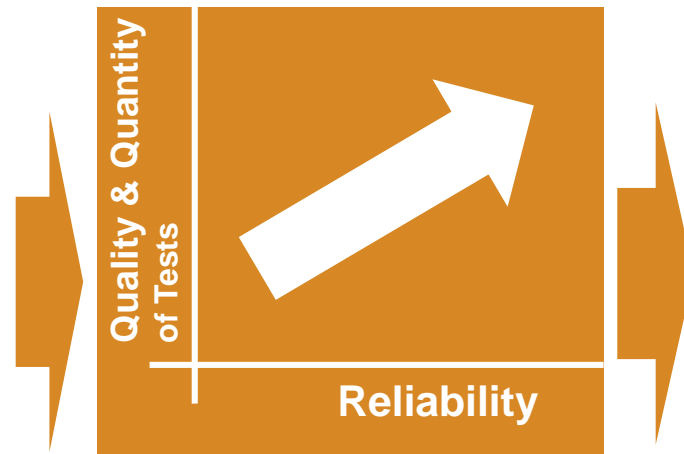
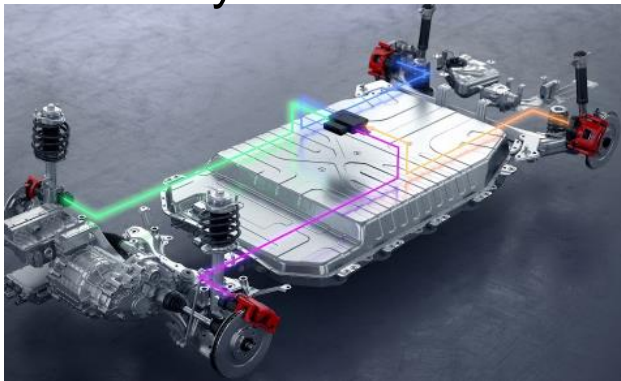
SW Campus

# New products like X-by-wire requires high performance and efficient test environment

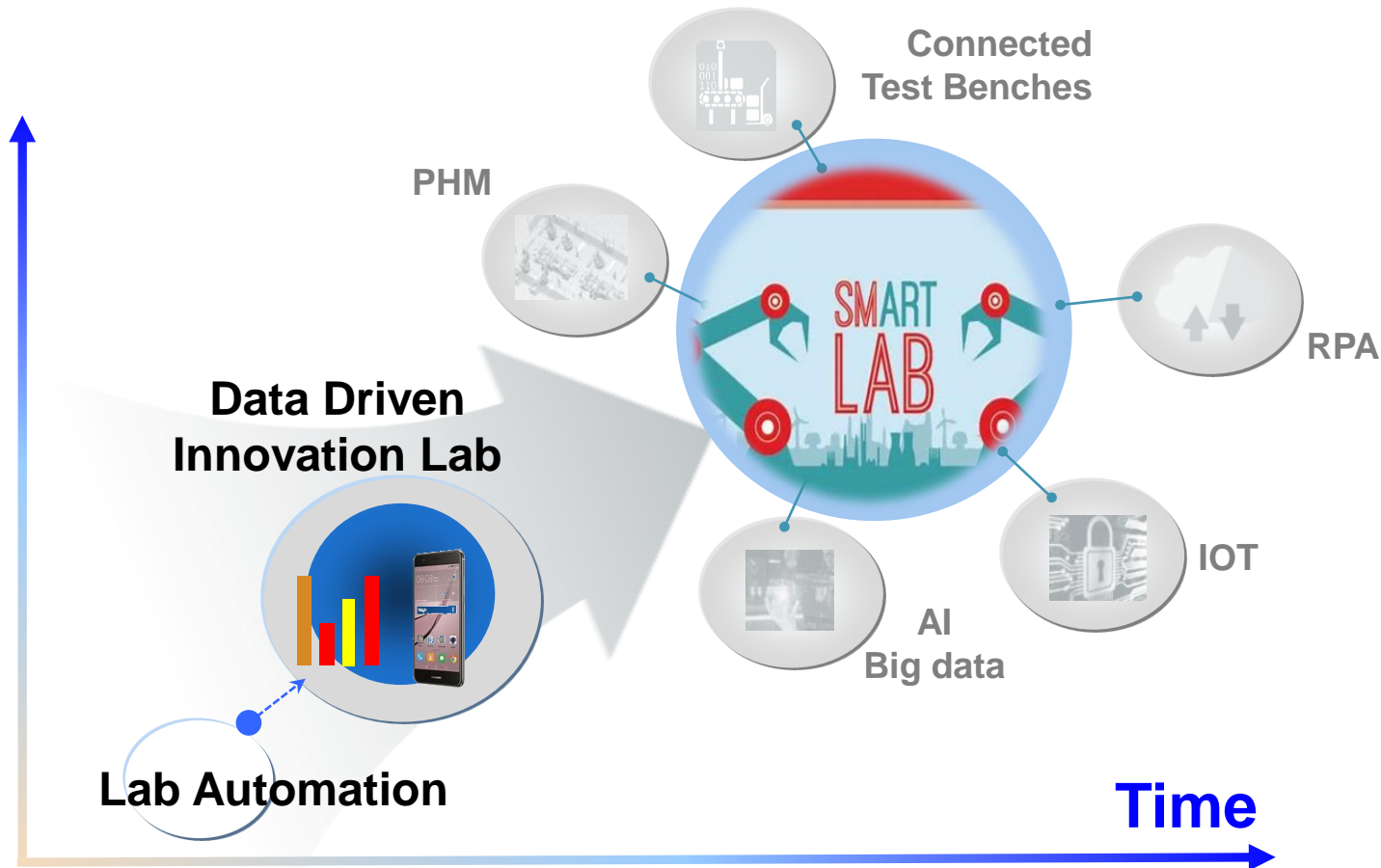
Steer by wire



Brake by wire



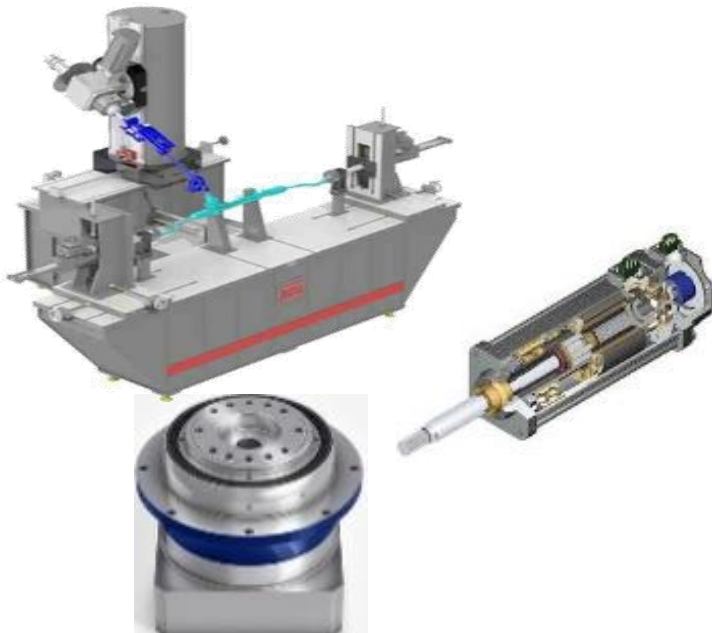
# Smart Lab for Digital Transformation in HL Mando



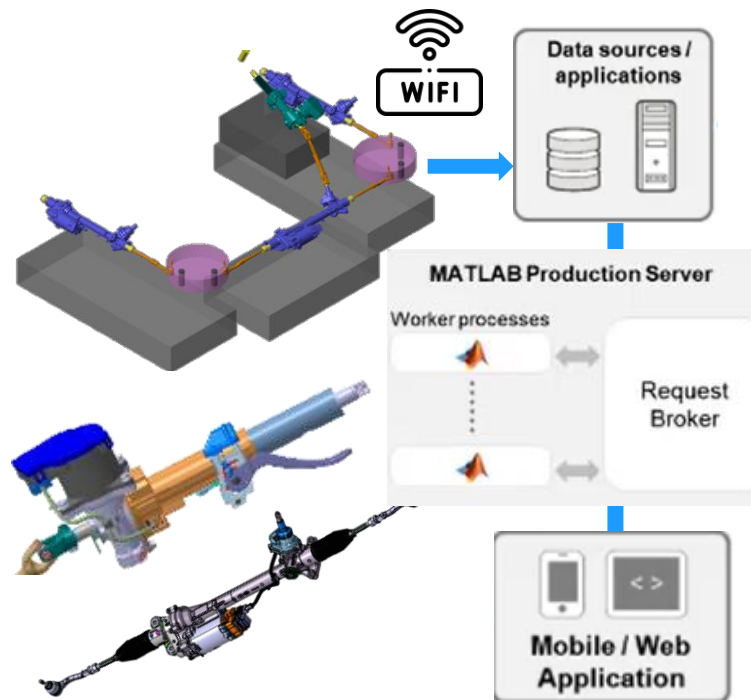
- Smart Lab comprises
1. Connected test benches
  2. IOT based monitoring system
  3. AI powered big data training and predictive analysis

# Concept of connected test benches

Conventional test benches



New test benches



Advantages of new test benches

1. Cost reduction by using in-house actuators
2. Maintenance platform
3. High performances



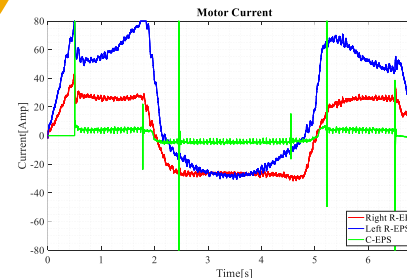
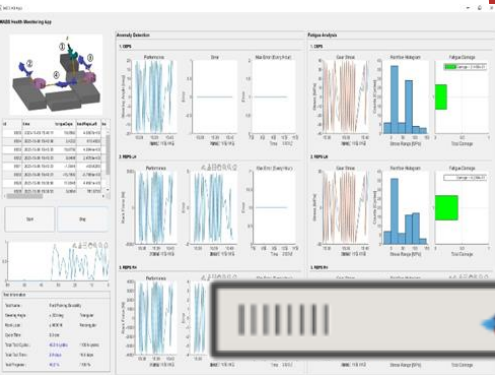
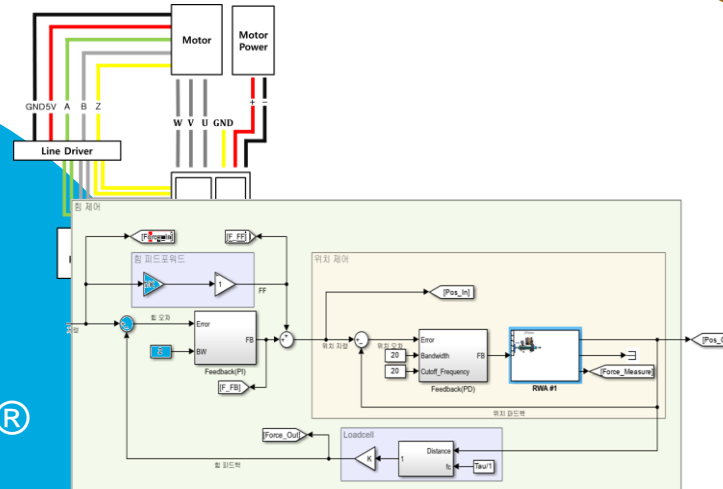
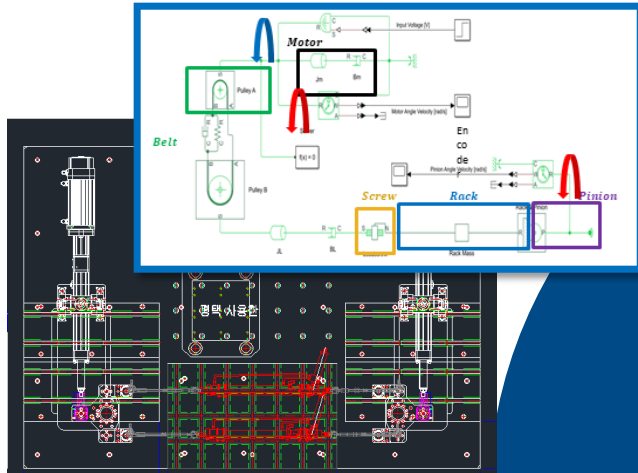
# Building SmartLAB with model based design

Design  
by  
Simscape®

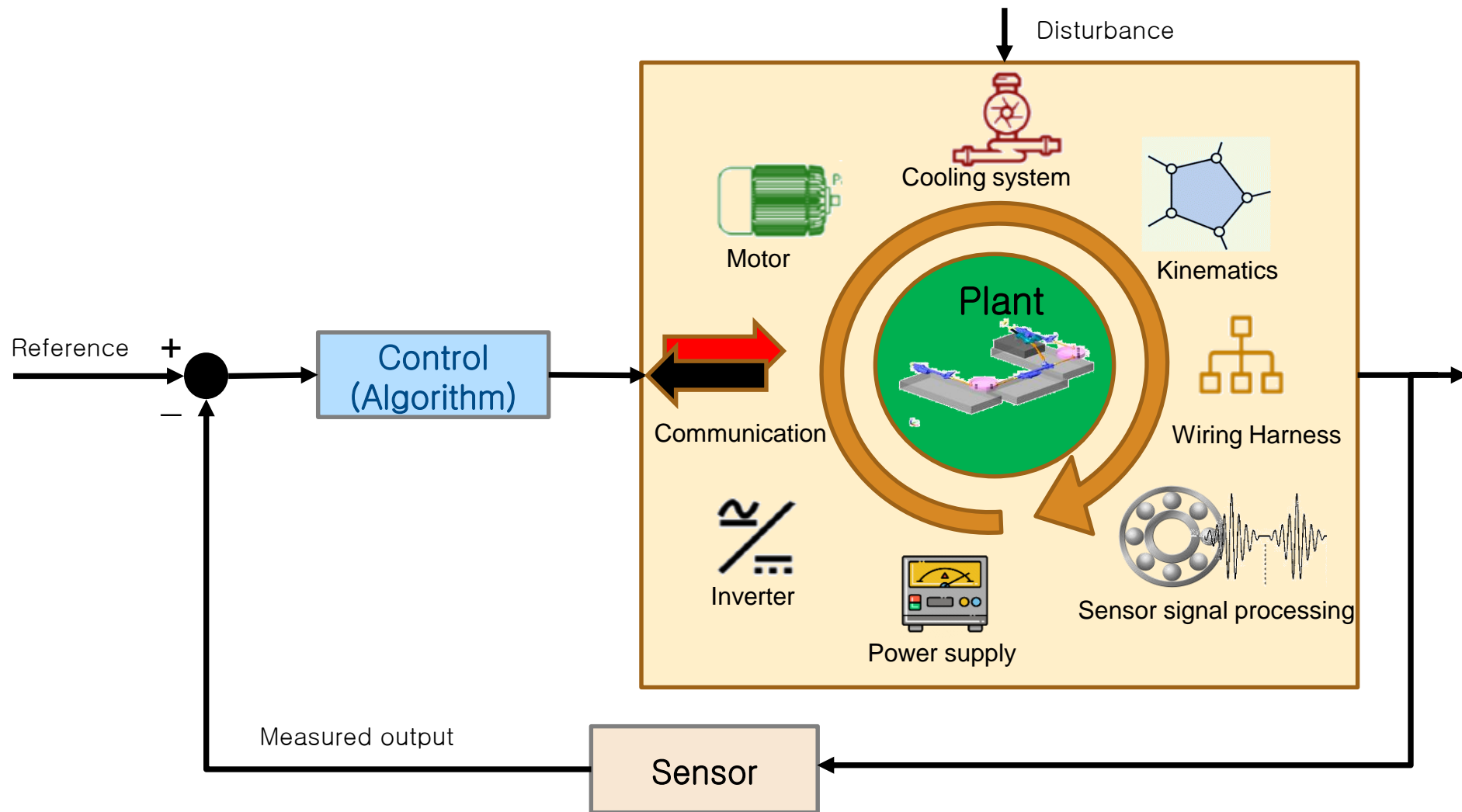
Control  
by  
Simulink®

Maintenance  
by  
MPS®

Test  
by  
Speedgoat®

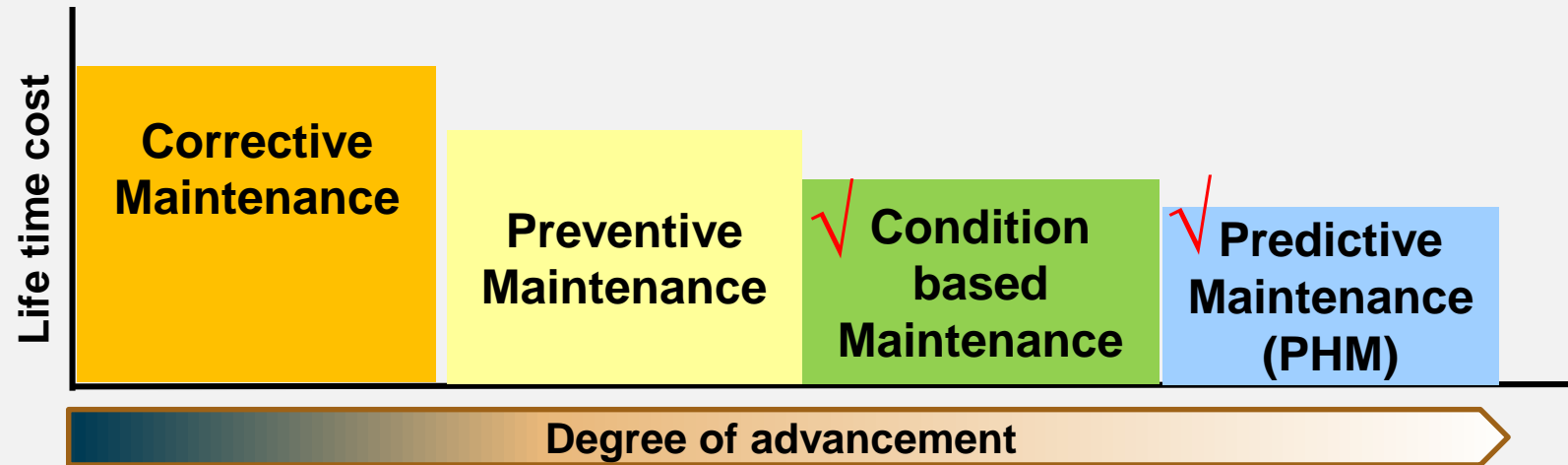


# Patented new control algorithms for high performances of test rigs



# Comparison of strategies for new test bench maintenance

- ✓ Condition Based Maintenance(CBM) , Predictive Maintenance(PHM)

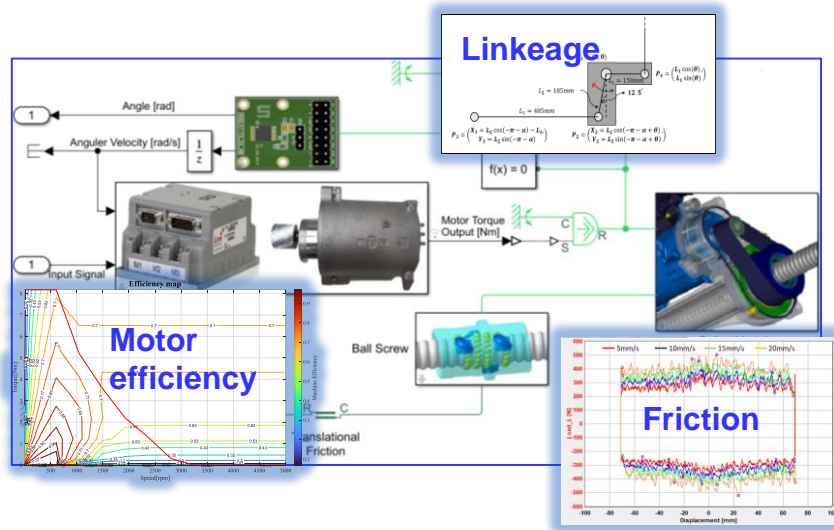


- ✓ Global R&D web-based smart maintenance platform

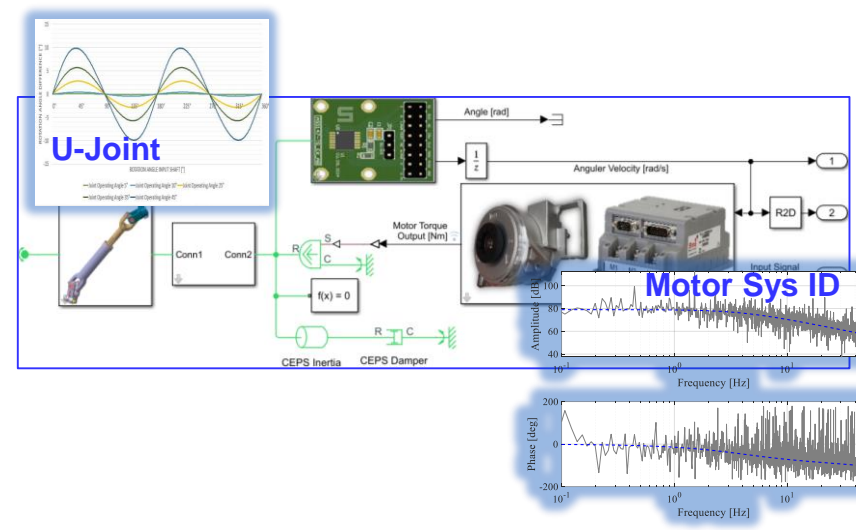




# Bench design using digital twin – physical modeling

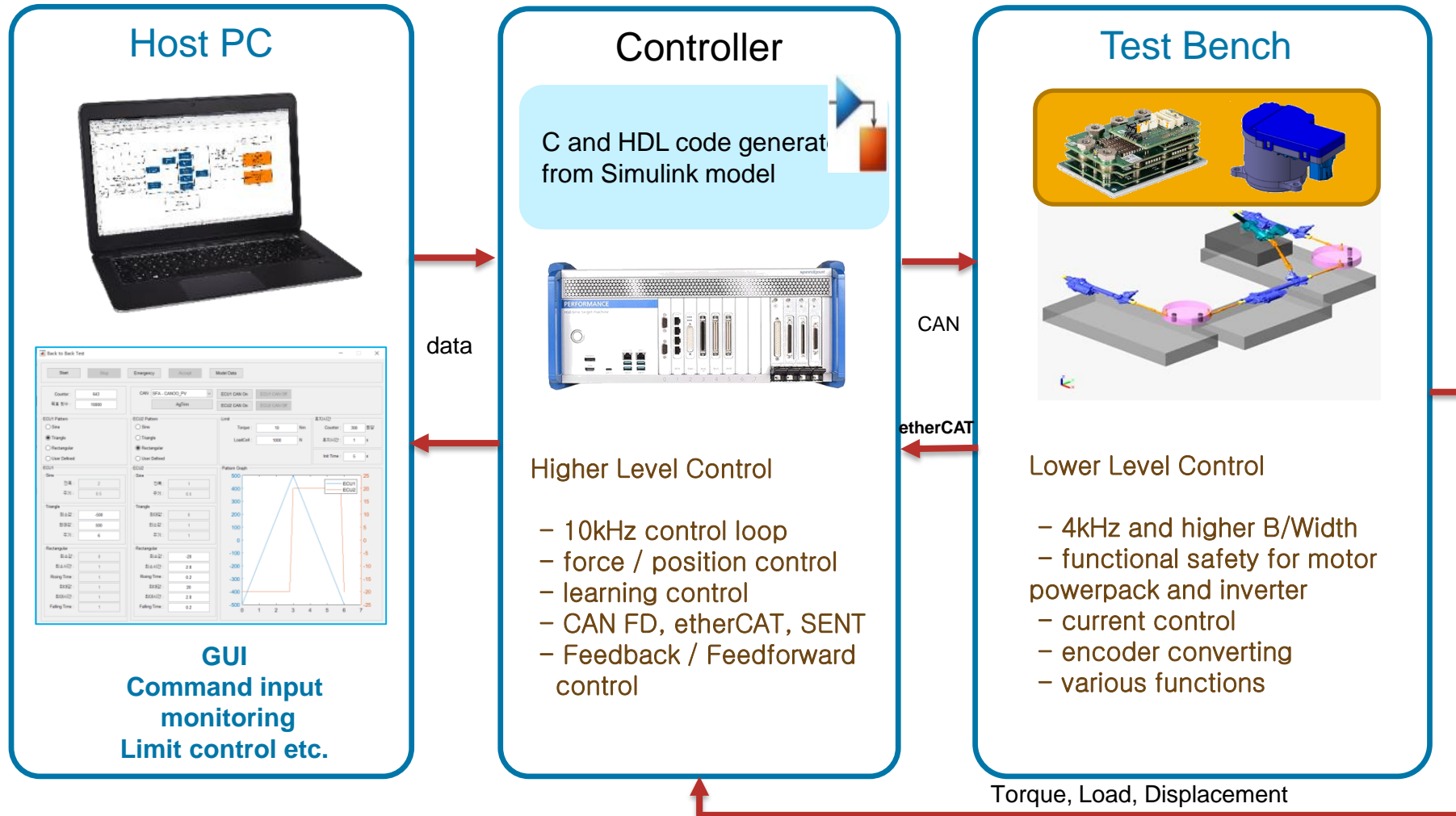


< Linear actuator modeling >



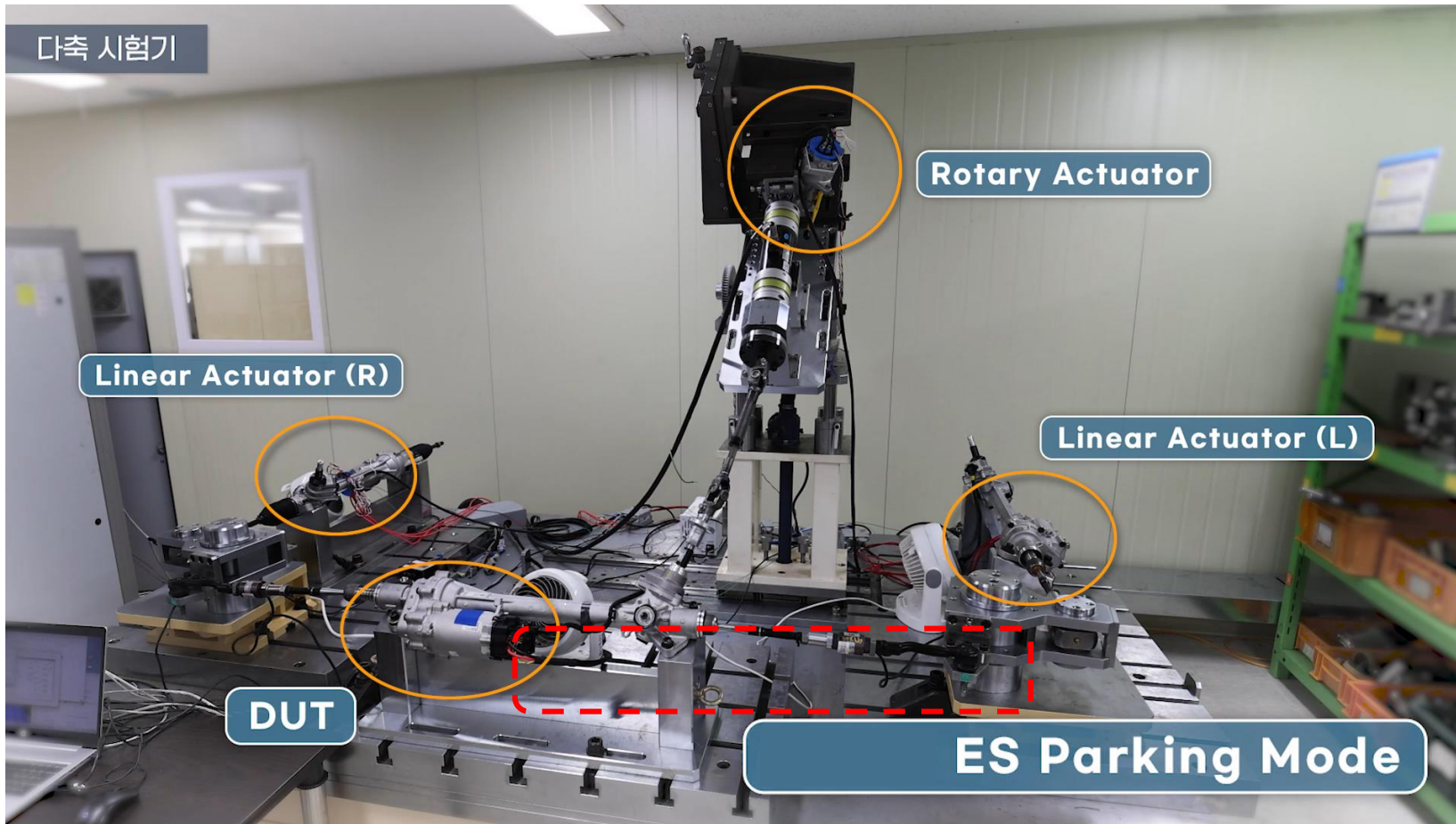
< Rotary actuator modeling >

# Control architecture

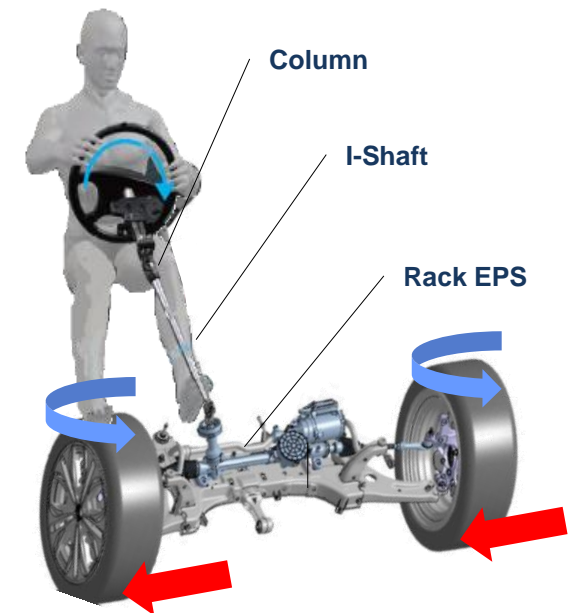


# 3 Axes steering durability test stand

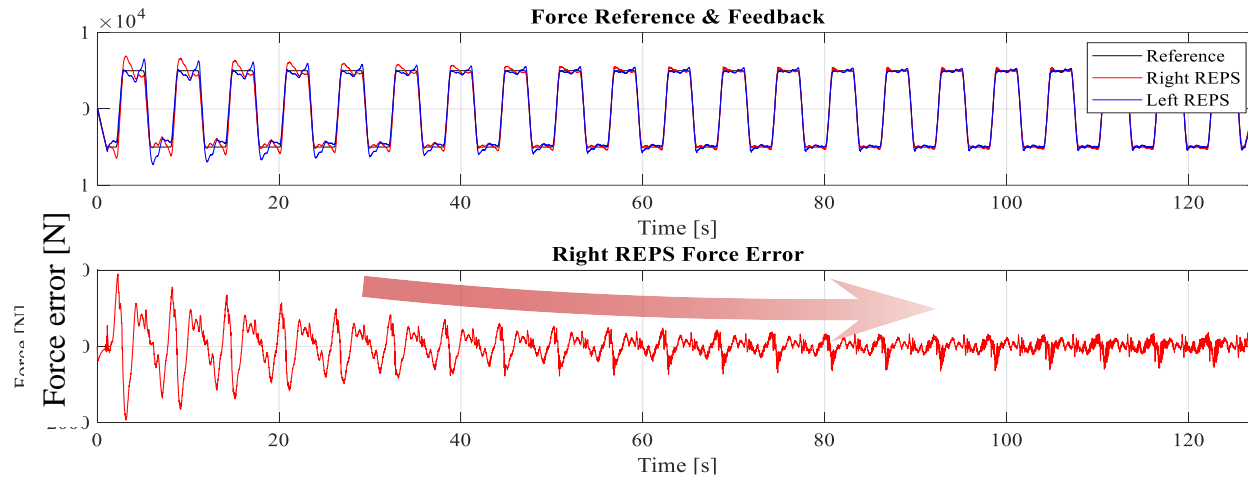
Target test stand – 3 axes steering durability test rig



Newly developed steering test stand simulate real vehicle



# New benches with ILC(Iterative Learning Control) shows better performances

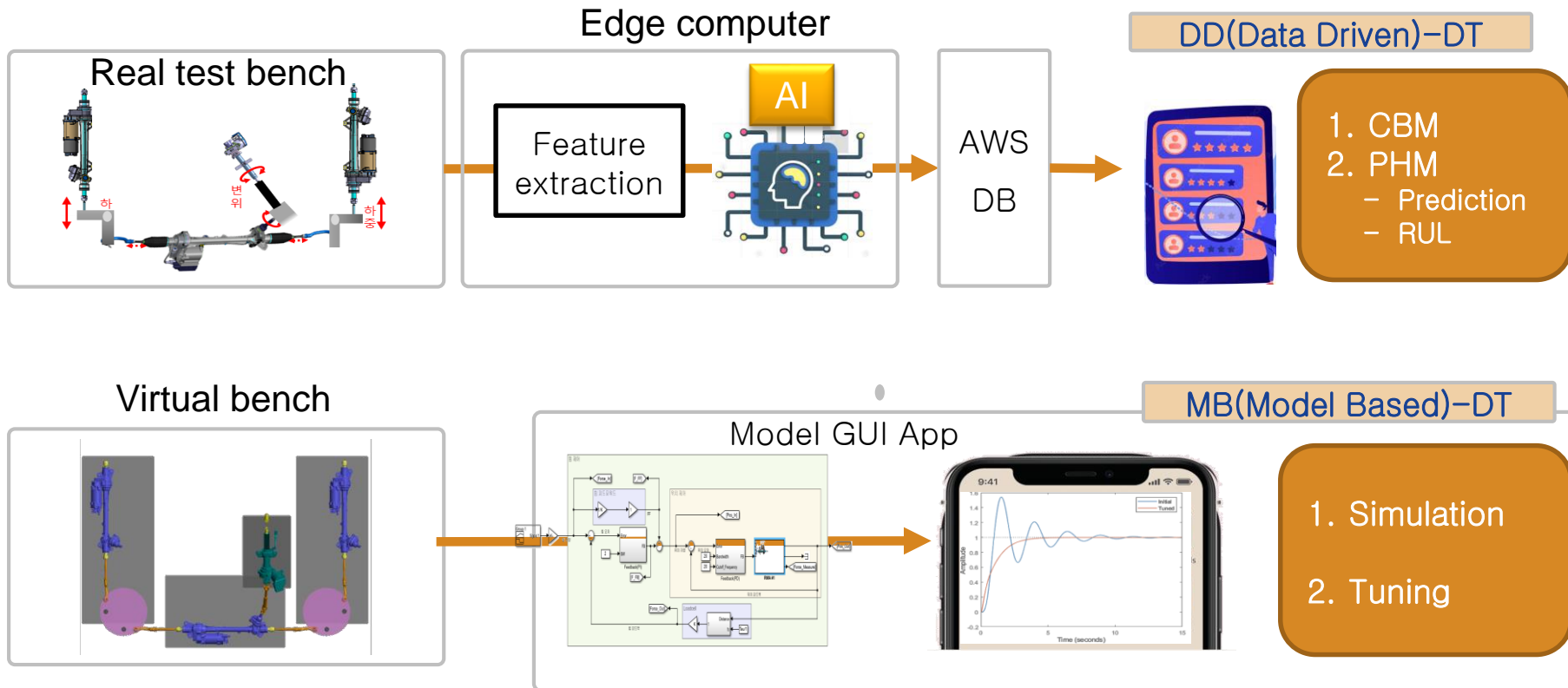


- Response per command error reduced by 33% ( target  $\text{Error}_{\text{RMS}} < 10\%$  )

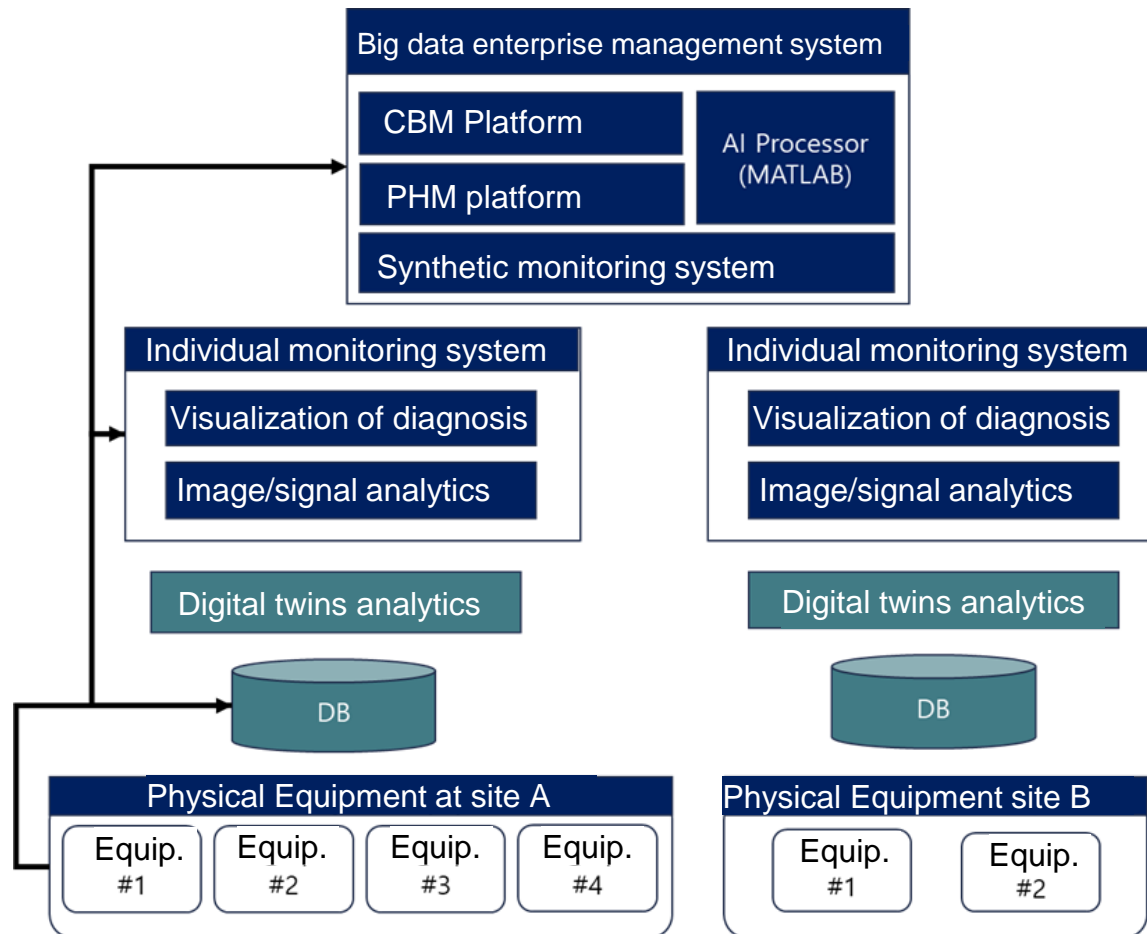
	Existing bench	New bench with ILC control	
RMS error (%)			

# PHM basic architecture

## - Data driven and model based digital twin



# PHM platform architecture for administering multiple test stands at various sites



## Data and information flow

**EMS (enterprise management system)** : data integration to main server and analyse the machine status based on CBM and PHM

## Real time monitoring

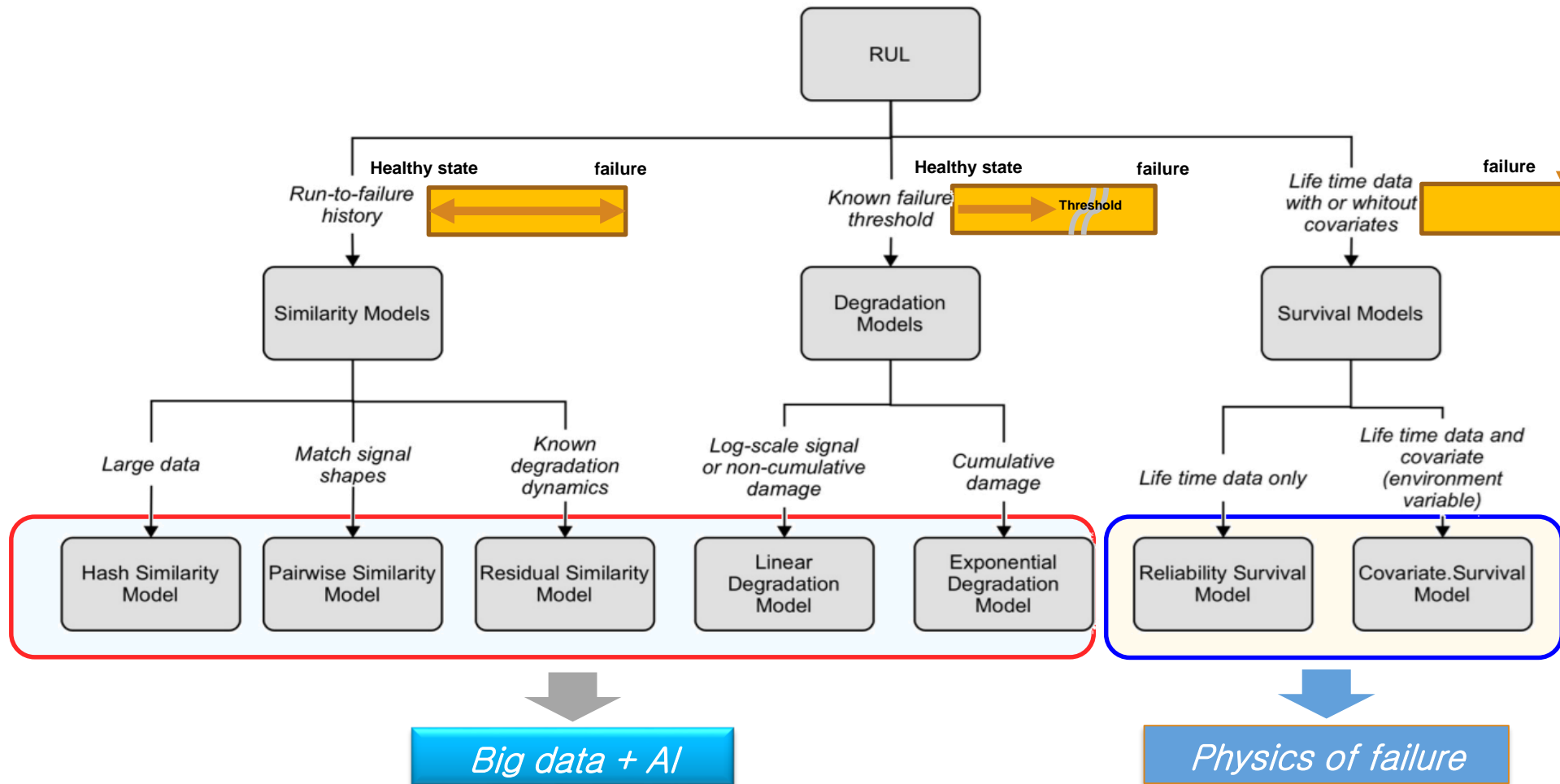
**Prediction based on physics and machine learning**

## Quality control and diagnosis

Detection of failure and diagnose its cause



# RUL(Remaining Useful Life) estimation requires models with right big data

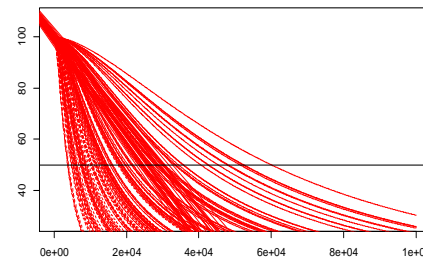
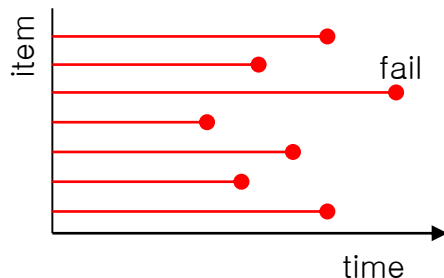
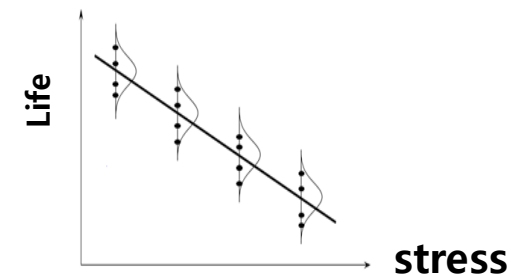


# Collecting life data by implementing accelerated life test or accelerated degradation test

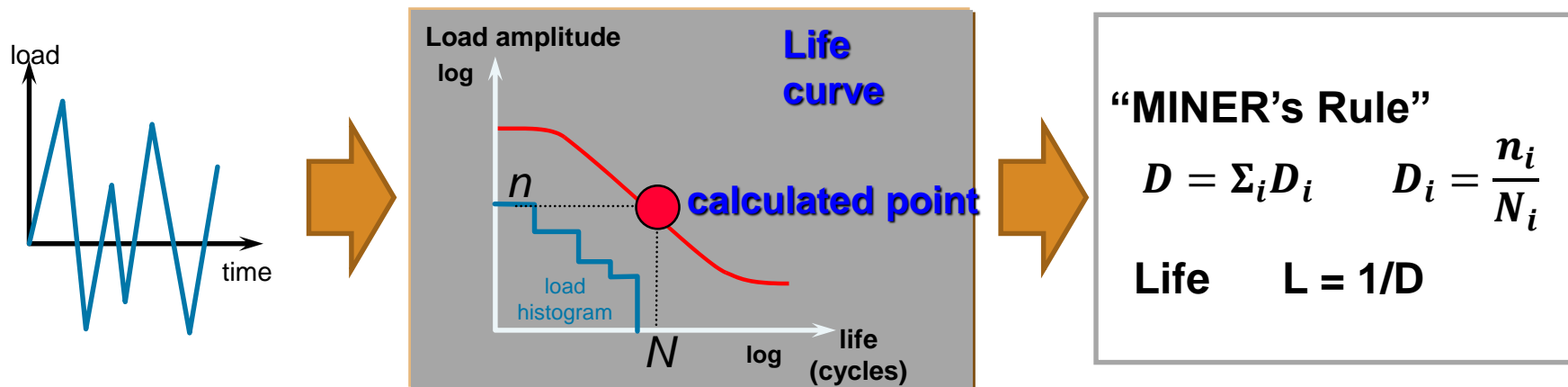
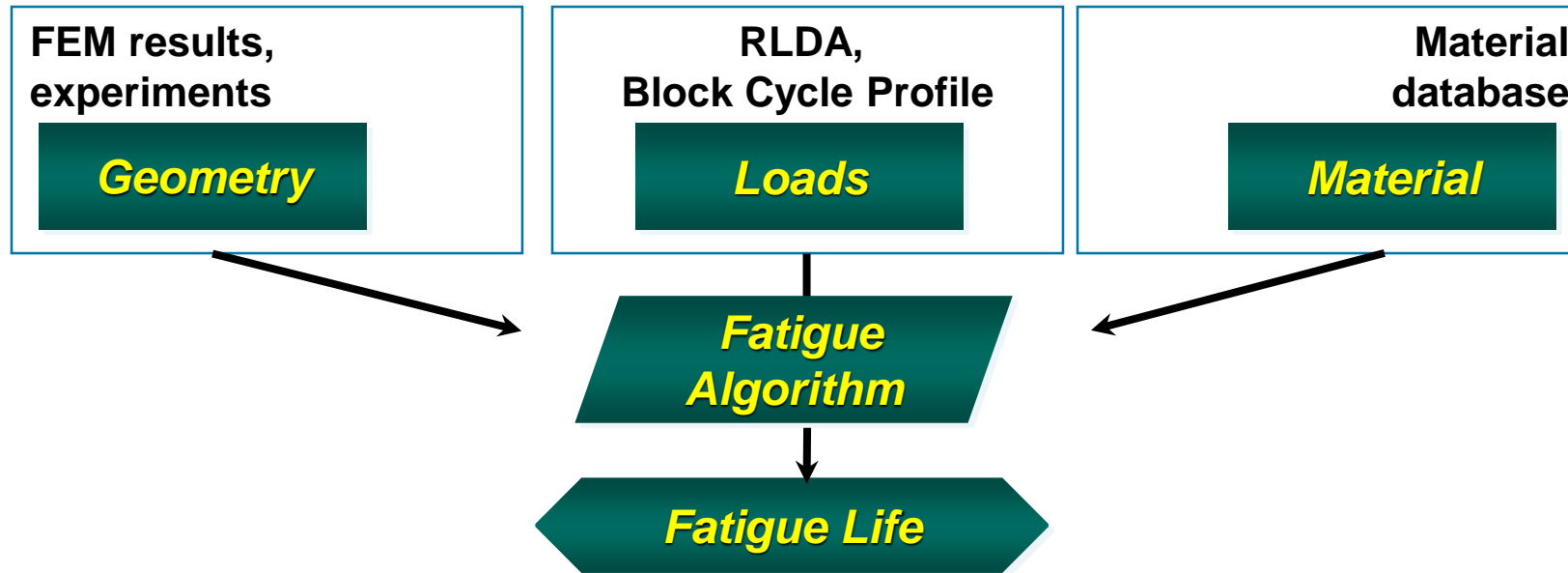
## What is Accelerated Life testing?

Obtaining life or degradation data is difficult because of long life times of products  
So life in devised condition could be used to quickly fail the product.

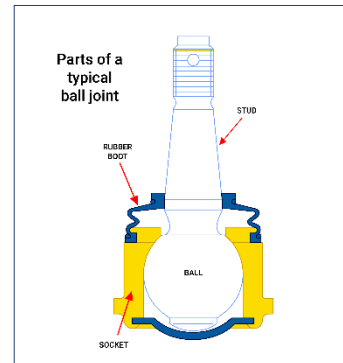
$$\text{Acceleration Factor} = \frac{\text{Life in normal condition}}{\text{Life in accelerated condition}}$$



# Physics of failure like fatigue can estimate the life of product

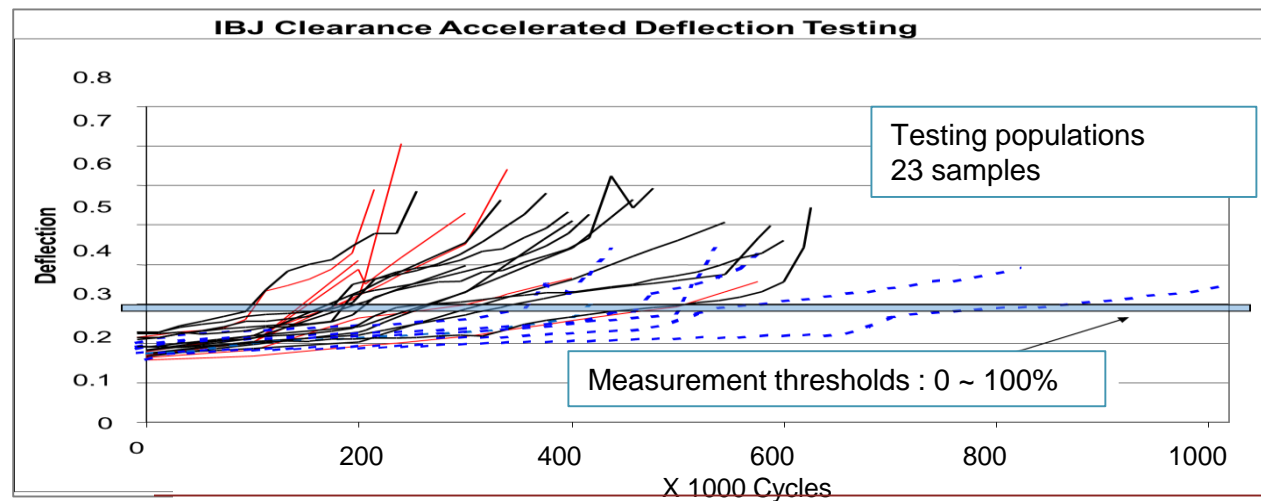


# Example. plastic bearing



Plastic Bearing

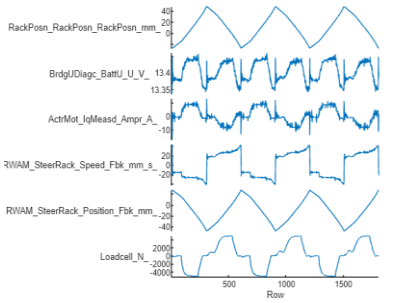
## ■ Degradation data



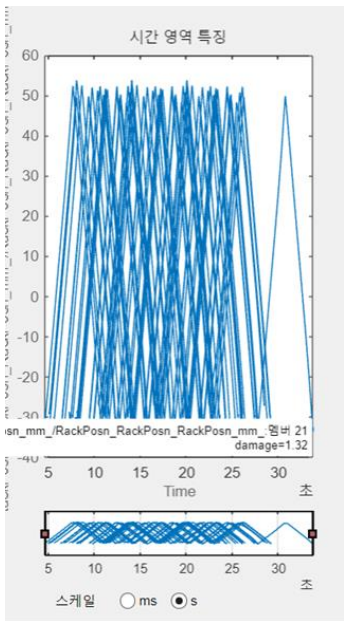
# RUL estimation process



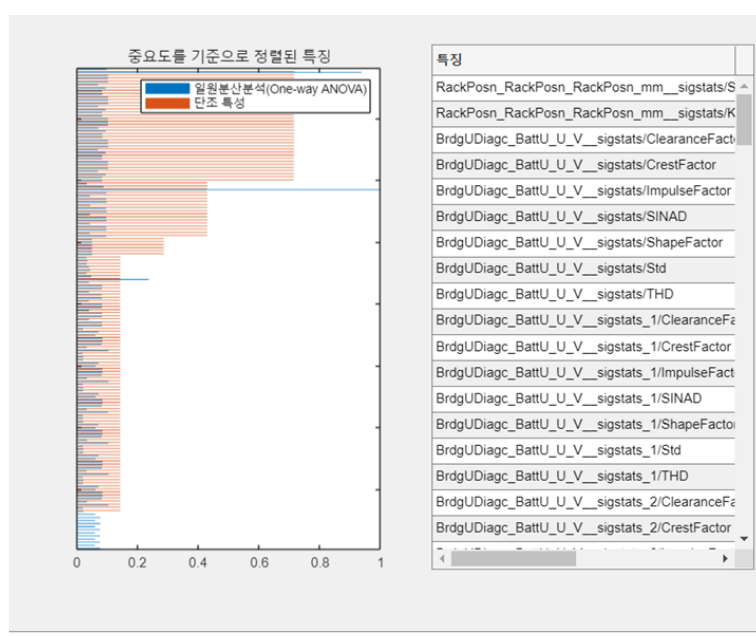
Tie Rod data collection



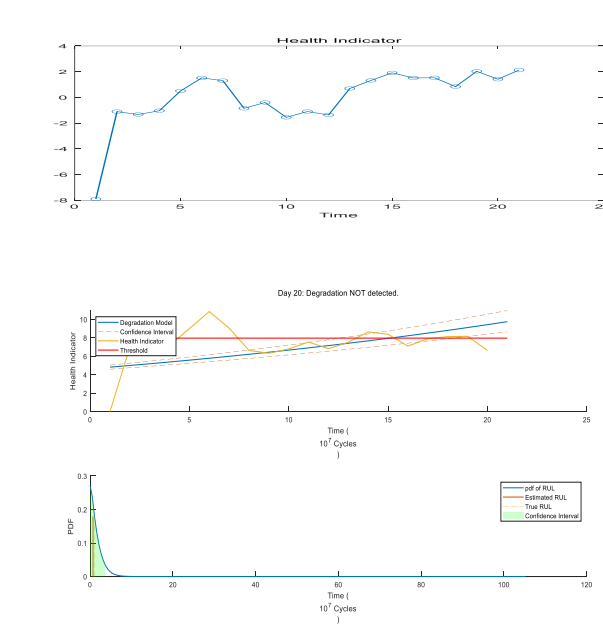
Time features



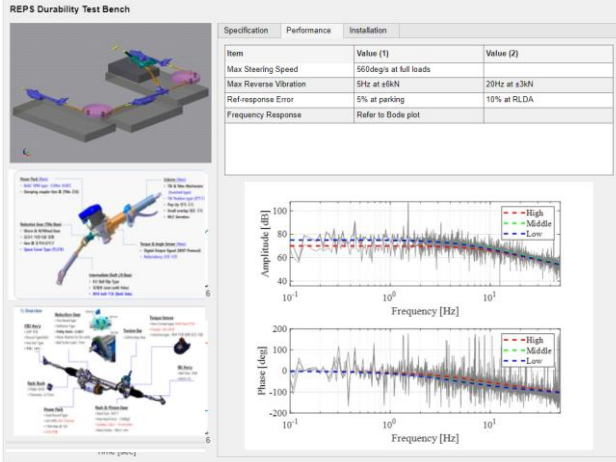
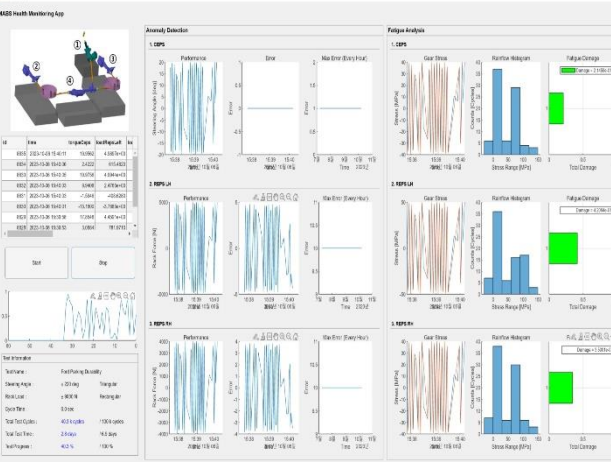
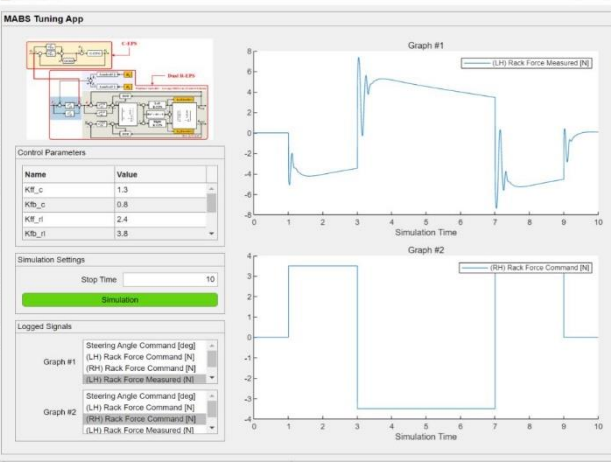
Feature extraction (70ea)



RUL estimation



# PHM platform consists of three basic functions

Information App	Monitoring App (DD-DT)	Tuning App (MB-DT)																									
 <p><b>REPS Durability Test Bench</b></p> <table border="1"> <thead> <tr> <th>Item</th> <th>Value (1)</th> <th>Value (2)</th> </tr> </thead> <tbody> <tr> <td>Max Steering Speed</td> <td>55deg/s at full loads</td> <td></td> </tr> <tr> <td>Max Reverse Vibration</td> <td>5Hz at 40N</td> <td>20Hz at 20N</td> </tr> <tr> <td>Rtd-response Error</td> <td>5% at parking</td> <td>10% at RLDA</td> </tr> <tr> <td>Frequency Response</td> <td colspan="2">Refer to Bode plot</td> </tr> </tbody> </table> <p>Amplitude [dB] vs Frequency [Hz] (High, Middle, Low)</p> <p>Phase [deg] vs Frequency [Hz] (High, Middle, Low)</p>	Item	Value (1)	Value (2)	Max Steering Speed	55deg/s at full loads		Max Reverse Vibration	5Hz at 40N	20Hz at 20N	Rtd-response Error	5% at parking	10% at RLDA	Frequency Response	Refer to Bode plot		 <p><b>MABS Health Monitoring App</b></p> <p>Amplitude, Phase, Fatigue Analysis plots</p>	 <p><b>MABS Tuning App</b></p> <p>Control Parameters:</p> <table border="1"> <thead> <tr> <th>Name</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>Kf_c</td> <td>1.3</td> </tr> <tr> <td>Kf_i</td> <td>0.8</td> </tr> <tr> <td>Kd_c</td> <td>2.4</td> </tr> <tr> <td>Kd_i</td> <td>3.8</td> </tr> </tbody> </table> <p>Simulation Settings: Stop Time: 10</p> <p>Graph #1: (LH) Rack Force Measured [N]</p> <p>Graph #2: (RH) Rack Force Command [N]</p>	Name	Value	Kf_c	1.3	Kf_i	0.8	Kd_c	2.4	Kd_i	3.8
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<ul style="list-style-type: none"> <li>■ <b>Basic information</b></li> <li>① <b>Specification</b></li> <li>② <b>Performances</b></li> <li>③ <b>Install and repair history</b></li> </ul>	<ul style="list-style-type: none"> <li>■ <b>Realtime Monitoring</b></li> <li>① <b>Warning and alarm</b></li> <li>② <b>RUL estimation</b></li> </ul>	<ul style="list-style-type: none"> <li>■ <b>Parameter tuning</b></li> <li>■ <b>Simulation</b></li> </ul>																									



## Key takeaways

1. A Whole process for the big data processing is accomplished by making connected test benches and real time PHM platform
2. Newly developed equipment and platform helped to accelerate the maturity of our product - autonomous components like X-by-wire system
3. Further plan
  - Wider application to other area : robots and medical environment

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