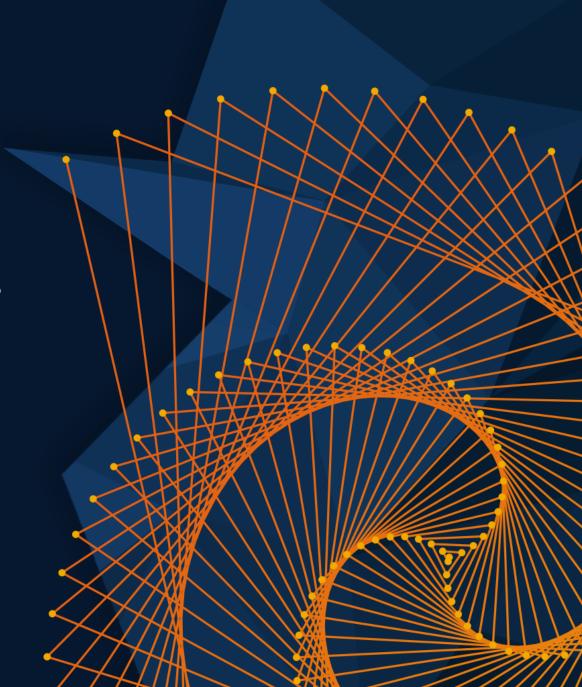
WATLAB EXPO UNITED KINGDOM

# Simulation-Driven Safety Analysis through Fault Injection Testing

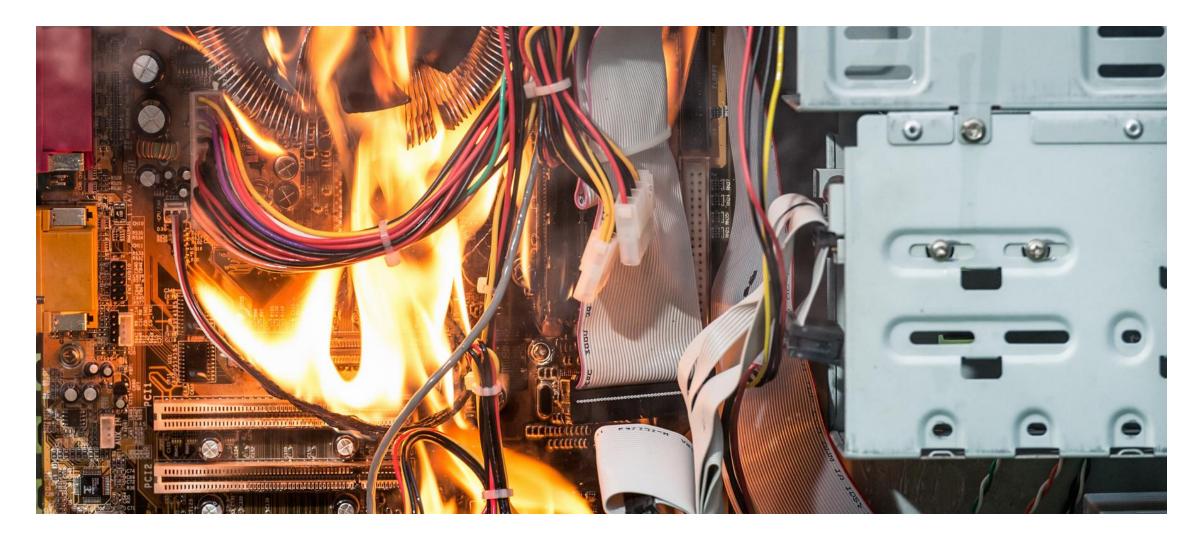
Fredrik Håbring, MathWorks





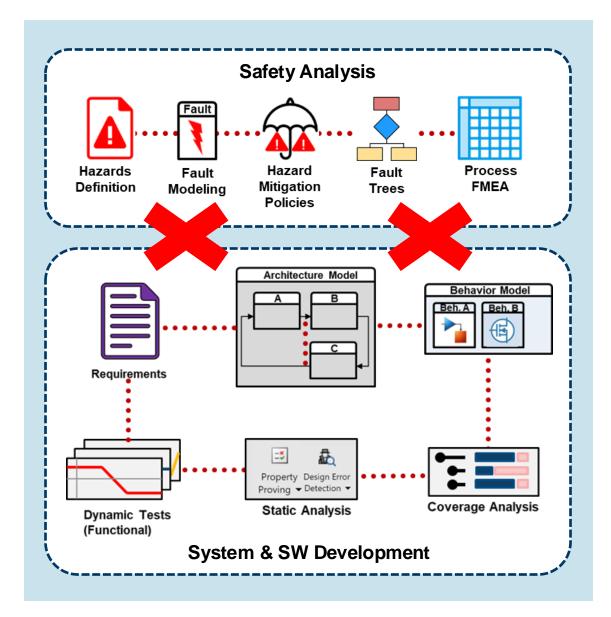


#### We need to verify that our developed system is safe and can handle faults in a safe way to not cause harm



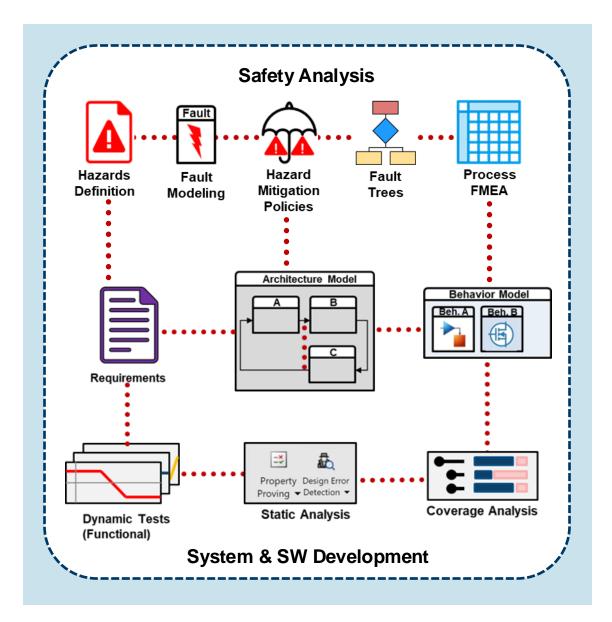
#### Key Takeaways

- Traditional Safety Analysis is
  - Decoupled from design work
  - Complex and complicated
  - Error-prone



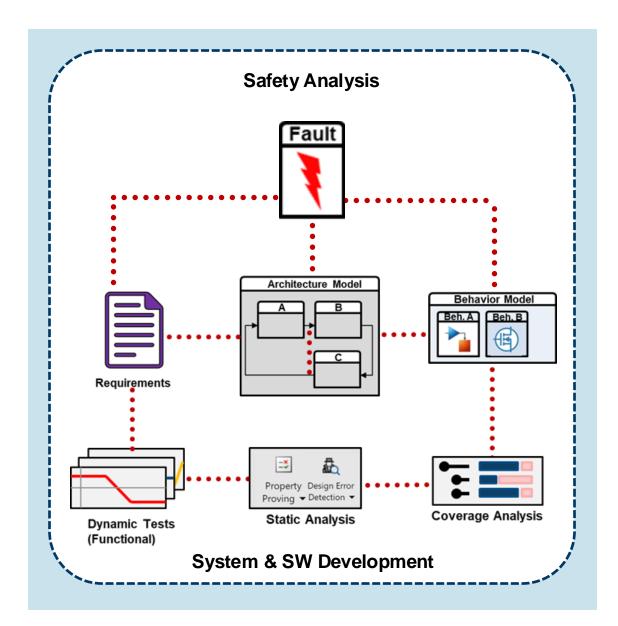
#### Key Takeaways

- <u>Model-Based</u> Safety Analysis is
  - Fully integrated with design
  - Fully traceable w.r.t. changes
  - Consistent
  - Validated by simulation



#### Key Takeaways

- Enhanced Fault Modeling
  - Separated from design
  - Supports **complex** faults
  - Analyze fault effects
  - Connected to hazards



# MathWorks and TUM\* won Best of Session award at DASC 2024 for implementing this workflow for an unmanned helicopter

|       | Sar                                 | <u> </u>    | Avionics System<br>o, CA, USA - September  | 43 <sup>rd</sup><br>ms Conference<br>er 29-October 3, 2024              |
|-------|-------------------------------------|-------------|--|---|
|       | sion ision Name                     | Paper<br>ID | Paper Title  | Authors   |
| B2L-D | System and Safety<br>Considerations | 3120        | Simulation-Driven Failure<br>Modes and Effects Analysis of<br>Flight Control System<br>Architectures | Julian Rhein, Marco Bimbi,<br>Giovanni Miraglia, & Florian<br>Holzapfel |

https://2024.dasconline.org/awards/best-paper-awards

#### Today's Agenda

Importance of safety in product development

System: Model-based safety analysis workflow

**Component: Fault injection modeling** 

Case Study: Aircraft fuel system

Conclusion

# Two recent examples of why safety analysis is paramount for engineered systems

#### Huge Fire Sparked by a Mercedes-Benz EV Adds to Safety Concerns Dogging Industry

Blaze in South Korea prompts debate over whether electric vehicles should be allowed in the country's ubiquitous underground parking lots

By Jiyoung Sohn Follow and Soobin Kim Updated Aug. 7, 2024 6:54 pm ET

 Listen (2 min) :

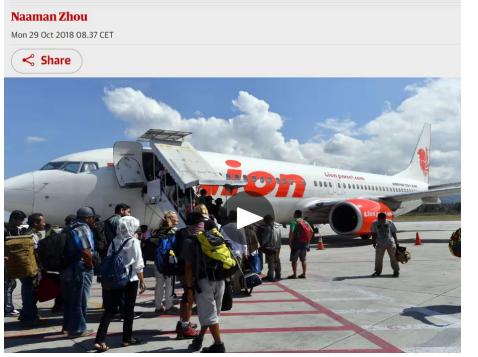


https://www.wsj.com/business/autos/huge-fire-sparked-by-a-mercedes-benz-ev-adds-to-safety-concerns-dogging-industry-8143d058

#### Lion Air crash: officials say 189 onboard lost flight JT610 - as it happened

Boeing passenger plane went down shortly after take-off from Jakarta

• Full story: Flight JT610 plunges into waters off Jakarta



https://www.theguardian.com/world/live/2018/oct/29/lion-air-crash-rescue-teams-search-waters-off-jakarta-for-flight-jt610

#### Functional safety standards recommends activities for system safety analysis: **aerospace example**

ARP4761A

An MBSA employs an analytical model called a Failure Propagation Model (FPM). The analyst uses a software application to perform an analysis of the system FPM and generate outputs such as failure sequences, minimal cut sets, or other safety focused results. These outputs are compared to objectives and requirements by safety analysts as part of the overall safety assessment process. MBSA can be applied as a failure propagation method in performing an FMEA or CEA. See Appendix N.

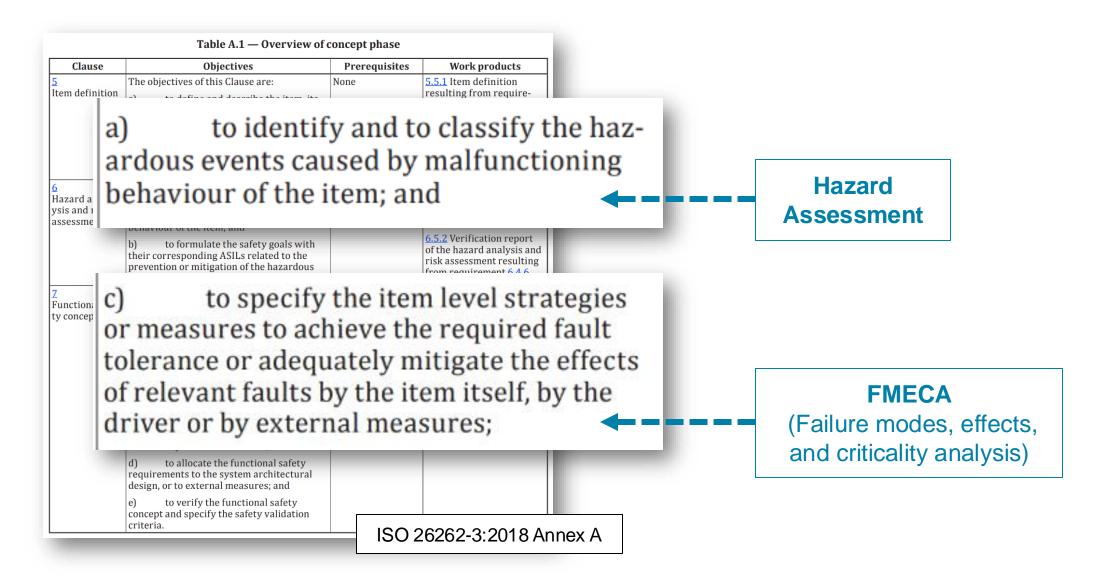
#### 3.1.2 Safety Analysis Methods

**FMECA** (Failure modes, effects, and criticality analysis)

ARP4761A

The safety assessment process includes safety analysis methods which may be applied throughout the typical development cycle to provide the analyst a means of qualitatively and/or quantitatively assessing the safety of a design. These methods include Fault Tree Analysis (FTA), Dependency Diagrams (DD), Markov Analysis (MA), Model Based Safety Analysis (MBSA), Failure Modes and Effects Analysis/Summary (FMEA/FMES), Cascading Effects Analysis (CEA), Particular Risks Analysis (PRA), Zonal Safety Analysis (ZSA), and Common Mode Analysis (CMA). The method(s) selected will vary based on system characteristics and organizational practices. The results of these methods may be incorporated into any of the higher level assessments. Figure 3 shows where safety analysis methods can be used within the safety assessment process. The PRA/ZSA/CMA include consideration of physical and installation risks fundamental to the definition of both aircraft and system architectures. These analyses interact with the development process throughout the development lifecycle.

#### Functional safety standards recommends activities for system safety analysis: **automotive example**

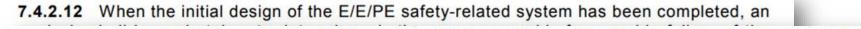


# Functional safety standards recommends activities for system safety analysis: **automotive example**

#### Table 9 — Correct implementation of functional safety and technical safety requirements at the system level

| Methods  |          |          |                     |          |          |  |  |  |
|--|----------|----------|---------------------|----------|----------|--|--|--|
|  | Α        | A B C    |                     | D        |          |  |  |  |
| a Requirement-based test <sup>a</sup>  | ++       | ++       | ++                  | ++       |          |  |  |  |
| b Fault injection test <sup>b</sup>  | +        | +        | ++                  | ++       |          |  |  |  |
| c Back-to-back test <sup>c</sup>   | U        | +        | +                   | ++       |          |  |  |  |
| A requirements-based test denotes a test against functional and non-functional requi   | lirement | ts.      |                     | Fault In | njection |  |  |  |
| A fault injection test uses special means to introduce faults into the system. This can<br>becial test interface or specially prepared elements or communication devices. The met                              | ethod is | often us | n the s<br>sed to i |          | ting     |  |  |  |
| test coverage of the safety requirements, because during normal operation safety mechanisms are not invoked.   |          |          |                     |          |          |  |  |  |
| c A back-to-back test compares the responses of the test object with the responses of a simulation model to the same stimuli, to detect differences between the behaviour of the model and its implementation. |          |          |                     |          |          |  |  |  |

## Functional safety standards recommends activities for system safety analysis: **industrial example**



analysis shall be undertaken to determine whether any reasonably foreseeable failure of the E/E/PE safety-related system could cause a hazardous situation or place a demand on any

IEC 61508-2:2010

system to avoid such failure modes. If this cannot be done, then measures shall be taken to reduce the likelihood of such failure modes to a level commensurate with the target failure measure. These measures shall be subject to the requirements of this standard.

#### 7.4.8 Requirements for system behaviour on detection of a fault

The detection of a dangerous fault (by diagnostic tests, proof tests or by any other in any subsystem that has a hardware fault tolerance of more than 0 shall result in

me a specified action to achieve or maintain a safe state (see Note); or

a) a specified action to achieve or maintain a safe state (see Note); or

b) the isolation of the faulty part of the subsystem to allow continued safe operation of the EUC whilst the faulty part is repaired. If the repair is not completed within the mean repair time (MRT), see 3.6.22 of IEC 61508-4, assumed in the calculation of the probability of random hardware failure (see 7.4.5.2), then a specified action shall take place to achieve or maintain a safe state (see Note).

**FMECA** (Failure modes, effects, and criticality analysis)

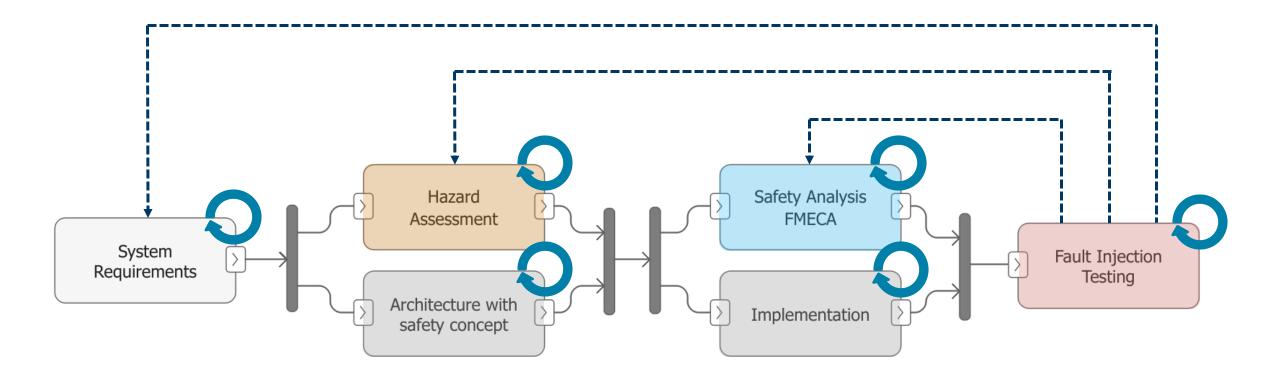
Hazard

Assessment

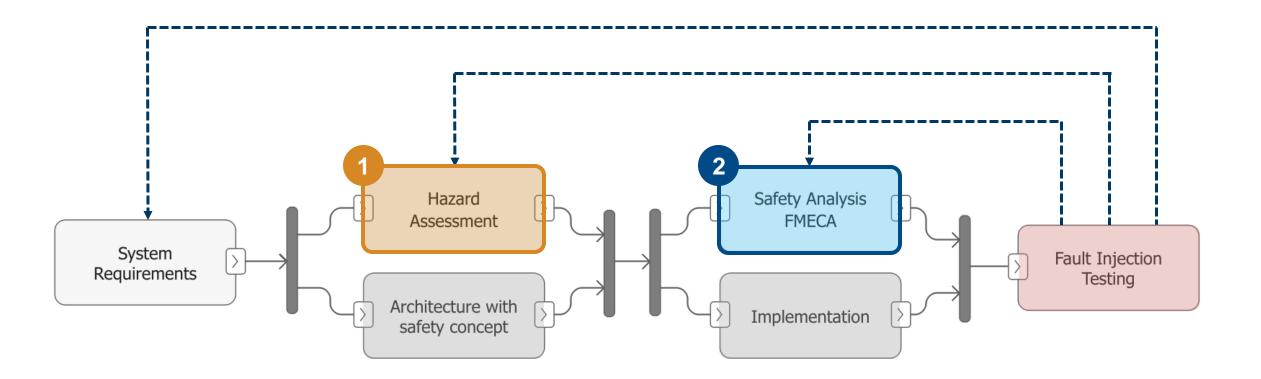
#### Functional safety standards recommends activities for system safety analysis: **industrial example**

| Table B.5 – Techn  | iques and r             | noncurac t | o avoid fou | lte during   | IEC 61508-2 | 2:2010          |
|--|-------------------------|------------|-------------|--------------|-------------|-----------------|
|  | system safe             |            |             | •            |             |                 |
| Technique/measure  | See<br>IEC 61508-7      | SIL 1      | SIL 2       | SIL 3        | SIL 4       |                 |
| Static analysis, dynamic analysis and failure analysis             | B.6.4<br>B.6.5<br>B.6.6 | _<br>low   | R<br>Iow    | R<br>medium  | R<br>high   |                 |
| Simulation and failure analysis                                    | B.3.6<br>B.6.6          | –<br>Iow   | R<br>Iow    | R<br>medium  | R<br>high   |                 |
| Worst-case analysis, dynamic<br>analysis and failure analysis      | B.6.7<br>B.6.5<br>B.6.6 | _<br>low   | –<br>Iow    | R<br>medium  | F<br>high   |                 |
| Static analysis and failure analysis (see Note 4)                  | B.6.4<br>B.6.6          | R<br>low   | R<br>low    | NR           | NR          | Fault Injection |
| Expanded functional testing  | B.6.8                   | low        | HR<br>low   | HR<br>medium | HR<br>high  | Testing         |
| Black-box testing  | B.5.2                   | R<br>Iow   | R<br>low    | R<br>medium  | R<br>hioh   |                 |
| Fault insertion testing (when required diagnostic coverage < 90 %) | B.6.10                  | R<br>Iow   | R<br>low    | R<br>medium  | R<br>high   |                 |

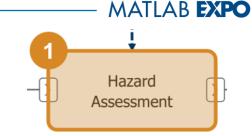
# Safety analysis is a highly **iterative** workflow involving detection, mitigation, and verification



## Safety analysis is a highly **iterative** workflow involving detection, mitigation, and verification



# Let's make an example of a Hazard Assessment **Electric Car Battery**



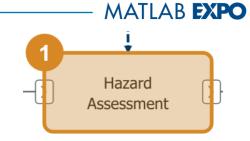
#### **Thermal Runaway**

- **Description**: Uncontrolled increase in temperature within the battery cells.
- **Potential Consequences**: Fire, explosion, damage to the vehicle, injury to occupants.
- Severity: High
- Likelihood: Medium
- Risk Level: High

#### Overcharging

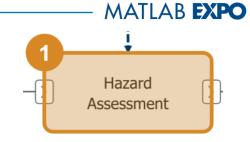
- **Description**: Battery cells receive more charge than their maximum capacity.
- Potential Consequences: Degradation of battery life, thermal runaway, fire.
- Severity: Medium
- Likelihood: Medium
- Risk Level: Medium

# Let's make an example of a Hazard Assessment **Electric Car Battery**



| Hazard          | Description  | Potential Consequences | Severity | Likelihood | Risk Level | Mitigation Measures  |
|-----------------|--|------------------------|----------|------------|------------|--|
| Thermal Runaway | Uncontrolled increase in<br>I Runaway temperature within battery<br>cells Fire, explosion, damage to<br>vehicle, injury to occupants |                        | High     | Medium     | High       | Advanced thermal<br>management system,<br>redundant temperature<br>sensors |
| Overcharging    | Battery cells receive more<br>charge than their maximum<br>capacity  |                        | Medium   | Medium     | Medium     | Battery Management System (BMS), overcharge protection circuits            |

# Let's make an example of a Hazard Assessment **Electric Car Battery**



| Hazard                         | Description  | Potential Consequences   | Severity | Likelihood | Risk Level | Mitigation Measures  |
|--------------------------------|--|--|----------|------------|------------|--|
| Thermal Runaway                | Uncontrolled increase in temperature within battery cells        | perature within battery  |          | Medium     | High       | Advanced thermal<br>management system,<br>redundant temperature<br>sensors                 |
| Overcharging                   | Battery cells receive more charge than their maximum capacity    | Degradation of battery life,<br>thermal runaway, fire  |          |            | Medium     | Battery Management System (BMS), overcharge protection circuits                            |
| Short Circuit                  | Electrical short circuit within battery pack or connections      | Loss of power, thermal runaway, fire   | High     | Low        | Medium     | Insulation, circuit breakers, regular maintenance  |
| Mechanical<br>Damage           | Physical damage to battery<br>pack due to impact or<br>vibration | Short circuit, thermal runaway, fire, reduced battery performance                                  | High     | Medium     | High       | Robust battery enclosure, impact sensors   |
| Overheating<br>During Charging | Excessive heat generated during the charging process             |  |          | Low        | Medium     | Advanced thermal<br>management system, pressure<br>sensor for coolant leakage<br>detection |
| Software<br>Malfunction        | Failure of battery<br>management system (BMS)<br>software        | Incorrect battery monitoring<br>and control, overcharging,<br>deep discharging, thermal<br>runaway | High     | Low        | Medium     | Software validation, redundancy in control system  |

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# Failure modes, effects, and criticality analysis (FMECA) **Electric Car Battery**



| Component      | Potential<br>Failure Mode | Potential Effect(s)                     | Sever<br>ity (S) | Potential Cause(s)     | Occurre<br>nce (O) | Current Control(s)                    | Detecti<br>on (D) | Risk Priority<br>Number |
|----------------|---------------------------|---|------------------|------------------------|--------------------|---------------------------------------|-------------------|-------------------------|
| Cooling Medium | Leakage                   | Loss of cooling efficiency, overheating | 8                | Puncture, poor sealing | 3                  | Regular maintenance,<br>robust design | 3                 | 72                      |
|                | Contamination             | Reduced heat transfer<br>efficiency     | 6                | Impurities in coolant  | 2                  | Filtration system                     | 3                 | 36                      |

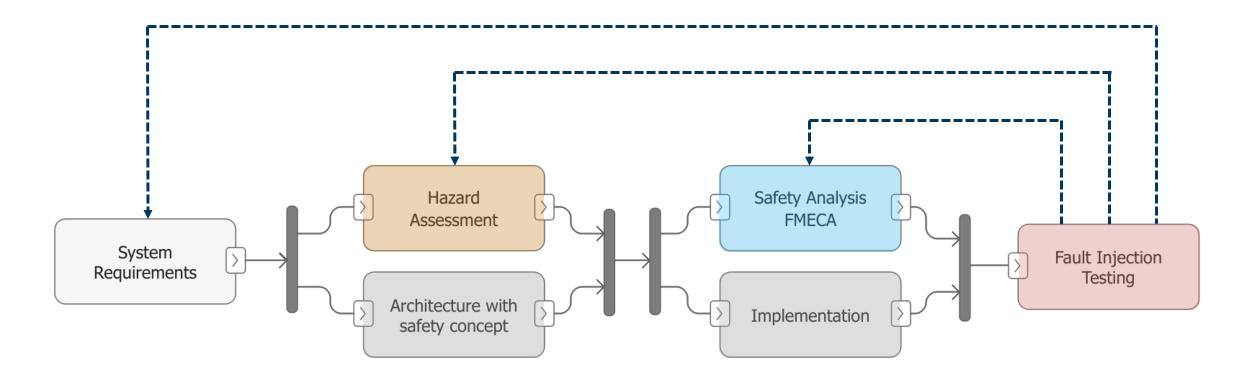
#### MATLAB EXPO

# Failure modes, effects, and criticality analysis (FMECA) **Electric Car Battery**

2 Safety Analysis FMECA

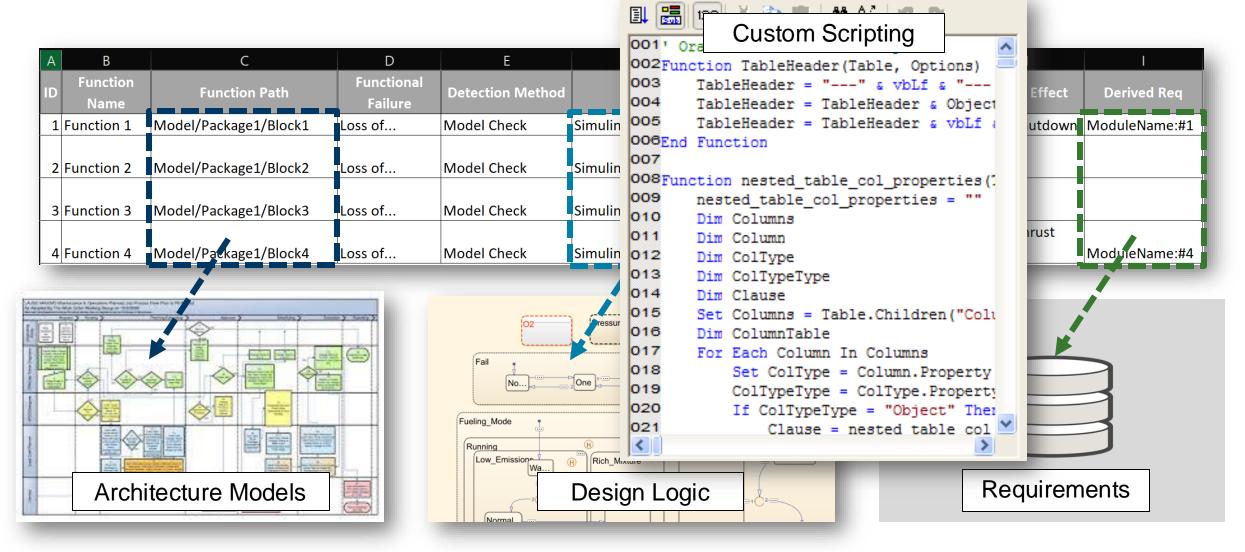
| Component      | Potential<br>Failure Mode | Potential Effect(s)                        | Sever<br>ity (S) | Potential Cause(s)                       | Occurre<br>nce (O) | Current Control(s)                       | Detecti<br>on (D) | Risk Priority<br>Number |
|----------------|---------------------------|--|------------------|--|--------------------|--|-------------------|-------------------------|
| Cooling Medium | Leakage                   | Loss of cooling efficiency, overheating    | 8                | Puncture, poor sealing                   | 3                  | Regular maintenance,<br>robust design    | 3                 | 72                      |
|                | Contamination             | Reduced heat transfer efficiency           | 6                | Impurities in coolant                    | 2                  | Filtration system                        | 3                 | 36                      |
| Heat Exchanger | Blockage                  | Reduced cooling<br>efficiency, overheating | 8                | Debris, corrosion                        | 2                  | Regular inspection and cleaning          | 3                 | 48                      |
|                | Corrosion                 | Leakage, reduced heat transfer             | 7                | Poor material quality, harsh environment | 3                  | Use of corrosion-<br>resistant materials | 4                 | 84                      |
| Coolant Pump   | Mechanical<br>Failure     | Loss of coolant flow, overheating          | 9                | Wear and tear, motor<br>failure          | 3                  | Regular maintenance, quality components  | 3                 | 81                      |
|                | Electrical<br>Failure     | Pump stops working, overheating            | 9                | Electrical faults                        | 2                  | Electrical system checks                 | 3                 | 54                      |
| Control Unit   | Software<br>Malfunction   | Incorrect system operation, overheating    | 9                | Software bugs, control logic errors      | 2                  | Software validation, redundancy          | 3                 | 54                      |
|                | Hardware<br>Failure       | System stops working, overheating          | 9                | Component failure                        | 2                  | Quality control, redundancy              | 3                 | 54                      |

## Safety analysis is a highly **iterative** workflow involving detection, mitigation, and verification

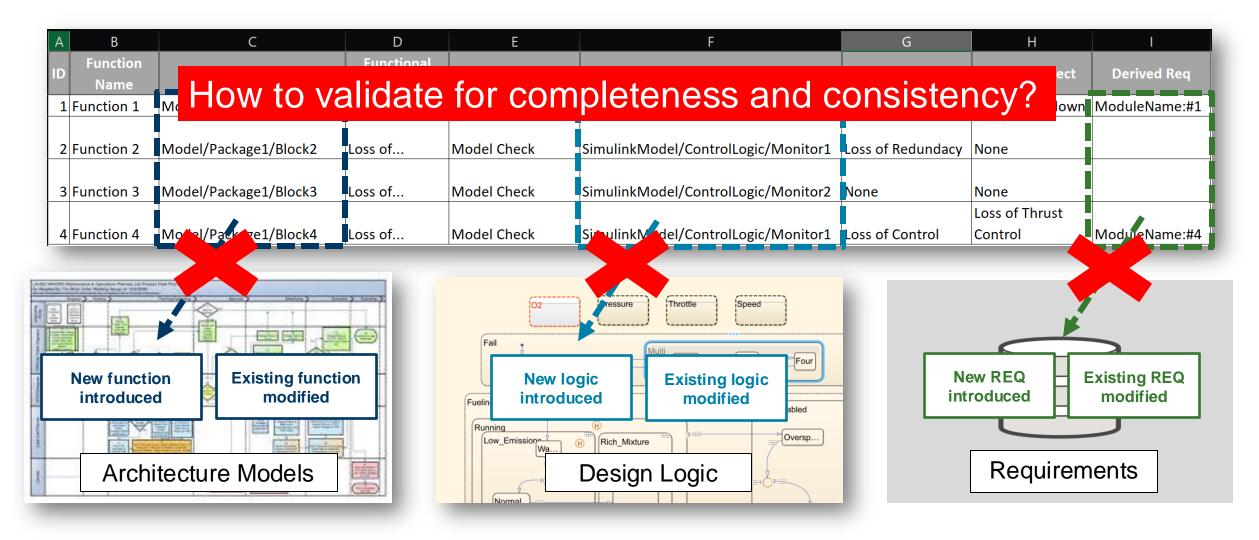


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#### Traditional safety analysis is decoupled from design, complex, complicated and error-prone



# Traditional safety analysis is inherently difficult to validate for completeness and consistency



#### Today's Agenda

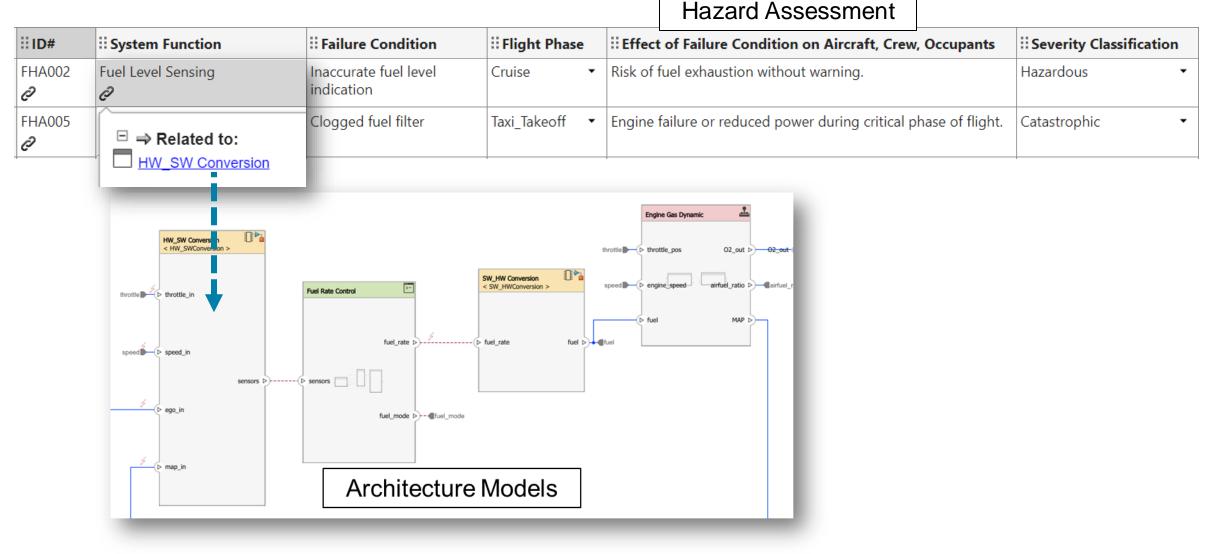
nportance of safety in product development

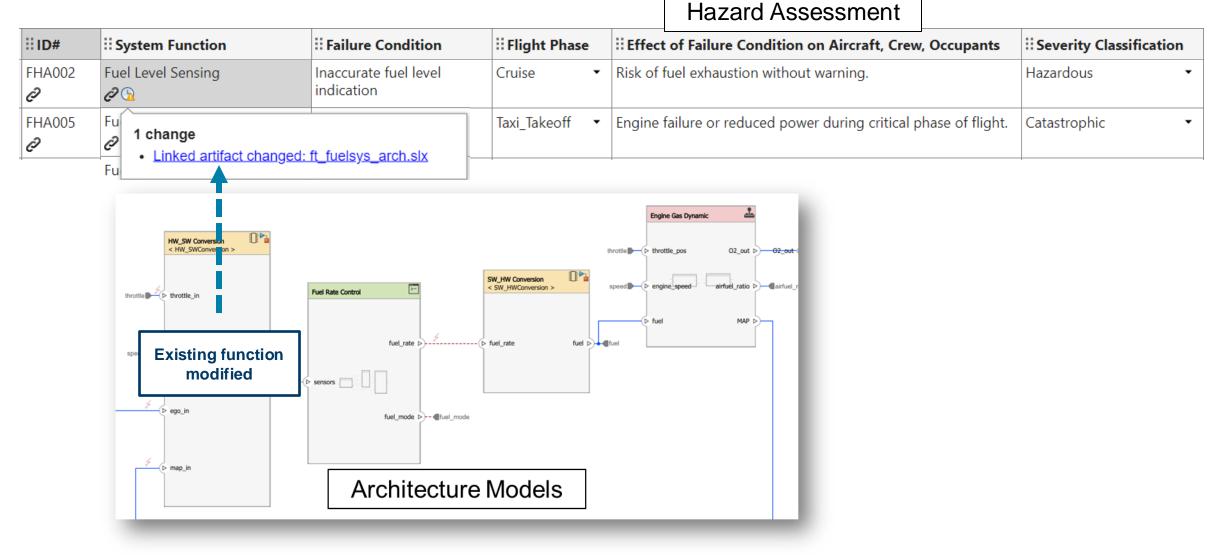
System: Model-based safety analysis workflow

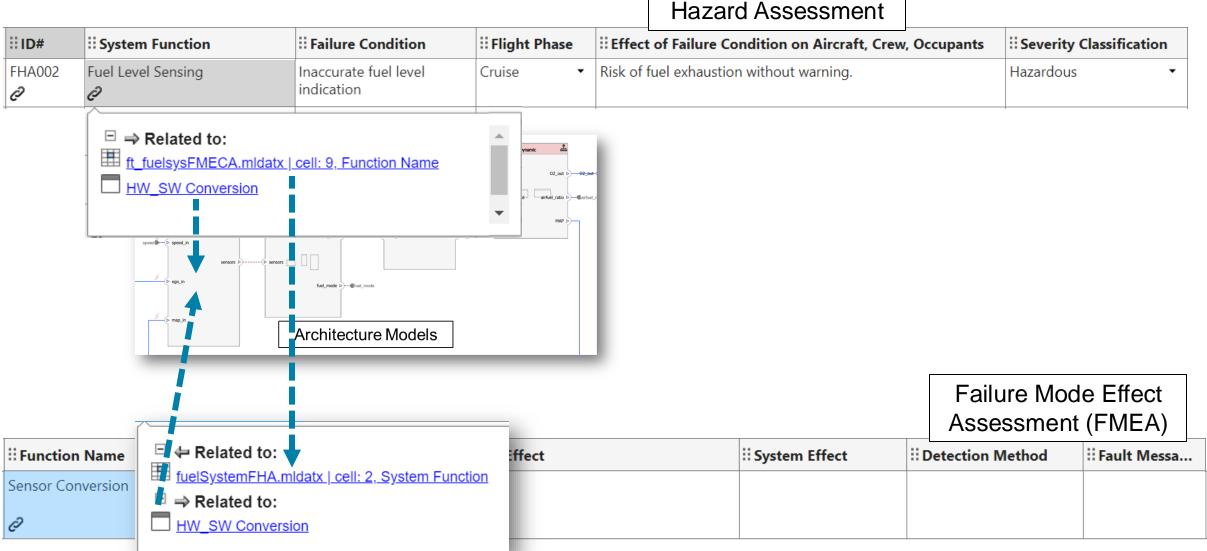
**Component: Fault injection modeling** 

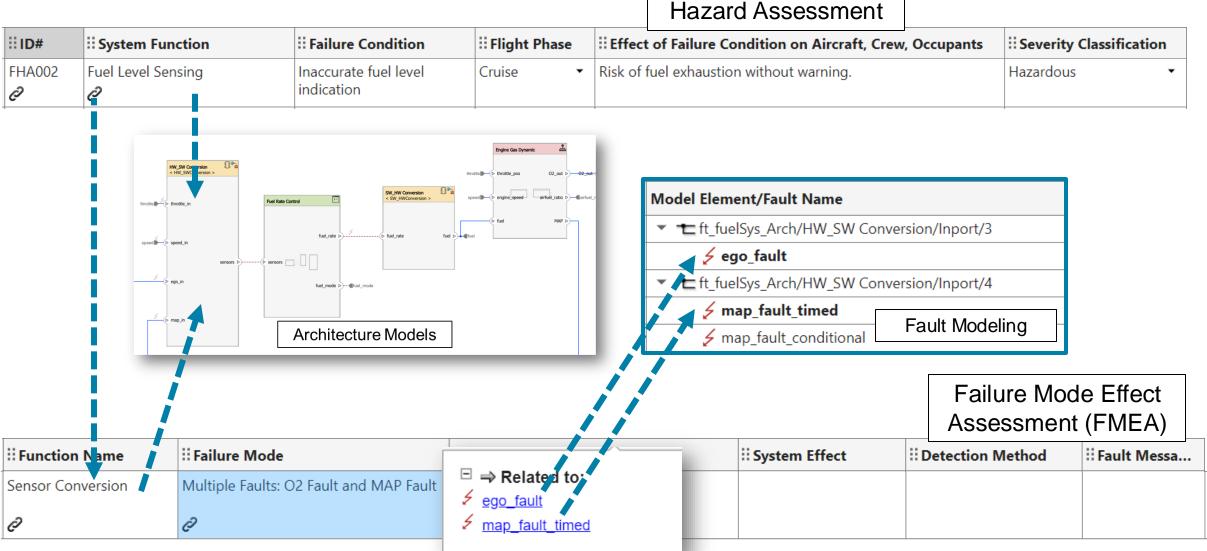
Case Study: Aircraft fuel system

Conclusion

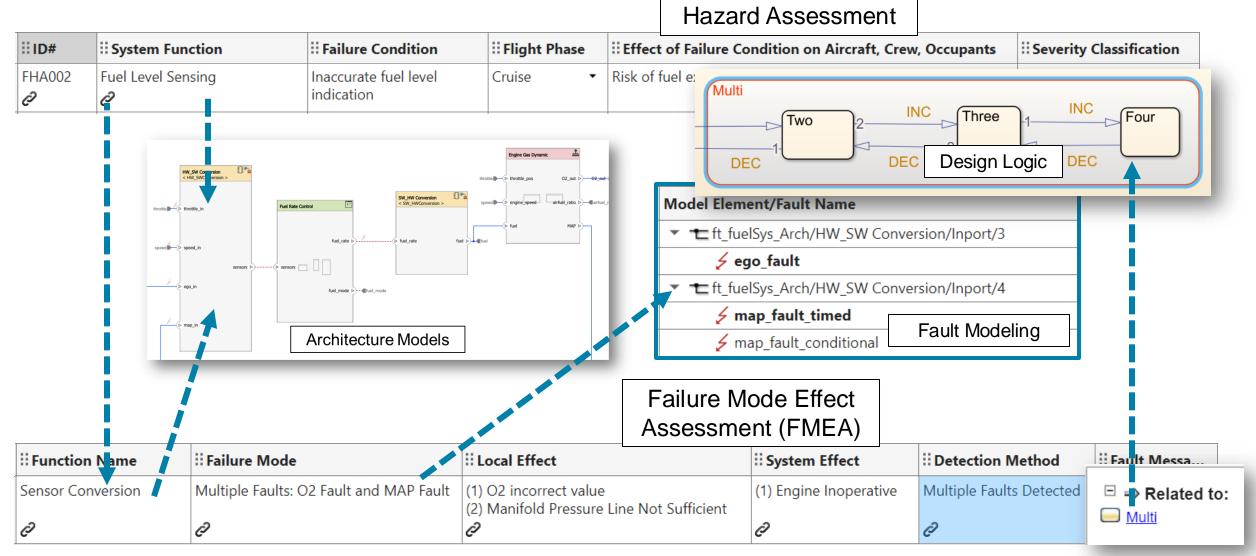








|                    |                           |                                  |   |  | Hazar                                      | d Assessment   | t                |             |                |  |
|--------------------|---------------------------|----------------------------------|---|--|--|--|------------------|-------------|----------------|--|
| ∷ID#               | System Function           | ii Failure Condition             | ii Flight Phase                                 | :: Effect  | of Failure Co                              | ondition on Aircraft, C  | rew, Occupants   | Severity    | Classification |  |
| FHA002<br><i>©</i> | Fuel Level Sensing        | Inaccurate fuel level indication | Cruise •  | <ul> <li>Risk of fuel exhaustion without warning.</li> </ul> |  |  |                  | Hazardous   | •              |  |
|                    | speed_in                  | uel Rate Control                 | Engine Gas Dynamic                              |  | T ft_fue ✓ tft_fue ✓ tft_fue ✓ tft_fue ✓ m | ent/Fault Name<br>PlSys_Arch/HW_SW Cor<br>go_fault<br>PlSys_Arch/HW_SW Cor<br>ap_fault_timed<br>ap_fault_conditional |                  |             |                |  |
|                    |                           |                                  |   |  |  | ent (FMEA)   |                  |             |                |  |
| ii Functio         | n Name 👘 🗄 Failure Moo    | de                               | Local Effect                                    |  |  | ii System Effect   | <b>Detection</b> | Method      | ii Fault Messa |  |
| Sensor Co          | nversion / Multiple Fault |                                  | (1) O2 incorrect value<br>(2) Manifold Pressure |  | Sufficient                                 | (1) Engine Inoperative   | e Multiple Faul  | ts Detected |                |  |
| Õ                  | Õ                         |                                  | <del>O</del>                                    |  |  | Õ  | Õ                |             |                |  |



#### FMEA is validated by simulating the system architecture with faultinjections using implementation models

|   | #Function Name    | ∺Failure Mode                       | :: Loca             | l Effect                         | System Effect                            | ii Detection Method   | ii Fault Messa |
|---|-------------------|-------------------------------------|---------------------|----------------------------------|--|---|----------------|
| 1 | Sensor Conversion | nversion O2 stuck (1)               |                     | incorrect value                  | (1) Engine Operation<br>Interrupted      | O2 Fault Detection  | O2Stat         |
| 2 | Sensor Conversion | Analyze Spreadshe                   | eet F5              | old Pressure Line Not Sufficient | (1<br>In Failure mode dete               | <ul> <li>1 check</li> <li>Failure mode detected during simulation.</li> </ul> |                |
|   | Q                 | Custom Callbacks                    |                     |                                  |  |   |                |
| 3 | Sensor Conversion | version SyncReftables               |                     | old Pressure Line Not Sufficient | (1) Engine Operation<br>Interrupted<br>2 | Manifold Pressure Fault<br>Detection  | MAPStat        |
| 4 | Sensor Conversion | StaticChecks                        |                     |                                  | (1) Engine Inoperative                   | Engine Speed Fault<br>Detection<br>9 2  | EngSpeedStat   |
| 5 | Sensor Conversion | ✓ ValidateFMECA                     |                     | ≥ Speed too low                  | 1 error<br>• Failure mode not de         | etected during simulation.  | ngSpeedStat    |
| 6 | Sensor Conversion | speed high noise                    | (1) Eng             | jine Speed too high              | (1) Engine Operation<br>Interrupted      | Engine Speed Fault<br>Detection<br>9 2  | EngSpeedStat   |
| 7 | Sensor Conversion | throttle stuck at value             | (1) Thr             | ottle position not moving        | (1) Engine Inoperative                   | Engine Throttle Fault<br>Detection  | ThrottleStat   |
| 8 | Fuel Control      | fuel rate stuck at zero<br><i>?</i> | (1) Fue<br><i>©</i> | el to burners too low            |  | 9   |                |

#### Today's Agenda

mportance of safety in product development

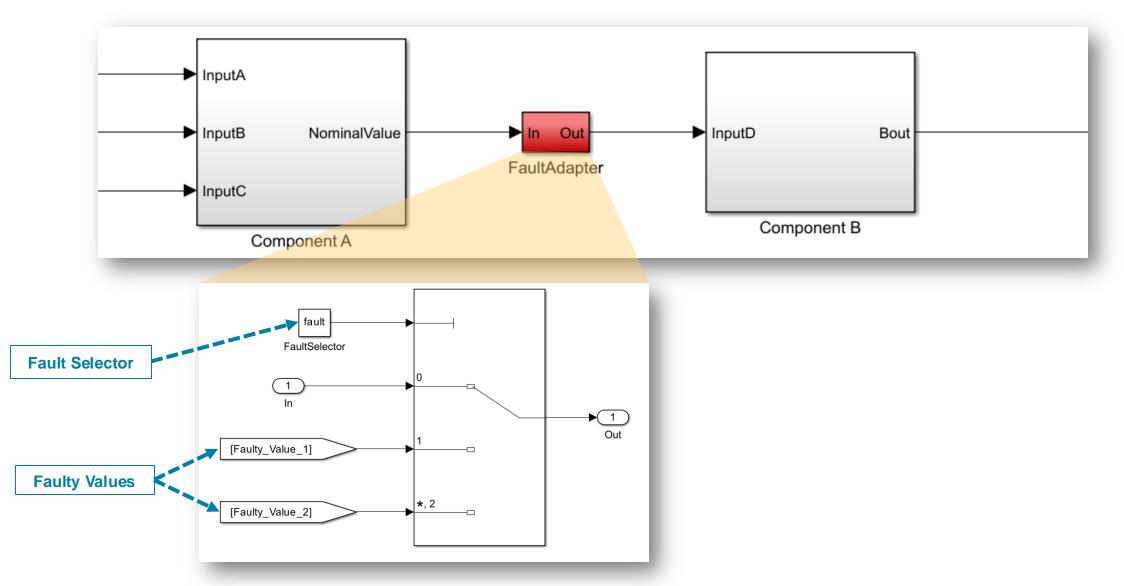
System: Model-based safety analysis workflow

**Component: Fault injection modeling** 

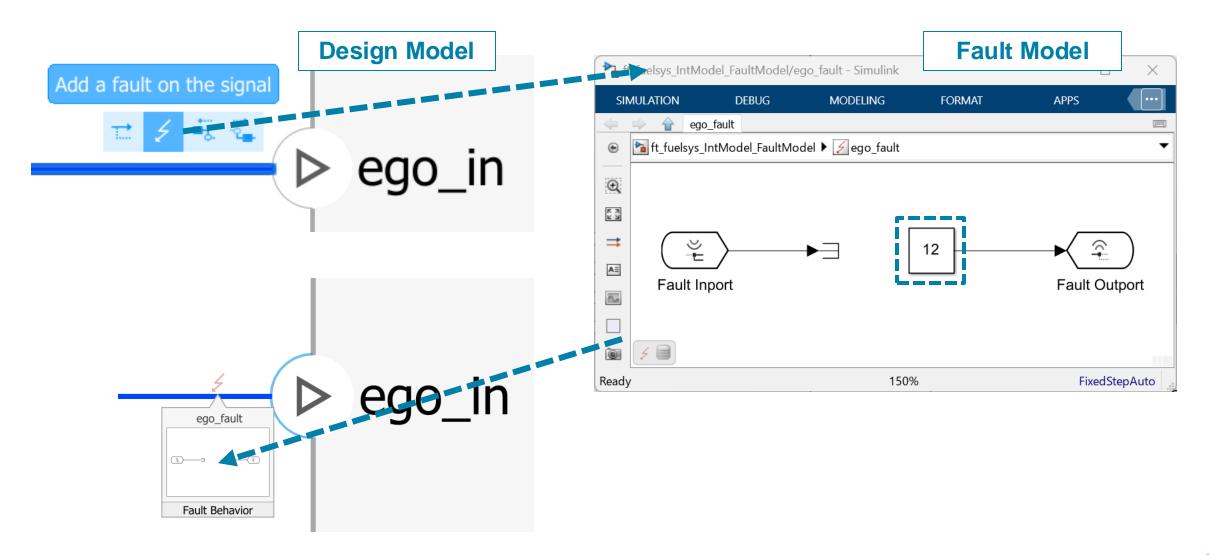
Case Study: Aircraft fuel system

Conclusion

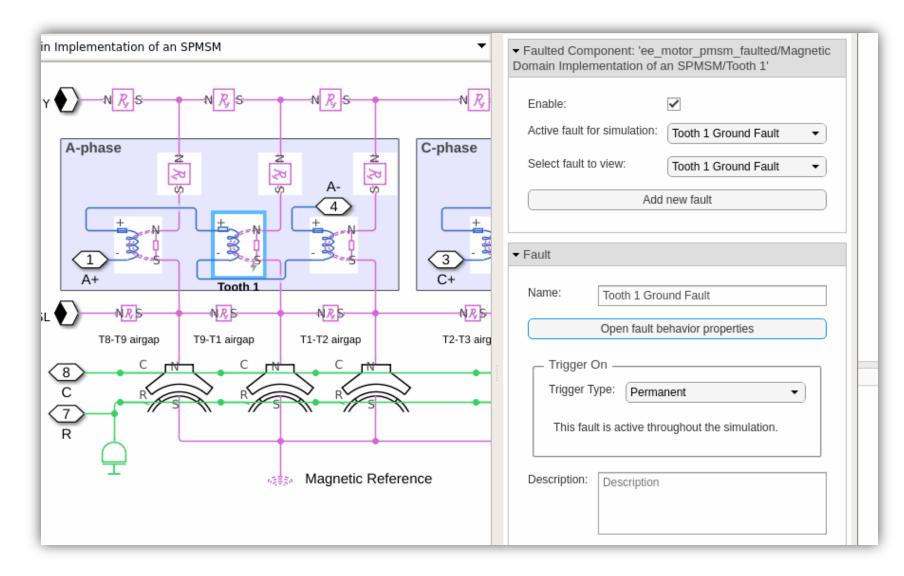
Fault modeling today modifies the design, makes it difficult to analyze effects and is not connected to hazards



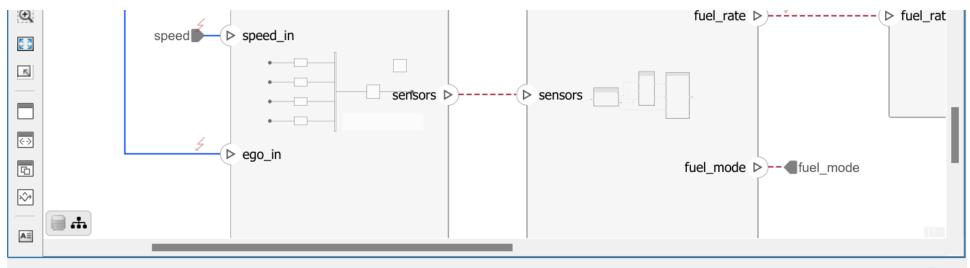
## New enhanced fault modeling is separated from the design, makes it easy to analyze effects and is connected to hazards



## New enhanced fault modeling is separated from the design, makes it easy to analyze effects and is connected to hazards



#### New enhanced fault modeling is separated from the design, makes it easy to analyze effects and is connected to hazards



Fault Table - ft\_fuelsys\_IntModel\_faultInfo.xml\*

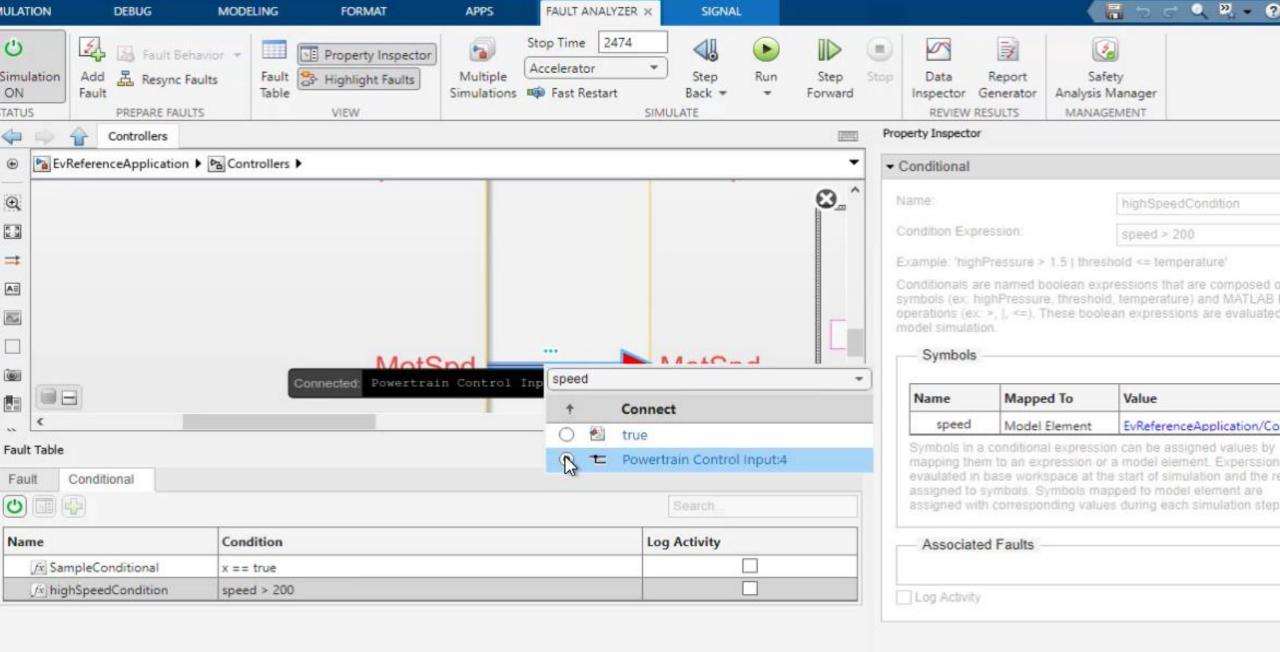
Θ×

| Fault  | Conditional       |                                       |              |                                |                             |
|--------|-------------------|---------------------------------------|--------------|--------------------------------|-----------------------------|
|        |                   | All faults in model                   | On/Off       | Time/Condition                 |                             |
| Enable | Model Elei        | ment/Fault Name                       | Active Fault | Trigger                        | Description                 |
| ✓      | ▼ <b>*⊏</b> ft_ft | uelSys_Arch/HW_SW Conversion/Inport/3 |              |                                |                             |
|        | 5                 | ego_fault                             |              | Timed: 5                       | O2 value stuck              |
| ✓      | ▼ 🛨 ft_ft         | uelSys_Arch/HW_SW Conversion/Inport/4 |              |                                |                             |
|        | 4                 | map_fault_timed                       |              | Timed: 10                      | Maniifold prressure too low |
|        | 4                 | map_fault_conditional                 |              | Conditional: SampleConditional |                             |
|        | ▼ <b>*</b> ft_ft  | uelSys_Arch/HW_SW Conversion/Inport/2 |              |                                |                             |
|        | 4                 | speed_high                            |              | Always On                      |                             |

Modelling Faults without Modifying the Design

|                                     | nodel element and specify the fault properties. To manage the fault, access the Faul<br>/ clicking on the fault badge in the model or by opening the Fault Table pane. |   |       | REVIEW RESU | 1013 |  |
|-------------------------------------|--|---|-------|-------------|------|--|
| asic Properties                     | Description  |   |       |             |      |  |
| Nodel element:                      | EvReferenceApplication/Environment/Constant6/Outport/1   | - |       |             |      |  |
| ault name:                          | Temp_fault   |   |       |             |      |  |
|                                     | Save fault information Help  |   |       |             |      |  |
| Fault information                   | b directory: Current working directory Browse  | 4 |       |             |      |  |
| Fault library: n<br>Add fault behav | or to: New fault model  V Fault behavior: Stuck-at-Ground  V   |   |       |             |      |  |
| Fault model dire                    | ctory: Current working directory Browse  |   | 1     | )           |      |  |
|                                     | enceApplication_FaultModel   | ] | ironm | ent         |      |  |
| Name: EvRefer                       |  |   |       |             |      |  |
|                                     | Always On 🗸  |   |       |             |      |  |

Modelling Conditional Fault Injections



Analyzing Fault Effects using Batch Simulations

| EvReference                      | Application - Simulink prere  | lease use  |  |                         |                  |   |             |                    |   |  |                     |
|----------------------------------|---|--|--|-------------------------|------------------|---|-------------|--------------------|---|--|---------------------|
| SIMULATION                       | MARK CONTRACTOR   | MODELING   | FORMAT   | APPS                    | FAULT ANALYZER > | SUBSYSTEM                               | BLOCK       |                    |   | ि च ट २ थ्     थ | - ? - •             |
| Fault Simulation<br>ON<br>STATUS | n Add & Resync Faults<br>Fault<br>PREPARE FAULTS  |  | Property Inspector<br>Highlight Faults<br>VIEW                                     | Multiple<br>Simulations | 1                | Step<br>Back +                          | Run         | Step Sto<br>Srward | Data Report<br>Inspector Generator Anal<br>REVIEW RESULTS MA  | Safety<br>ysis Manager<br>NNAGEMENT  |                     |
|                                  | Design Study  | Refresh<br># Sims<br>7   | <ul> <li>EvRefere</li> <li>EvRefere</li> <li>EvRefere</li> <li>EvRefere</li> </ul> | EvReferenceApp          |                  | Enviro                                  | nment       |                    | Faulted Model Element: 'Con     Enable     Select fault to view:  | stant6/Outport/1'<br>HighTemperatureFa<br>Add new fa   | ult 👻               |
| Specific<br>Root                 | s: Design Study<br>ation Run Options<br>t Parameter Set<br>: Set_1  |  | FTP7   | 5 (2474 secon           | ds)              | Longitud                                | inal Driver | •<br>•<br>•        | <ul> <li>✓ Fault</li> <li>Name: HighTemperatu</li> <li>Fault behavior: EvReferenceAp</li> <li>Trigger</li> <li>Trigger type:</li> </ul> | Conditional  | TemperatureFau<br>T |
|                                  | a constant a | Component  |  |                         |                  | [                                       | Search      |                    | Inject fault behavior when a I<br>Select conditional from mode  |  |                     |
|                                  | HighPressureFault<br>LowTemperaturFault<br>LowPressureFault<br>Grade_fault<br>Grade_fault_1                     | EvReferenceA<br>EvReferenceA<br>EvReferenceA<br>EvReferenceA<br>EvReferenceA | Enable   | Model Ele               |                  | Trigger<br>Conditi<br>Conditi<br>Always | Description | -                  | View conditional  Trigger stays on once act  Description:  Description  | tivated  |                     |
| Ready                            | wind_x_fault  | EvReferenceA   | Diagnostic Viewer  | Fault Table             | -                | View diagnos                            | tics        | -11                | 110%  |  | ode23tb             |

### Today's Agenda

mportance of safety in product development

System: Model-based safety analysis workflow

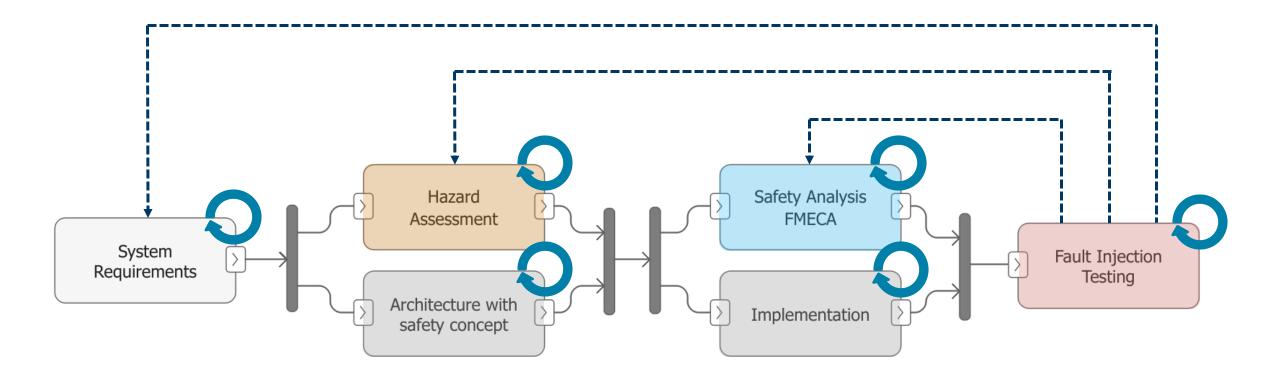
Component: Fault injection modeling

Case Study: Aircraft fuel system

Conclusion

# Model-Based Safety Analysis Example: Aircraft Fuel System

# Safety analysis is a highly **iterative** workflow involving detection, mitigation, and verification



### 

Perform Hazard Analysis

▷) throttle

▷) €speed

Link Analysis to Design Artifacts

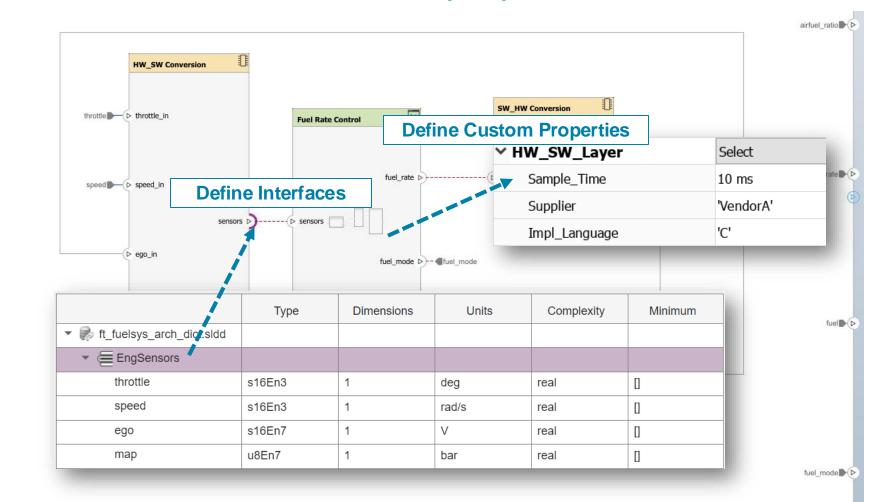
Characterize Faults

Static Checks

Inject Faults & Explore Effects

Validate through Simulation

# Develop your system and software architecture, incl. interfaces and custom properties



Develop Architecture

### >> Perform Hazard Analysis

Link Analysis to Design Artifacts

Characterize Faults

Static Checks

Inject Faults & Explore Effects

Validate through Simulation

# Identify potential hazards that could arise during the system's operation and assess the risks of each one

|             |                    |                                  | Hazard A        | Assessment   | User Defined            |
|-------------|--------------------|----------------------------------|-----------------|--|-------------------------|
| ∷ID#        | System Function    | ii Failure Condition             | ii Flight Phase | Effect of Failure Condition on Aircraft, Crew, Occupants | Severity Classification |
| FHA002<br>🖉 | Fuel Level Sensing | Inaccurate fuel level indication | Cruise 🔹        | Risk of fuel exhaustion without warning.                 | Hazardous 🔹             |

Develop Architecture

Perform Hazard Analysis

Link Analysis to Design Artifacts

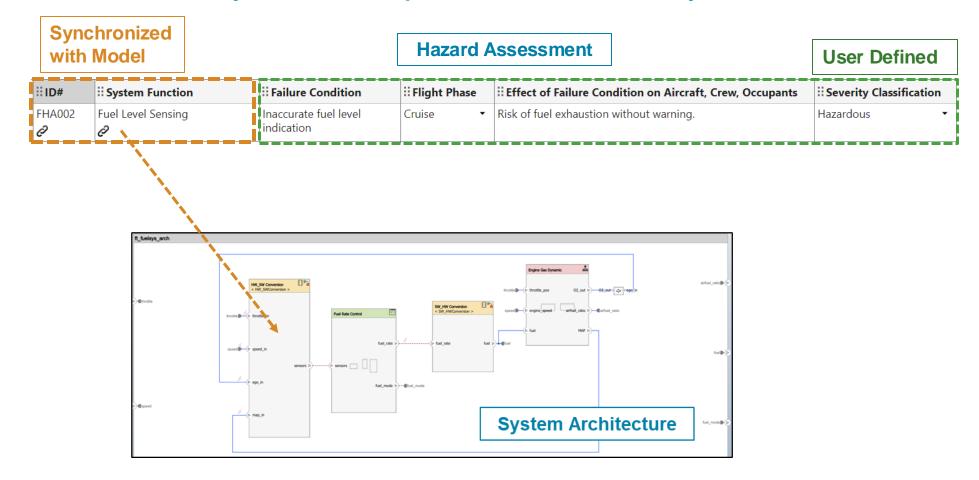
> Characterize Faults

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Validate through Simulation

# Link hazards to system architecture for ensuring consistency and completeness of analysis



Develop Architecture

Perform Hazard Analysis

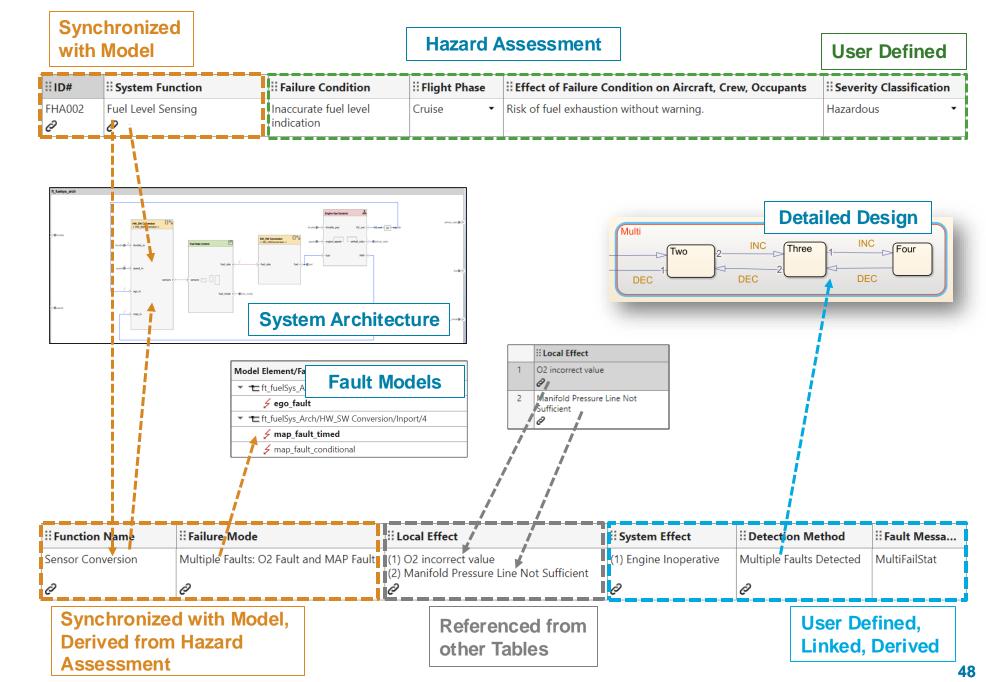
>> Link Analysis to Design Artifacts

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Develop Architecture

Perform Hazard Analysis



Characterize Faults

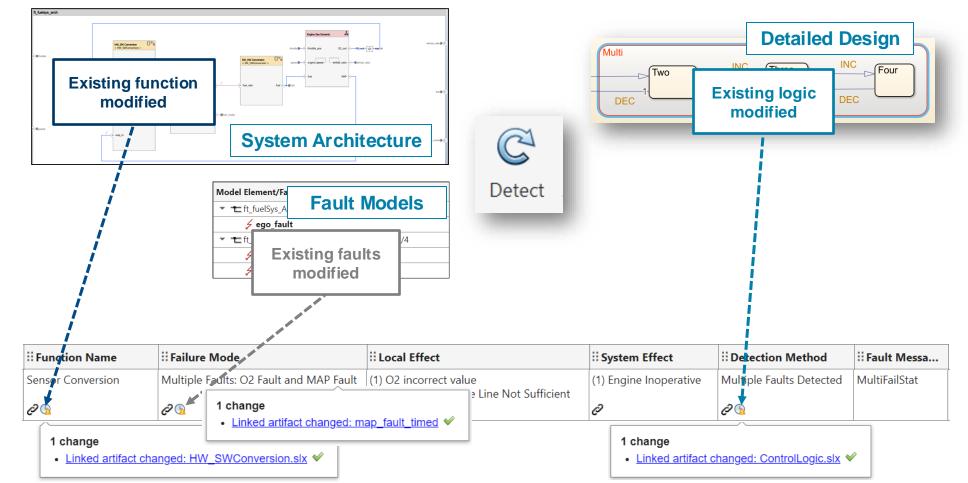
Static Checks

Inject Faults & Explore Effects

Validate through Simulation

# Manage changes using suspect links and reviews

| ∷ID# | System Function    | ii Failure Condition             | ii Flight Phase | Effect of Failure Condition on Aircraft, Crew, Occupants | Severity Classification |
|------|--------------------|----------------------------------|-----------------|--|-------------------------|
|      | Fuel Level Sensing | Inaccurate fuel level indication | Cruise •        | Risk of fuel exhaustion without warning.                 | Hazardous •             |



Four

Fault Messa...

MultiFailStat

**Detailed Design** 

Reviewed

Two

Existing

modifi

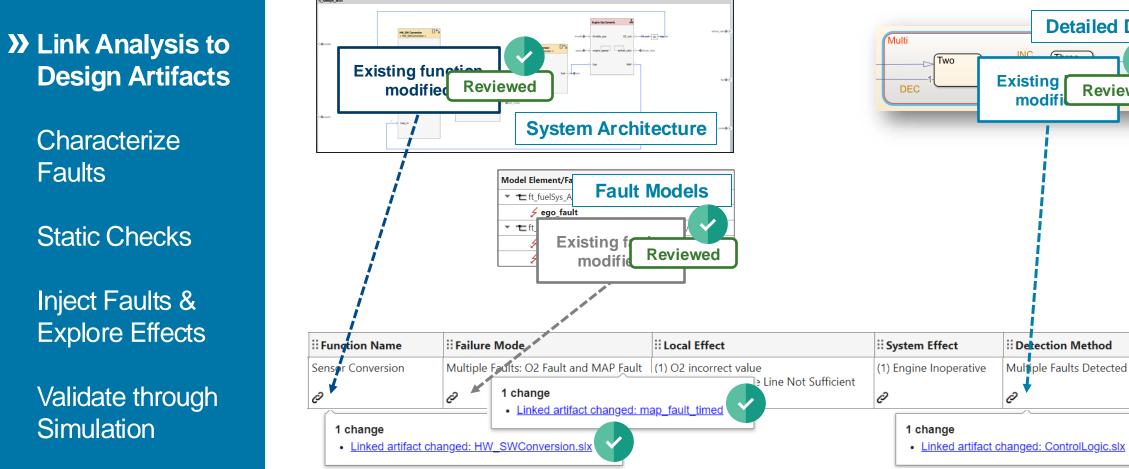
Detection Method

Q

Multiple Faults Detected

Develop Architecture

**Perform Hazard** Analysis



## Manage changes using suspect links and reviews

| ∷ID#               | System Function    | ii Failure Condition             | ii Flight Phase | Effect of Failure Condition on Aircraft, Crew, Occupants | Severity Classification |
|--------------------|--------------------|----------------------------------|-----------------|--|-------------------------|
| FHA002<br><i>©</i> | Fuel Level Sensing | Inaccurate fuel level indication | Cruise •        | Risk of fuel exhaustion without warning.                 | Hazardous 🔹             |

Develop Architecture

Perform Hazard Analysis

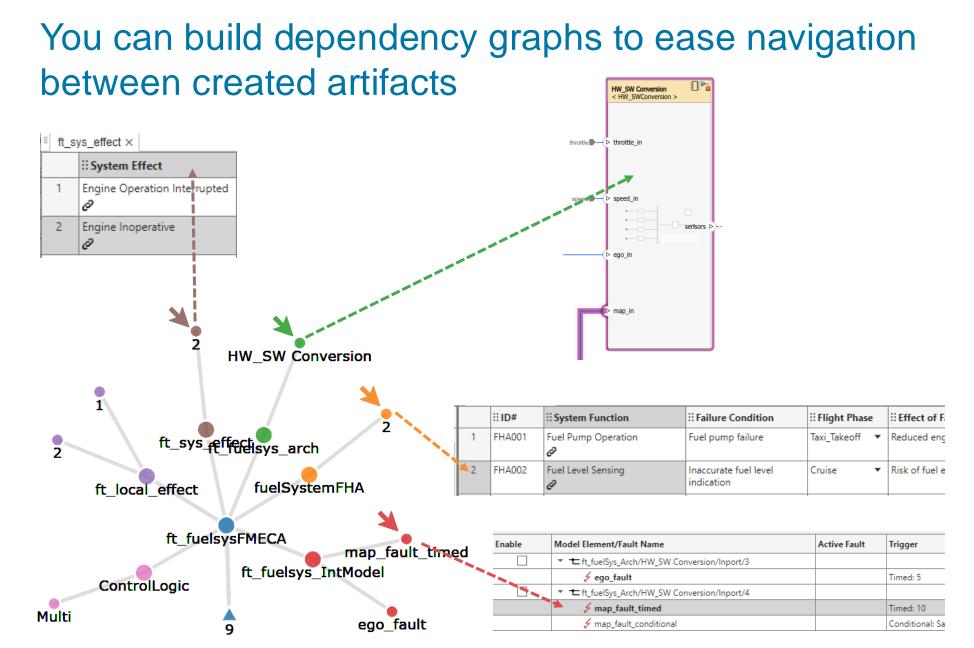
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Develop Architecture

Perform Hazard Analysis

Link Analysis to Design Artifacts

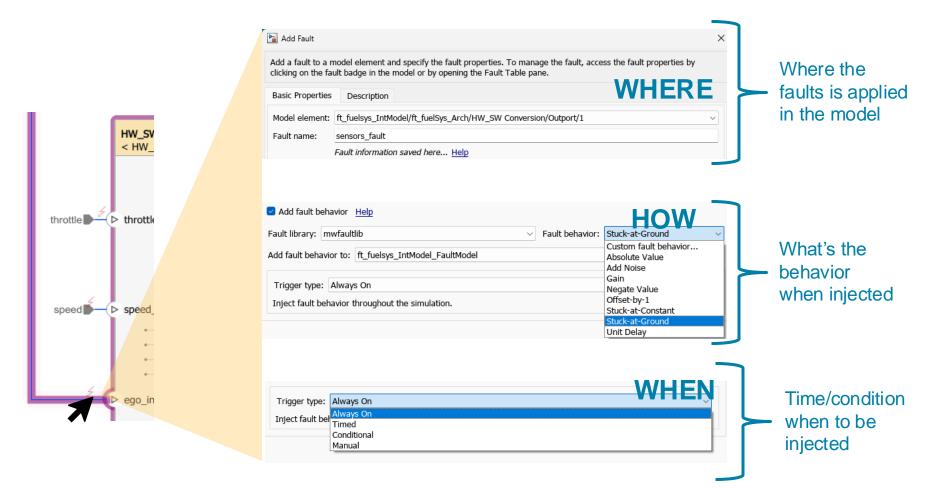
>> Characterize Faults

Static Checks

Inject Faults & Explore Effects

Validate through Simulation

## Model complex faults and easily define WHERE, HOW and WHEN to apply them in simulations



Develop Architecture

Perform Hazard Analysis

Link Analysis to Design Artifacts

Characterize Faults

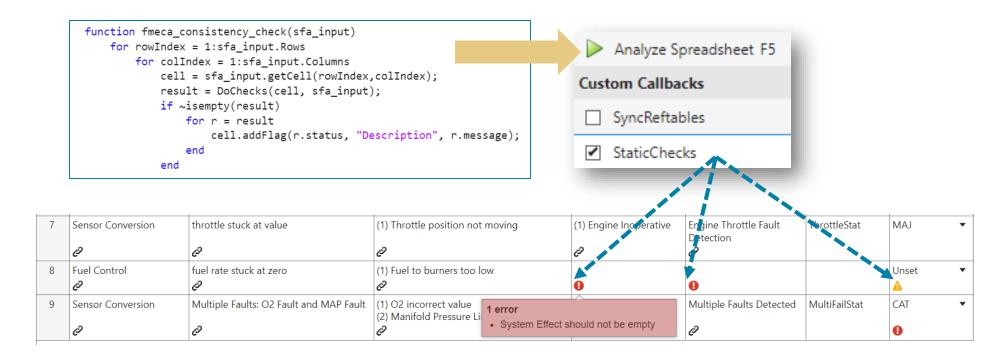
>> Static Checks

Inject Faults & Explore Effects

Validate through Simulation

# Analyze your safety analysis tables using MATLAB scripts for completeness analysis

| 7 | Sensor Conversion | throttle stuck at value $\mathcal{O}$   | (1) Throttle position not moving  | (1) Engine Inoperative | Engine Throttle Fault<br>Detection | ThrottleStat  | MAJ   | • |
|---|-------------------|---|---|------------------------|------------------------------------|---------------|-------|---|
| 8 | Fuel Control<br>🖉 | fuel rate stuck at zero $\mathscr{O}$   | (1) Fuel to burners too low<br><i>O</i>   |                        |                                    |               | Unset | • |
| 9 | Sensor Conversion | Multiple Faults: O2 Fault and MAP Fault | <ul> <li>(1) O2 incorrect value</li> <li>(2) Manifold Pressure Line Not Sufficient</li> </ul> | (1) Engine Inoperative | Multiple Faults Detected           | MultiFailStat | CAT   | • |



### Develop Architecture

Perform Hazard Analysis

# Link Analysis to Design Artifacts

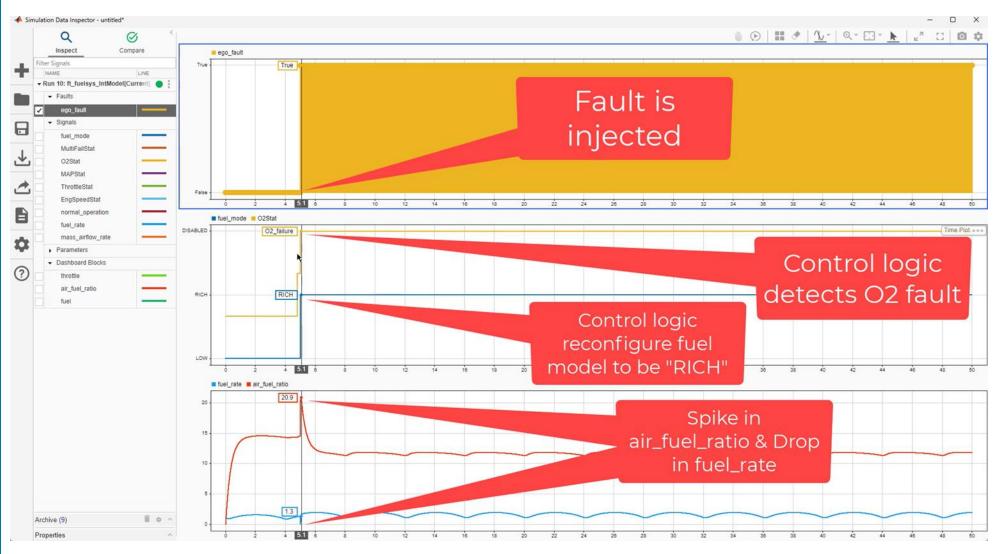
Characterize Faults

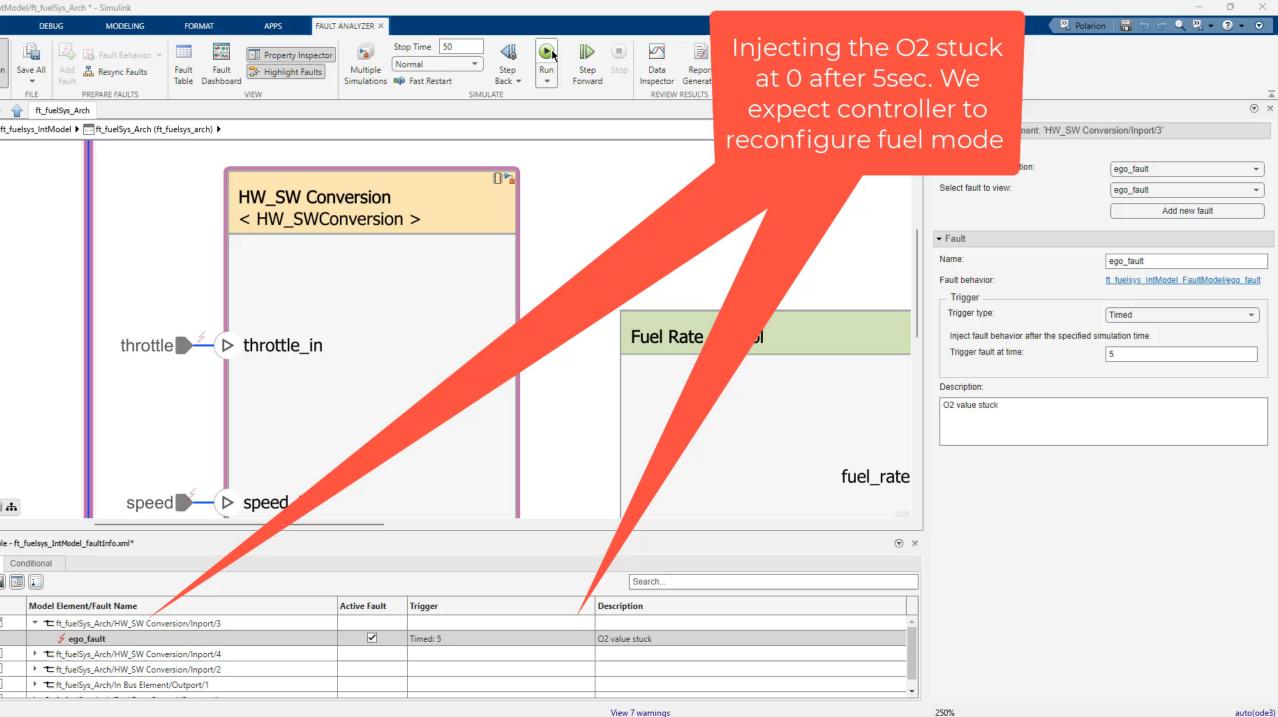
Static Checks

### >> Inject Faults & Explore Effects

Validate through Simulation

# Inject faults in system simulations to explore effects and confirm detection mechanisms have triggered





Develop Architecture

Perform Hazard Analysis

Link Analysis to Design Artifacts

Characterize Faults

Static Checks

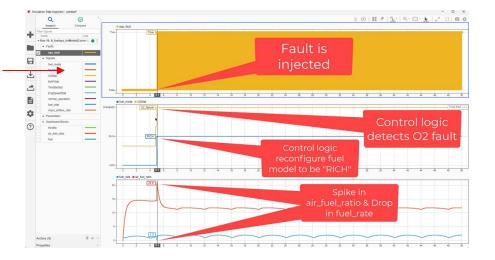
Inject Faults & Explore Effects

>> Validate through Simulation Perform simulations to validate your FMECA and correct design logic in case of fault not detected

# Run For All Faults

**Fault detected** 

| System Effect                                   | :: Detection Method                 | :: Fault Mersa                                     | :: Classification     | :: Probabi             |
|---|-------------------------------------|--|-----------------------|------------------------|
| (1) Engine Operation<br>Interrupted<br>🖉        | 02 Fault Detection                  | O2Stat   | MIN                   | < 10E-3                |
| (1) Engine Operation<br>Interrupted<br>🖉        | Manifold Pressure Faul<br>Detection | t MAPStat  | MAJ 🔻                 | < 10E-5                |
| (1) Engine Operation<br>Interrupted<br>🖉        | Manifold Pressure Faul<br>Detection | t MAPStat  | MAJ 🔻                 | < 10E-5                |
| (1) Engine Inoperative                          | Engine Speed Fault<br>Detection     | Sim Result   |                       | ×                      |
| (1) Engine Inoperative                          | Engine Speed Fault<br>Detection     | Validation Sumamry Re<br>- #1<br>- #2              | esult OverviewValidat | ed Ids: <sup>lie</sup> |
| (1) Engine Operation<br>Interrupted<br><i>O</i> | Engine Speed Fault<br>Detection     | - #3<br>- #5<br>- #7                               |                       |                        |
| (1) Engine Inoperative                          | Engine Throttle Fault<br>Detection  | Not Validated Ids:<br>- #4<br>- #6<br>- #8<br>- #9 |                       |                        |
|   | θ                                   | - 10   | ок                    |                        |
| (1) Engine Inoperative                          | Multiple Faults Detecte             |  | [                     |                        |
| 0   | 02                                  |  |                       |                        |



### Today's Agenda

mportance of safety in product development

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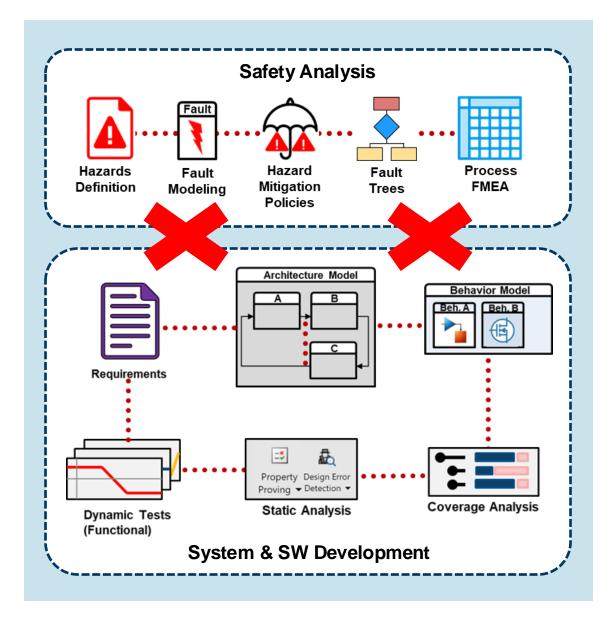
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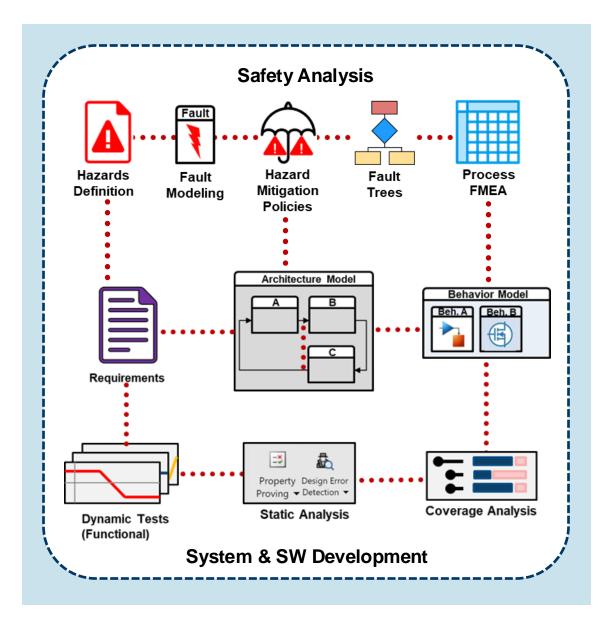
### Key Takeaways

- Traditional Safety Analysis is
  - Decoupled from design work
  - Complex and complicated
  - Error-prone



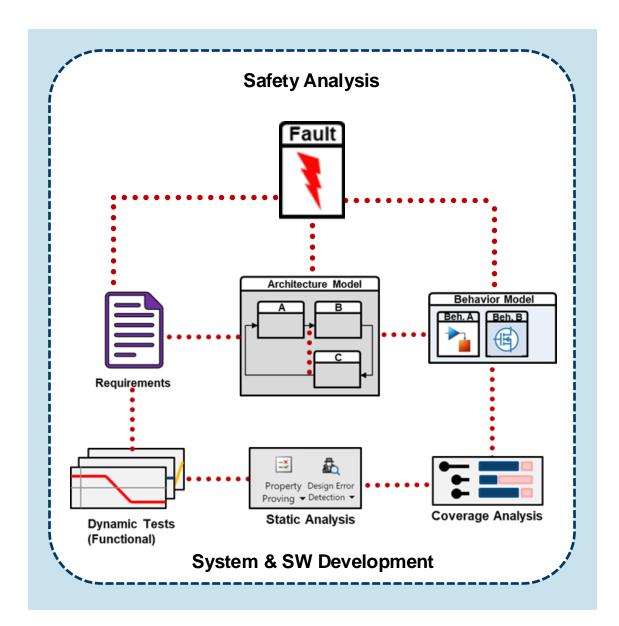
## Key Takeaways

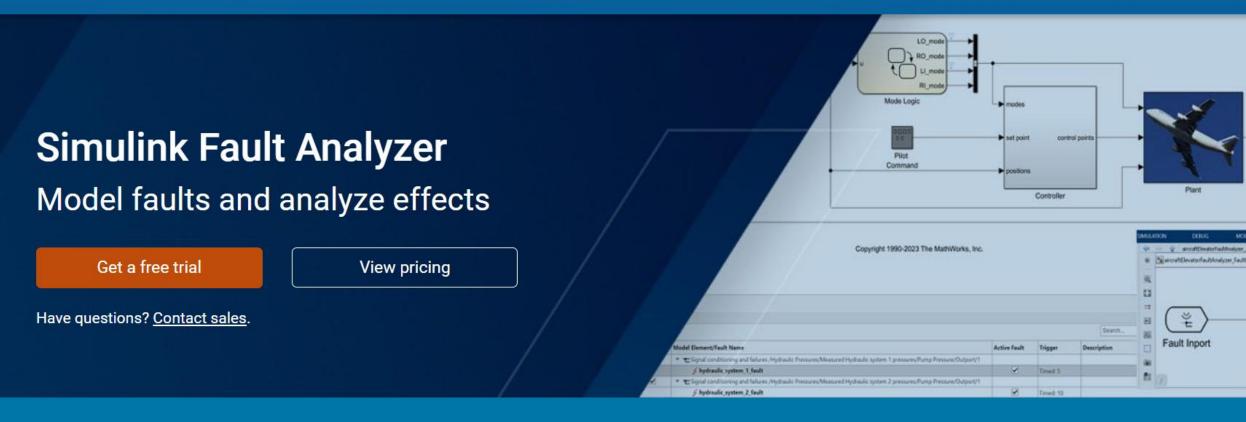
- <u>Model-Based</u> Safety Analysis is
  - Fully integrated with design
  - Fully traceable w.r.t. changes
  - Consistent
  - Validated by simulation



### Key Takeaways

- Enhanced Fault Modeling
  - Separated from design
  - Supports **complex** faults
  - Analyze fault effects
  - Connected to hazards





Simulink Fault Analyzer enables systematic fault effect and safety analysis using simulation.

Simulink Fault Analyzer performs fault injection simulations without modifying your design. Faults can be timed or triggered by system conditions. You can manage faults that are modeled in Simulink, Simscape, and System Composer. Fault effects can be analyzed with Simulation Data Inspector. You can conduct fault sensitivity

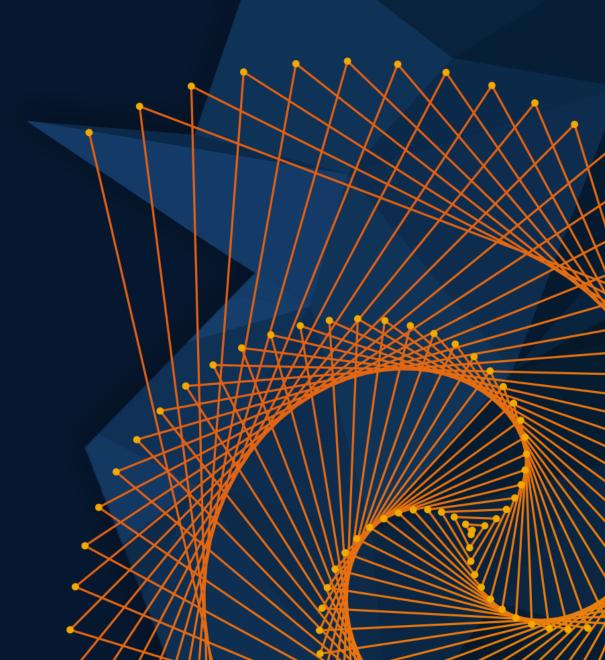


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# Thank you!



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