

MATLAB EXPO

모델 기반 설계를 이용한 광전 센서 성능 예측 모델

임재정 수석 연구원, 오토닉스



CONTENTS

I Introduction

1. About Autonics

2. Optical Sensors?

3. Optical Sensor Element

Technology

II Review Purpose

1. Introduction Background

- Conventional Development

2. Purpose

3. MBD Adaptation

III Detail Review

1. Requirements Management

2. Design

3. Implementation

4. Integration and Verification

IV Summary



CONTENTS

I Introduction

1. About Autonics

2. Optical Sensors?

3. Optical Sensor Element

Technology

II Review Purpose

1. Introduction Background

- Conventional Development

2. Purpose

3. MBD Adaptation

III Detail Review

1. Requirements Management

2. Design

3. Implementation

4. Integration and Verification

IV Summary



About Autonics

Autonics is a globally trusted provider of industrial automation products from South Korea.

Autonics is a leading provider of automation solutions in South Korea. We develop and manufacture a wide range of automation-related products which are marketed worldwide. Our core products include various sensors, control devices, motion devices, process automation instruments, control switches, and peripheral connection equipment.

Our products are trusted and adopted by engineers in various industrial applications including food manufacturing & packaging, plastic & rubber processing, semiconductor equipment, and metalworking machinery.

Our technology is also widely applied in day-to-day automation devices including elevators, screen doors, ATM machines, CCTVs, and electronic office equipment.

Overview

Make Life Easy: **Autonics**

Headquartered in
South
Korea

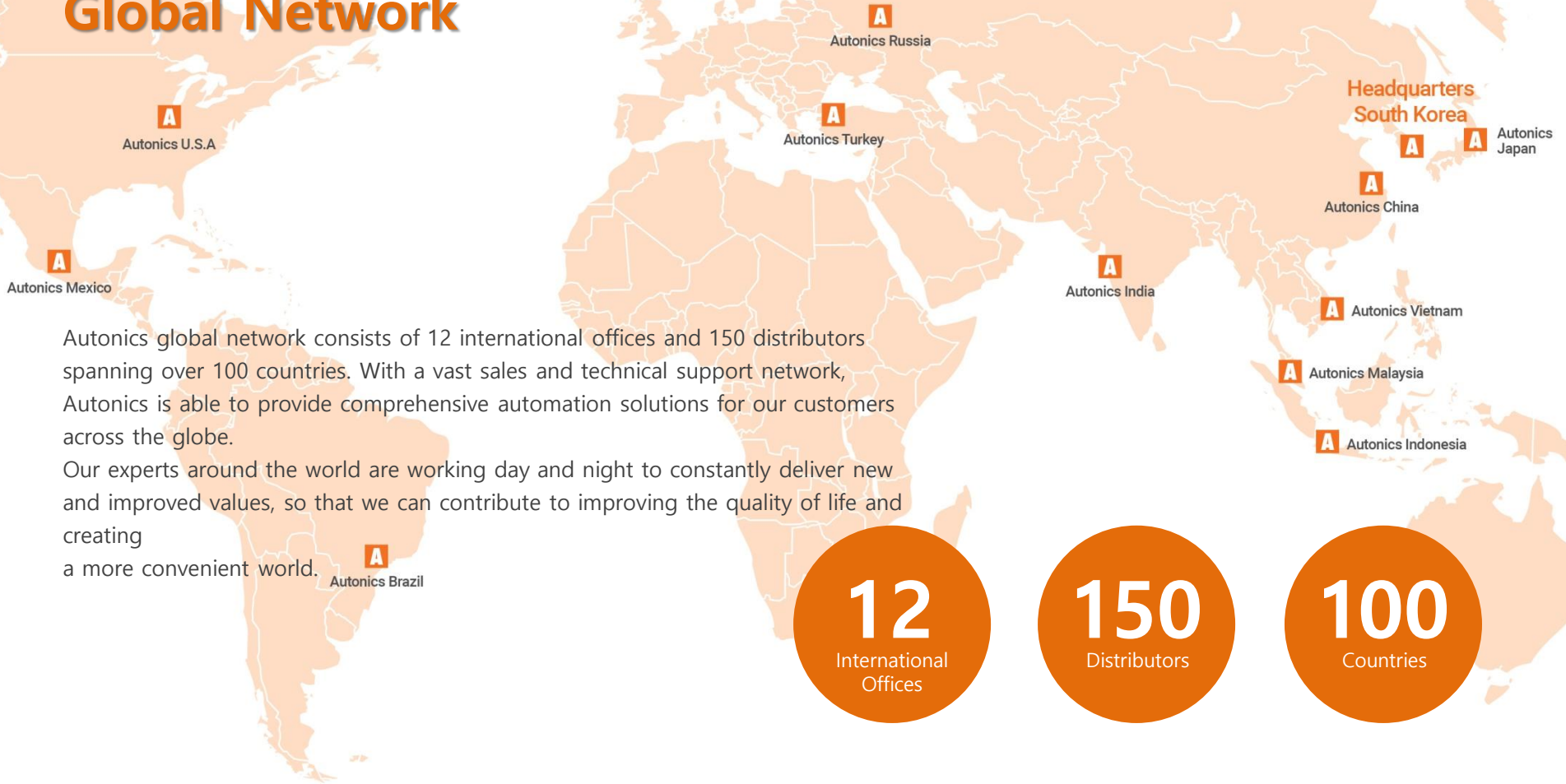
Korea's Top
Automation
Company

Specializes in
Industrial
Automation

Provides
Total
Solutions

Manufacturer of
Sensors
Controllers
Motion Devices
& More

Global Network



Autonics global network consists of 12 international offices and 150 distributors spanning over 100 countries. With a vast sales and technical support network, Autonics is able to provide comprehensive automation solutions for our customers across the globe.

Our experts around the world are working day and night to constantly deliver new and improved values, so that we can contribute to improving the quality of life and creating a more convenient world.

Research & Development

Autonics R&D Center (Seoul, S. Korea)

Autonics R&D Center is the hub of research and development aiming to advance current technology and securing new source technology. The R&D center also promises to strengthen research capabilities for diverse automation solutions across all industries.



Quality & Production Technology & Production Department

Autonics Reliability Center

Reliability Control Center

(Busan, S. Korea)

The Autonics product reliability center features state of the art equipment capable of EMC tests, to expand the certification and reliability of our products.

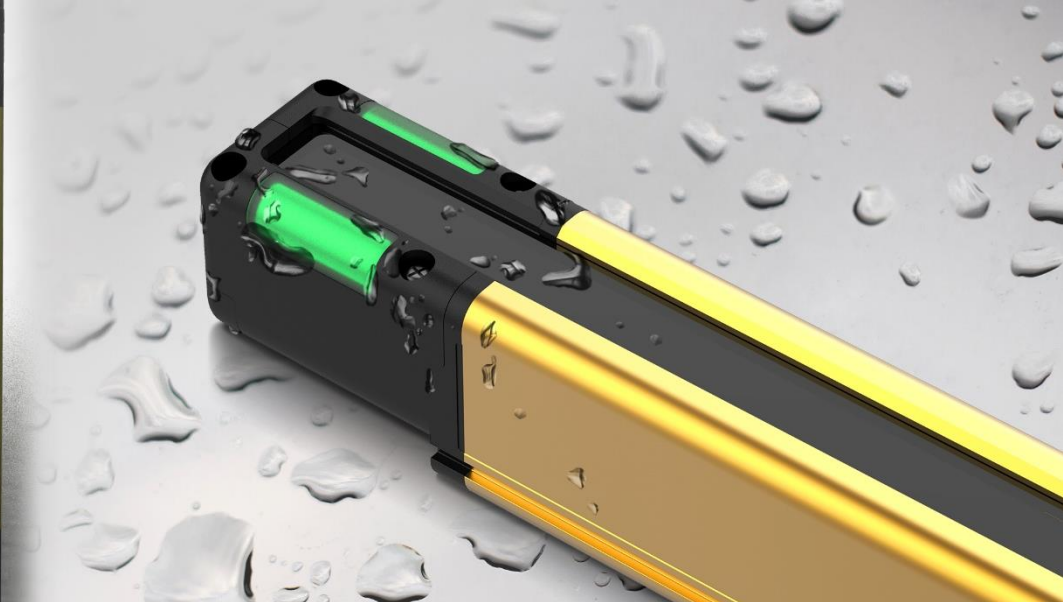
Products



- Sensor
- Controllers
- Motion Devices
- Connectivity
- Control Switches
- Software
- Field Instruments

Safety System

Safety products are installed in potentially dangerous or hazardous areas to safeguard personnel from injury and protect equipment from damage.



Safety Light Curtains

- Safety Light Curtain



Safety Switches

- Door Switches
- Door Lock Switches
- Safety Non-Contact Door Switch
- E-Stop Push Button Switches



Safety Controllers

- Controllers
- Relay Units



Sensors

Sensors are the most essential and commonly used components in automation systems. Autonics provides a wide variety of industrial and commercial sensors, ensuring that the most fundamental parts of automation systems are built with quality and performance.

Displacement Sensor



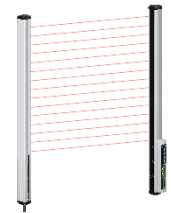
LiDAR



Photoelectric Sensors



Area Sensors



Vision Sensor



Proximity Sensors



Fiber Optic Sensors



Controllers



Controllers are widely used in various industrial settings to adjust or maintain desired outputs of specific processes within a desired range. Autonics provides a diverse range of highly accurate and reliable controllers for stable and ideal system control.



Temperature Controllers



Power Controllers



Solid State Relays



Counter



Industrial PC



SMPS



Timer

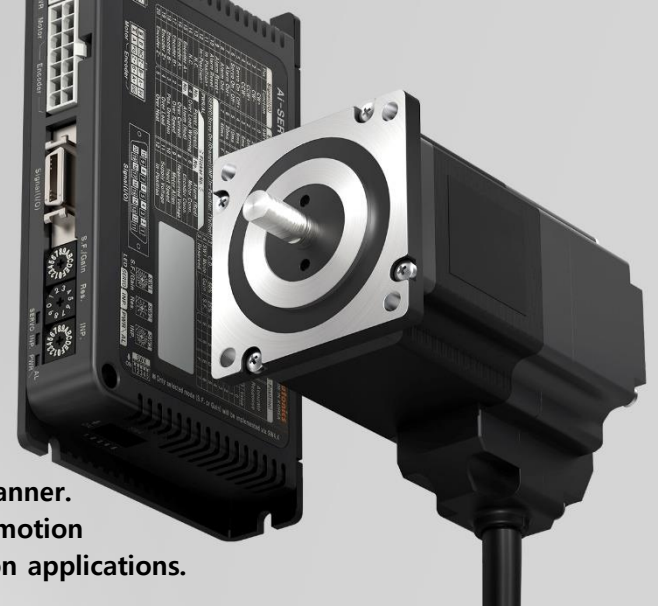


HMI's



Motion Devices

Motion control involves automation of moving parts of machines in a controlled manner. Autonics motion devices, consisting of stepper motors, stepper motor drivers, and motion controllers, provide comprehensive solutions well-suited for a wide variety of motion applications.



Closed Loop Stepper Motor & Drivers



Motion Controllers



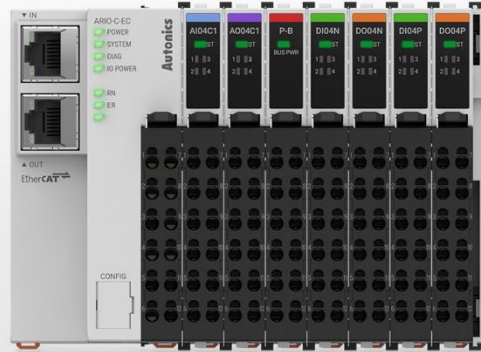
5-Phase Stepper Motor & Drivers



2-Phase Stepper Motor Drivers



Connectivity



Connectivity devices are communication devices used to send and receive signals or data between the environment and information processing systems.

Field Network Devices



Distribution Boxes



Valve Plugs



I/O Terminal Blocks



Connectors



Socket

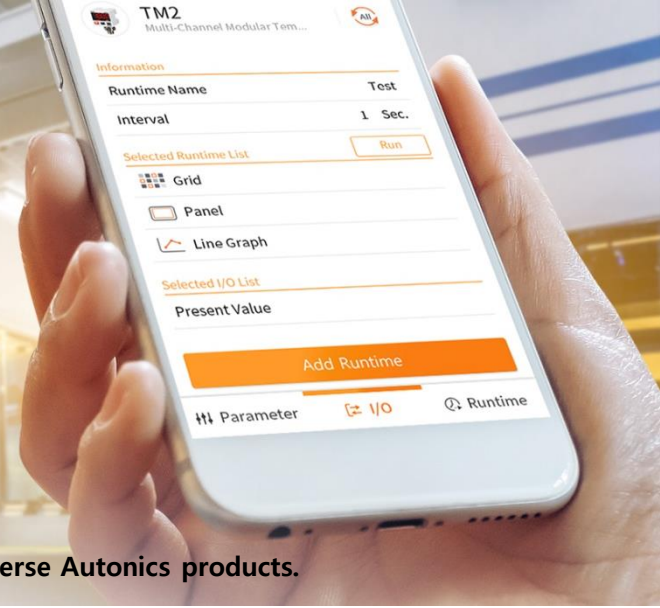


Software

Autonics software offers intuitive GUI interface and simple settings, allowing users to easily configure parameters, monitor and save important data, and create various programs for diverse Autonics products.

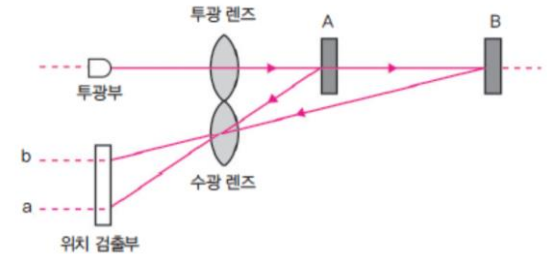
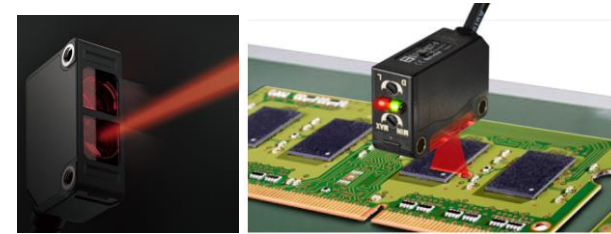
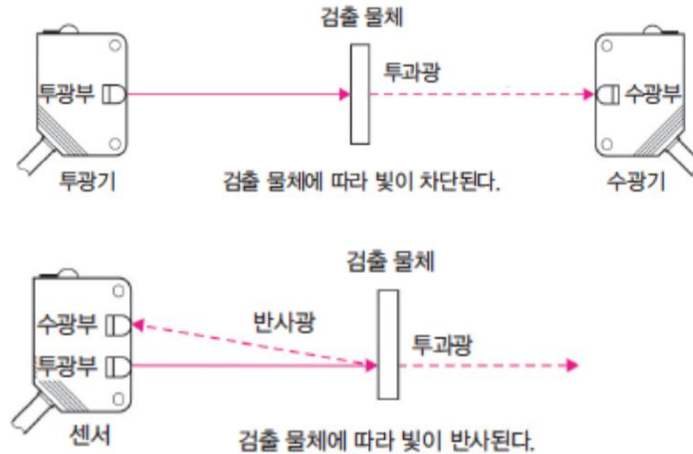
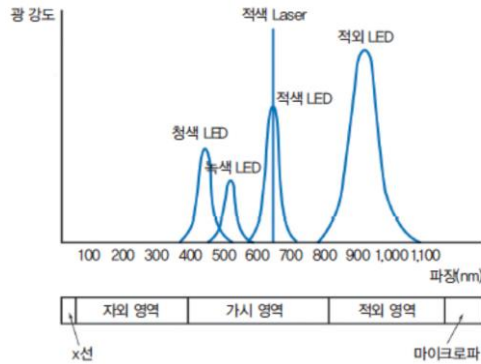
Software

- Device management software (DAQMaster)
- Vision system management software (Vision Master)
- Laser scanner management software (atLidar)
- Motion device management software (atMotion)
- Logic programming software (atLogic)
- GP/LP screen editor (atDesigner, GP Editor)
- DS/DA time sync software (World Clock)



Optical Sensors

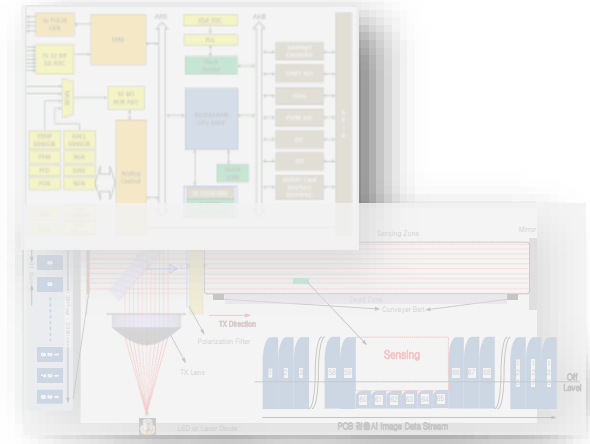
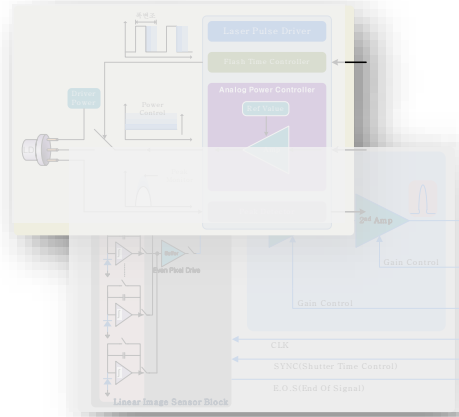
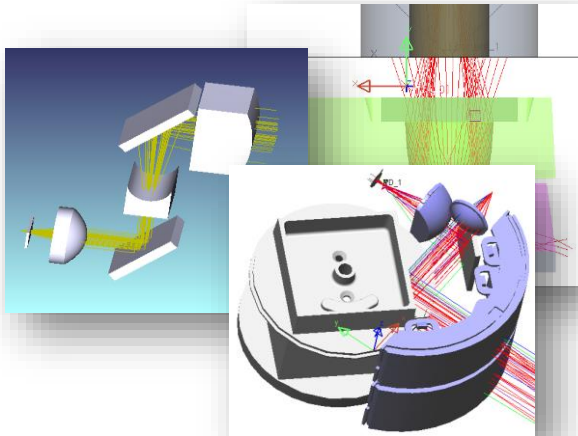
- A sensor that identifies the position(X, Y, Z) / Color / Size of an object of interest using light (visible & infrared light)



Optical Sensor Element Technology

- **Optical Design**

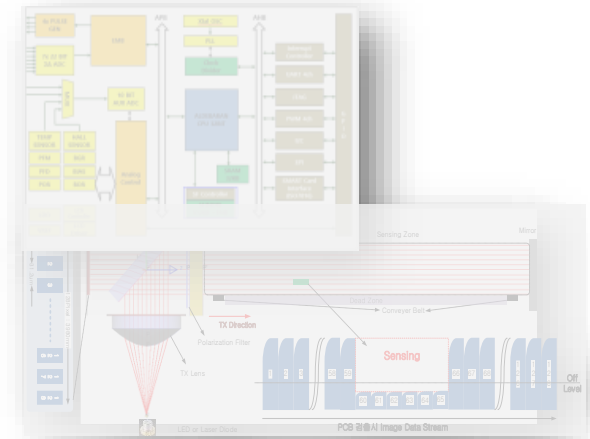
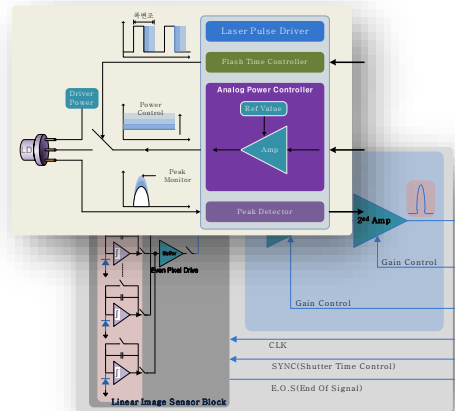
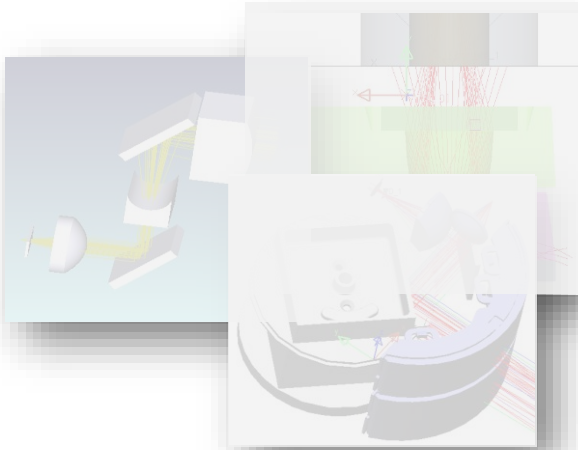
- Optical elements, lenses, and optical systems to emit and receive light
- Mechanical optical axis alignments of optical elements and optical systems.



Optical Sensor Element Technology

Hardware Design

- To handle the emitted light
 - ※ Precision/high speed control processing
- To process receiving light signals
 - ※ Light-receiving circuit design for high-speed response
 - ※ Noise removal processing for small signal



CONTENTS

I Introduction

1. About Autonics

2. Optical Sensors?

3. Optical Sensor Element

II Review Purpose

1. Introduction Background

- Conventional Development

2. Purpose

3. MBD Adaptation

III Detail Review

1. Requirements Management

2. Design

3. Implementation

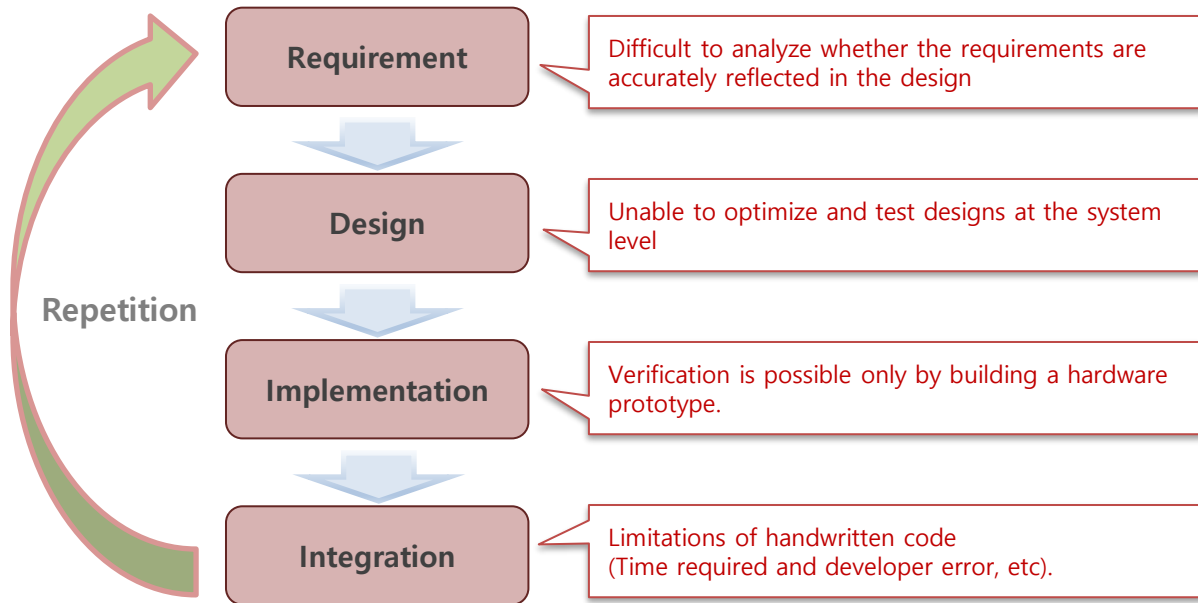
4. Integration and Verification

IV Summary



Conventional Development

- Inconsistency between Requirement, Design and Implementation
- Cost and Time consuming to debug after Implementation
- Too much Legacy Code

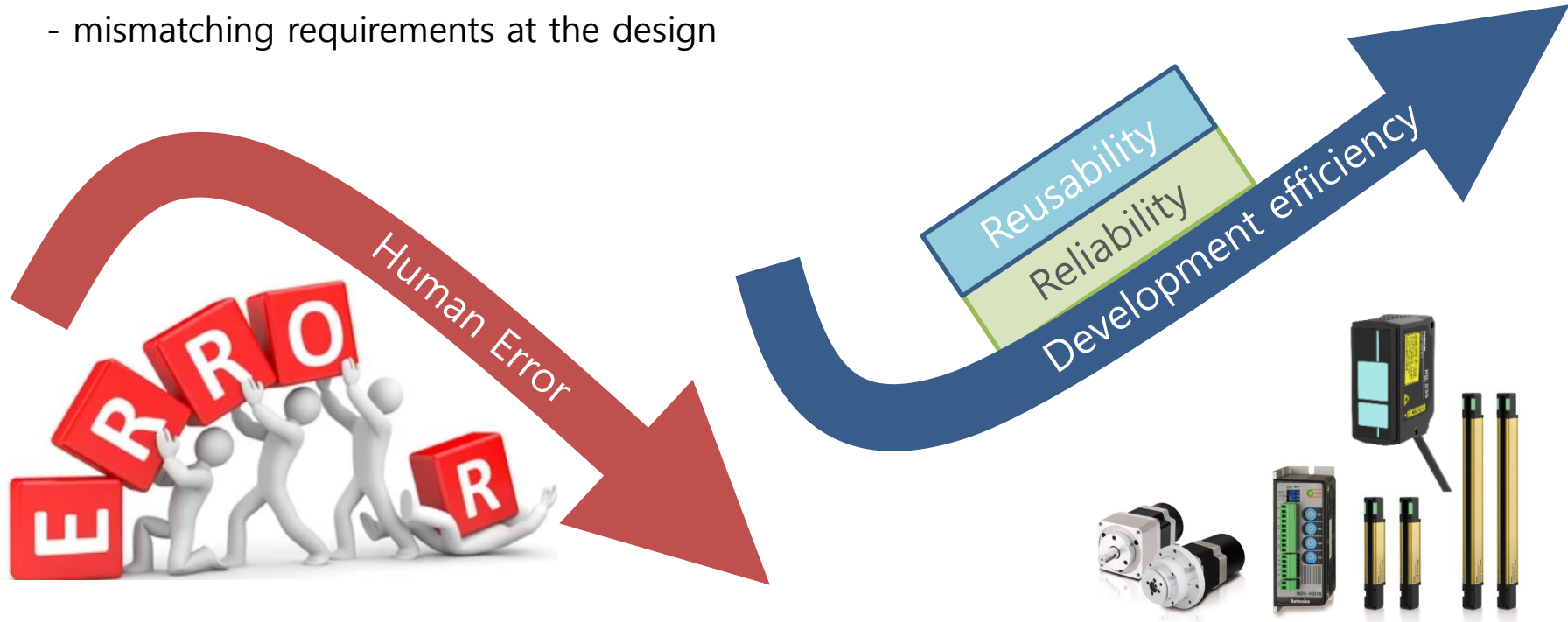


Can a sufficient review be done before actual implementation?



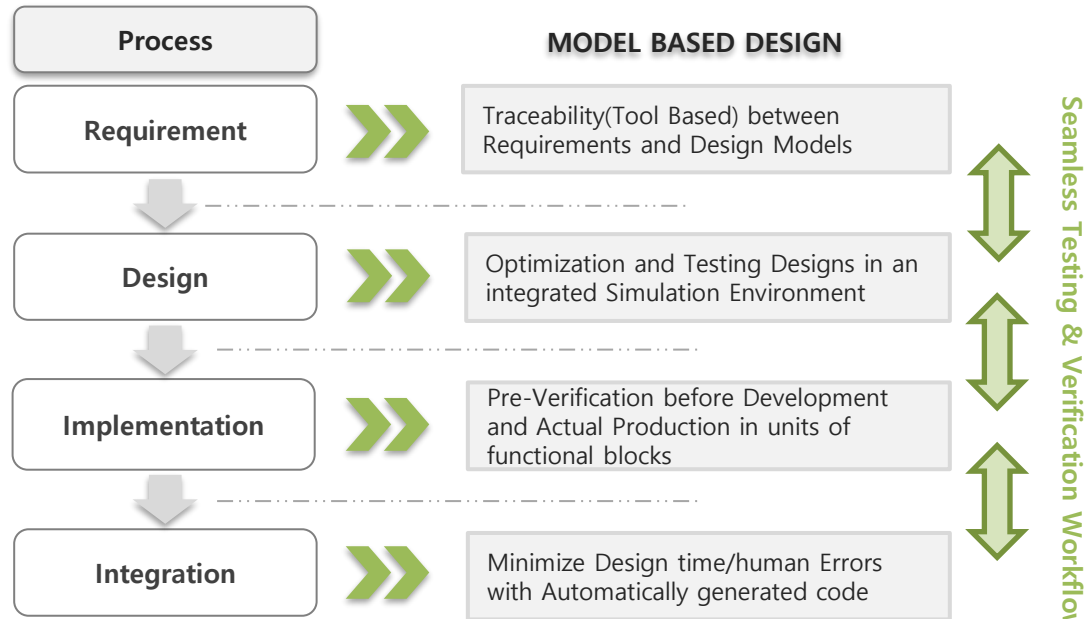
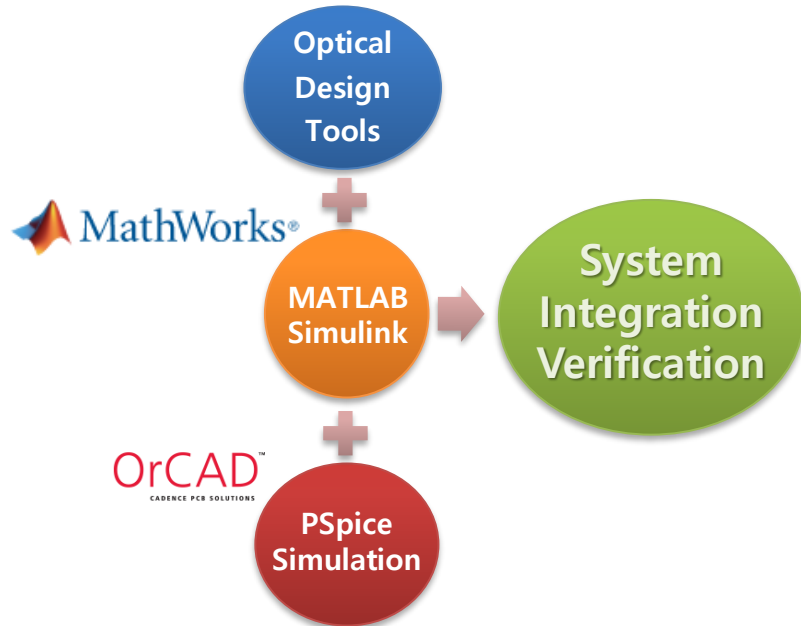
Purpose

- Analysis workflow based on Simulation
- Prevention of Human Errors
 - mismatching requirements at the design



MBD Adaptation

- Performance Prediction Analysis in Model-Based Design
 - By Integrating the Electronic circuit(PSpice) and Optical Analysis results in the Simulink Environment



CONTENTS

I Introduction

1. About Autonics

2. Optical Sensors?

3. Optical Sensor Element

II Review Purpose

1. Introduction Background

- Conventional Development

2. Purpose

3. MBD Adaptation

III Detail Review

1. Requirements Management

2. Design

3. Implementation

4. Integration and Verification

IV Summary



[Appendix] Action Example 1

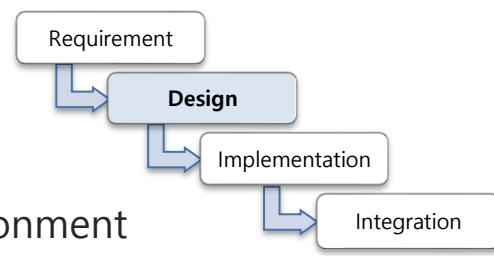
◆ Simulink - Requirement

The screenshot displays a Simulink environment with a requirement table and a block diagram. The requirement table is as follows:

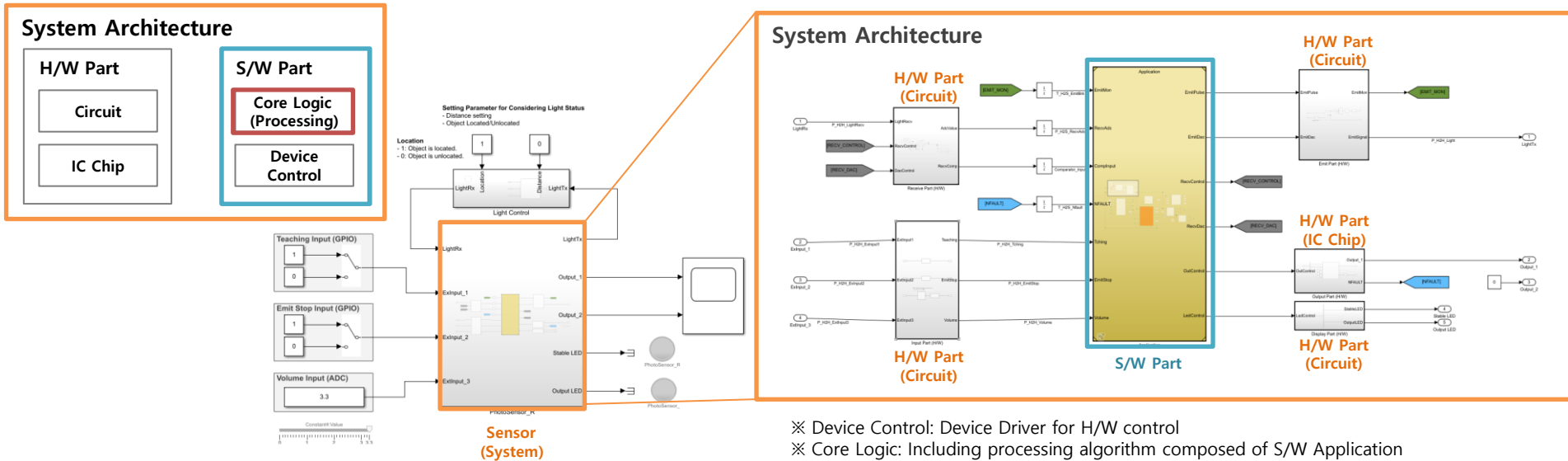
분류	Rev	일자	사유	작성	검토	승인
개발	11.	-	-	-	-	-
	10.	-	-	-	-	-
	9.	-	-	-	-	-
	8.	2021-10-08.	상세 요구사항 점검 및 업데이트.	양승아	-	-
	7.	2021-07-15.	요구사항 항목 정리 (통신&유지보수)	양승아	-	-
	6.	2021-06-07.	STM32G071G8U6의 ADC 검토 결과 반영.	유석재	-	-
	5.	2021-05-21.	공장모델 부트로드 추가.	박현준	-	-
	4.	2021-04-20.	내부 공유 진행 내용 반영.	양승아	-	-
	3.	2021-04-15.	상세 작성 항목 검토 및 내용 보완.	양승아	-	-

The block diagram shows a 'PhotoSensor_R' block with inputs for 'Teaching Input (GPIO)', 'Emit Stop Input (GPIO)', and 'Volume Input (ADC)'. It has outputs for 'LightIn', 'Output_1', 'Output_2', 'State LED', and 'Output LED'. A 'Light Control' block is connected to the 'LightIn' input and the 'Output_1' and 'Output_2' outputs. The diagram also includes a 'PhotoSensor' block and a 'Constant Value' block.

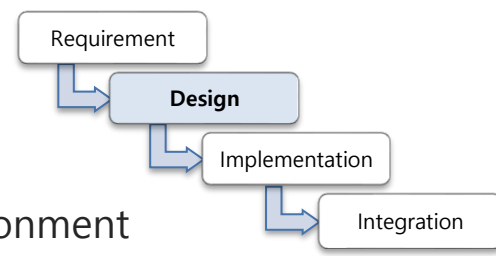
Detailed Design



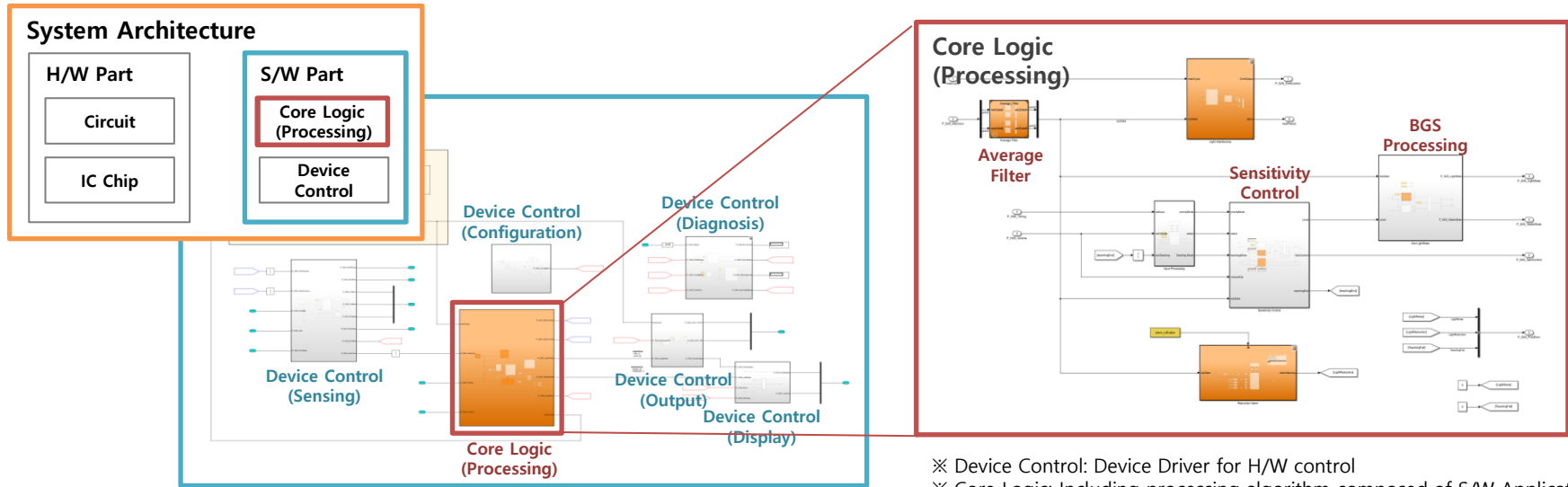
- Design Optimization and Estimation in an Integrated Simulation Environment
 - Configure the Integrated Test Environment based on System Architecture
 - System Configuration → Unit/Integration Test → Code generation



Detailed Design



- Design Optimization and Estimation in an Integrated Simulation Environment
 - Configure the Integrated Test Environment based on System Architecture
 - System Configuration → Unit/Integration Test → Code generation

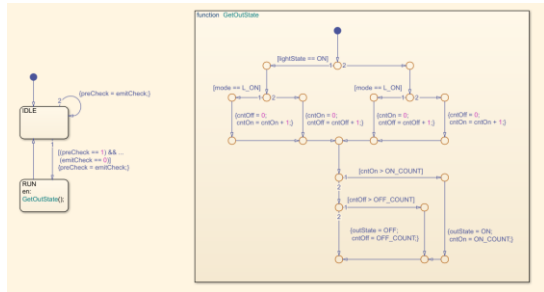
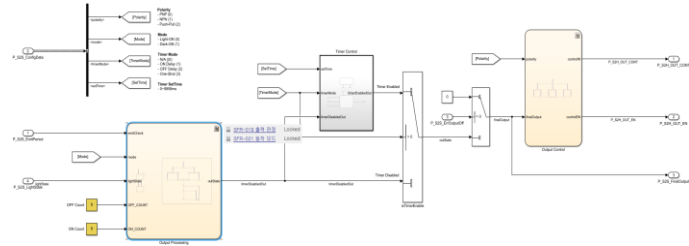


- ※ Device Control: Device Driver for H/W control
- ※ Core Logic: Including processing algorithm composed of S/W Application
- ※ BGS : BackGround Suppress

[Appendix] Simulink Module Test

◆ Optical sensor S/W module test

- Configure test harnesses by functional block and identify test cases based on requirement
- Check the simulation result by changing the input conditions according to the test procedure
- Perform functional unit verification for the designed module

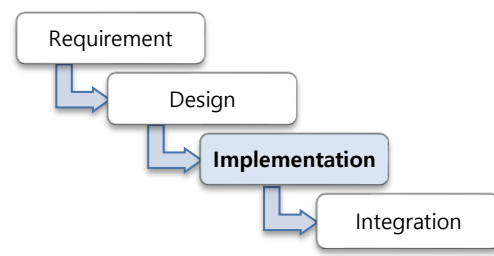


< Modeling block Design >

< Test case & Report >

Testing Method	테스트 절차/시나리오		Input Condition	Output Condition	Related Module
Simulink	<ol style="list-style-type: none"> 1. Simulink Output Block 대해 Test Harness를 구성한다. 2. 연속된 Cycles과 동기화 위한 EmitPeriod에 일정 주기의 Pulse 파형을 인가한다. 3. 최종 출력 판정의 값이 변화하도록 수광 판정 입력 조건을 설정한다. 4. 설정 파라미터의 동작 모드를 변경하여 출력 제어 신호의 변화를 확인한다. 		동작 모드 (설정 파라미터) 수광 판정 결과 (입/자갈 상태)	출력 판정 결과 (검출 결과)	TestHarness_Output_1 Output_SW
No	테스트 조건	입력	출력	테스트 결과	Pass/Fail
1	EmitPeriod : 연속된 동작 사이클에 해당하는 Pulse 신호 인가 (50us) 수광 판정 결과 (LightState) *일정의 입자광 조건 인가 (0.3~0.5s간 입자광 유지)	설정 파라미터: - 동작 모드(Mode) = Light-ON(0) *ON/OFF 카운트는 기본값 적용 (0회)	Light-ON 설정 출력 신호: - 수광 판정 결과가 자갈일 때, FinalOutput = 0(OFF) - 수광 판정 결과가 입자일 때, FinalOutput = 1(ON)		Pass
2	EmitPeriod : 연속된 동작 사이클에 해당하는 Pulse 신호 인가 (50us) 수광 판정 결과 (LightState) *일정의 입자광 조건 인가 (0.3~0.5s간 입자광 유지)	설정 파라미터: - 동작 모드(Mode) = Dark-ON(1) *ON/OFF 카운트는 기본값 적용 (0회)	Dark-ON 설정 출력 신호: - 수광 판정 결과가 자갈일 때, FinalOutput = 1(ON) - 수광 판정 결과가 입자일 때, FinalOutput = 0(OFF)		Pass

Implementation

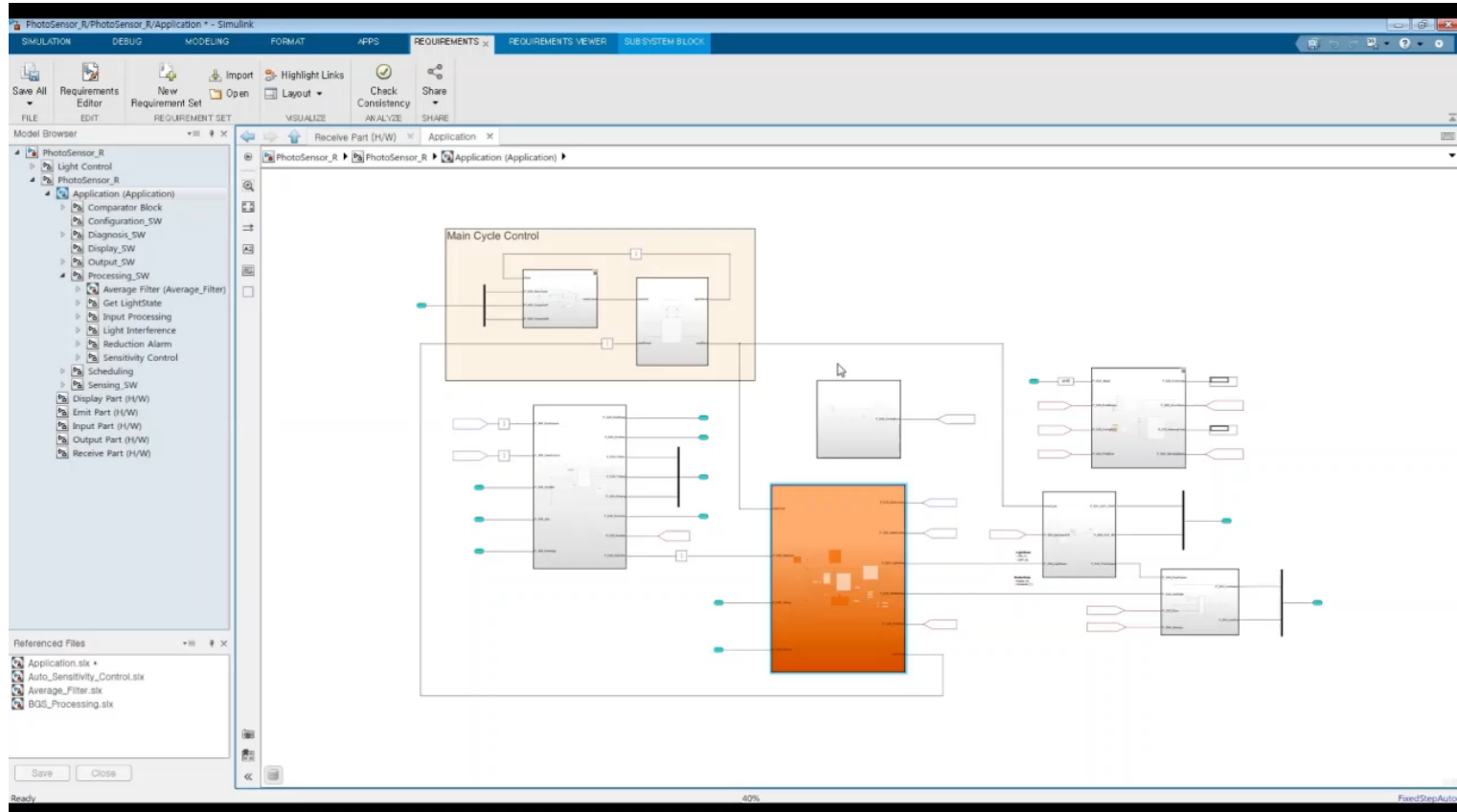


- Fast Implementation with Hardware [**Performance prediction**]
 - Advanced algorithm design using models to some functions of Core Logic
 - Algorithm Design → Simulink Modeling → Verification based on Simulation

<p>Sensitivity Control</p>	<p>✓ Anti-saturation and automatic sensitivity control</p> <p>Design</p>	<p>Modeling</p>	<p>Verification</p>
<p>Average Filter</p>	<p>✓ Moving average filter for noise reduction</p> <p>Design</p> $A[z] = \frac{(A[z] + A[z-2] + A[z-4] + A[z-6])}{4}$ $B[z+1] = \frac{(B[z+1] + B[z] + B[z-1] + B[z-2] + B[z-3] + B[z-4])}{6}$	<p>Modeling</p>	<p>Verification</p>
<p>BGS Processing</p>	<p>✓ B.G.S processing algorithm to improve black and white error</p> <p>Design</p>	<p>Modeling</p>	<p>Verification</p>

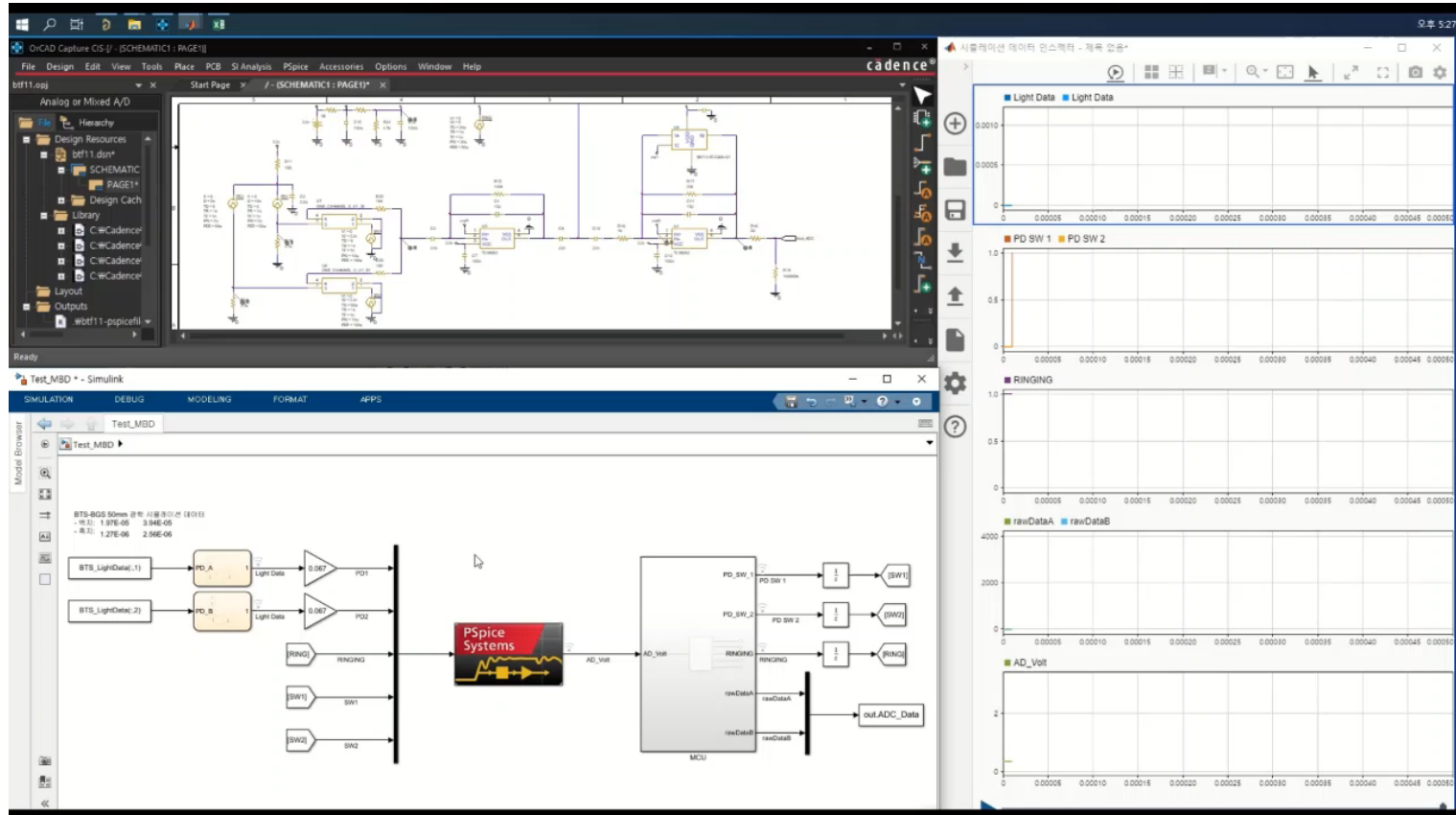
[Appendix] Action Example 2

◆ Simulink – Sensitivity Control



[Appendix] Action Example 3

◆ Simulink - BGS Analysis 1

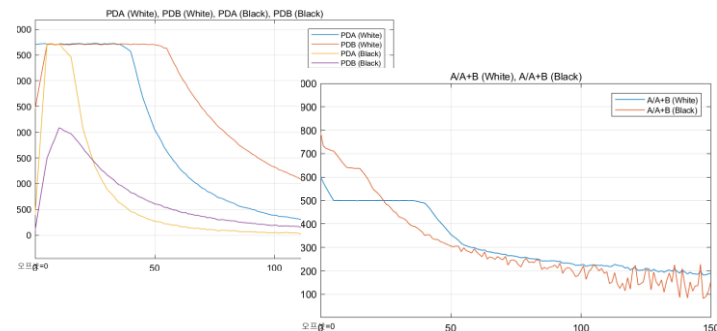
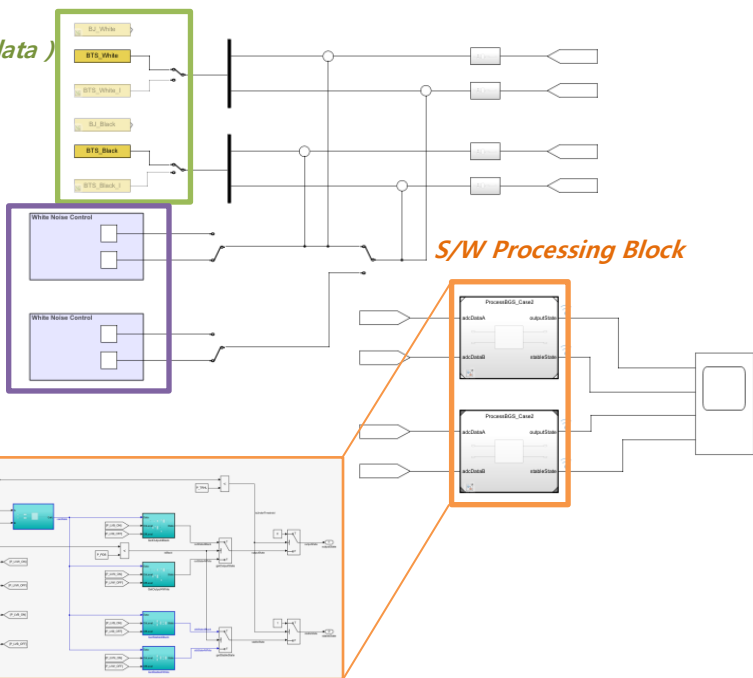
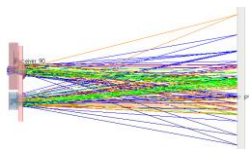


[Appendix] BGS Data Analysis

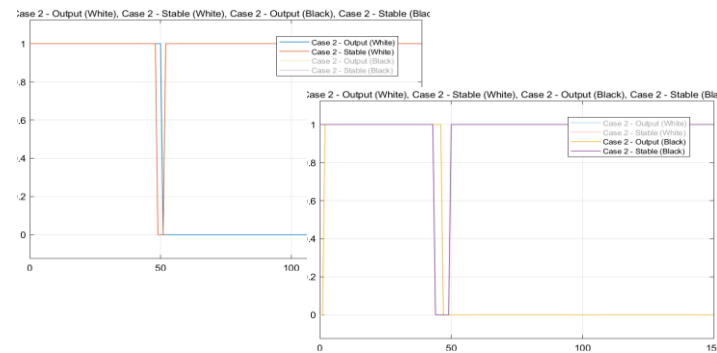
◆ Co-Simulation Extension applied

- Acquire test data by applying specified numerical parameters(Light data, Amp gain & noise, etc) to input data
- Predict the actual system performance of the built-in S/W algorithm
(Maximum detection distance, Hysteresis distance, Black/White Error distance, Etc)

Light data input
by distance (Optical data)



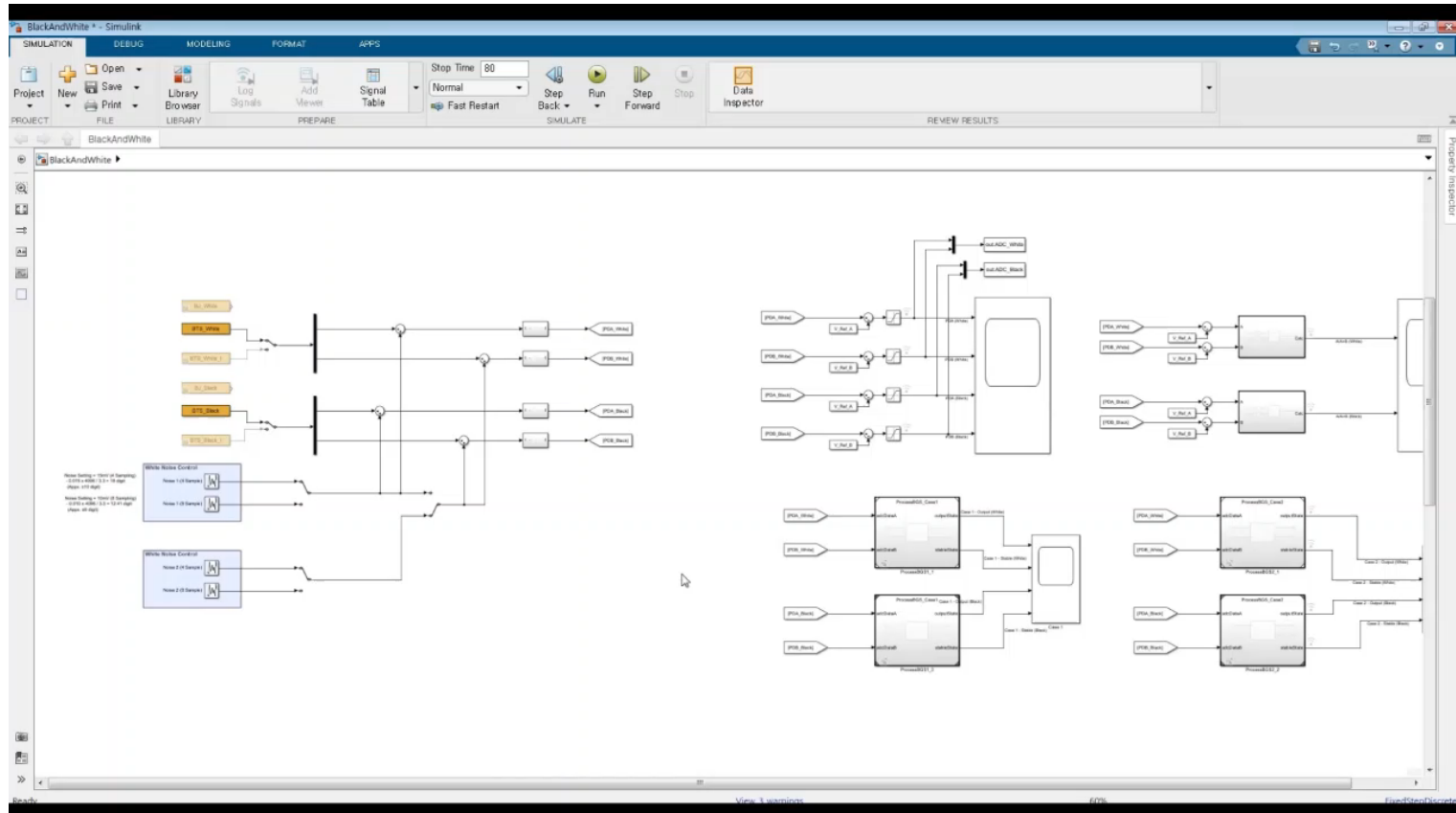
< Check processing result [ratio calculation]>



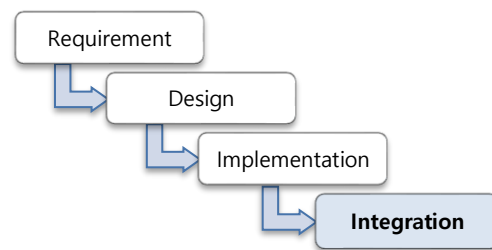
< Check output result [Detection distance]>

[Appendix] Action Example 4

◆ Simulink - BGS Analysis 2

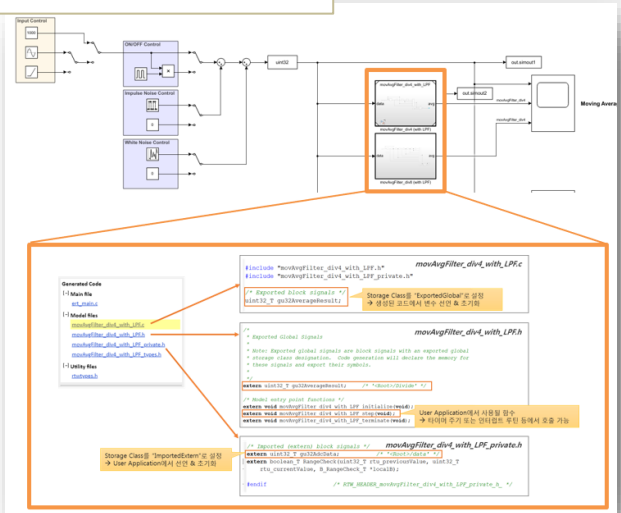


Integration and Verification



- Save the Design Time and Remove Human Errors (Using Auto-Code)
 - Auto-Code generation after verification
 - Real-Time behavior check at the Target
- ※ Reduce coding & debugging time on the real target

Auto-Code Generation



Consistency check at the Real Target

Code Editor:

```

/* Private variables */
uint32_t gu32AdcData = 0;
uint32_t testInput[10] = {991, 986, 1005, 1001, 1013, 996, 1000, 1009, 986, 986};
uint32_t testOutput[10] = {0, };
  
```

Scope Window:

시간	데이터1	시간	데이터1
0	991	0	0
0.1000	986	0.1000	246
0.2000	1005	0.2000	497
0.3000	2004	0.3000	749
0.4000	1013	0.4000	1002
0.5000	996	0.5000	1004
0.6000	1000	0.6000	1003
0.7000	1009	0.7000	1004
0.8000	986	0.8000	997
0.9000	986	0.9000	995
1	1000	1	995
1.1000	1005	1.1000	994
1.2000	985	1.2000	994

Live Watch:

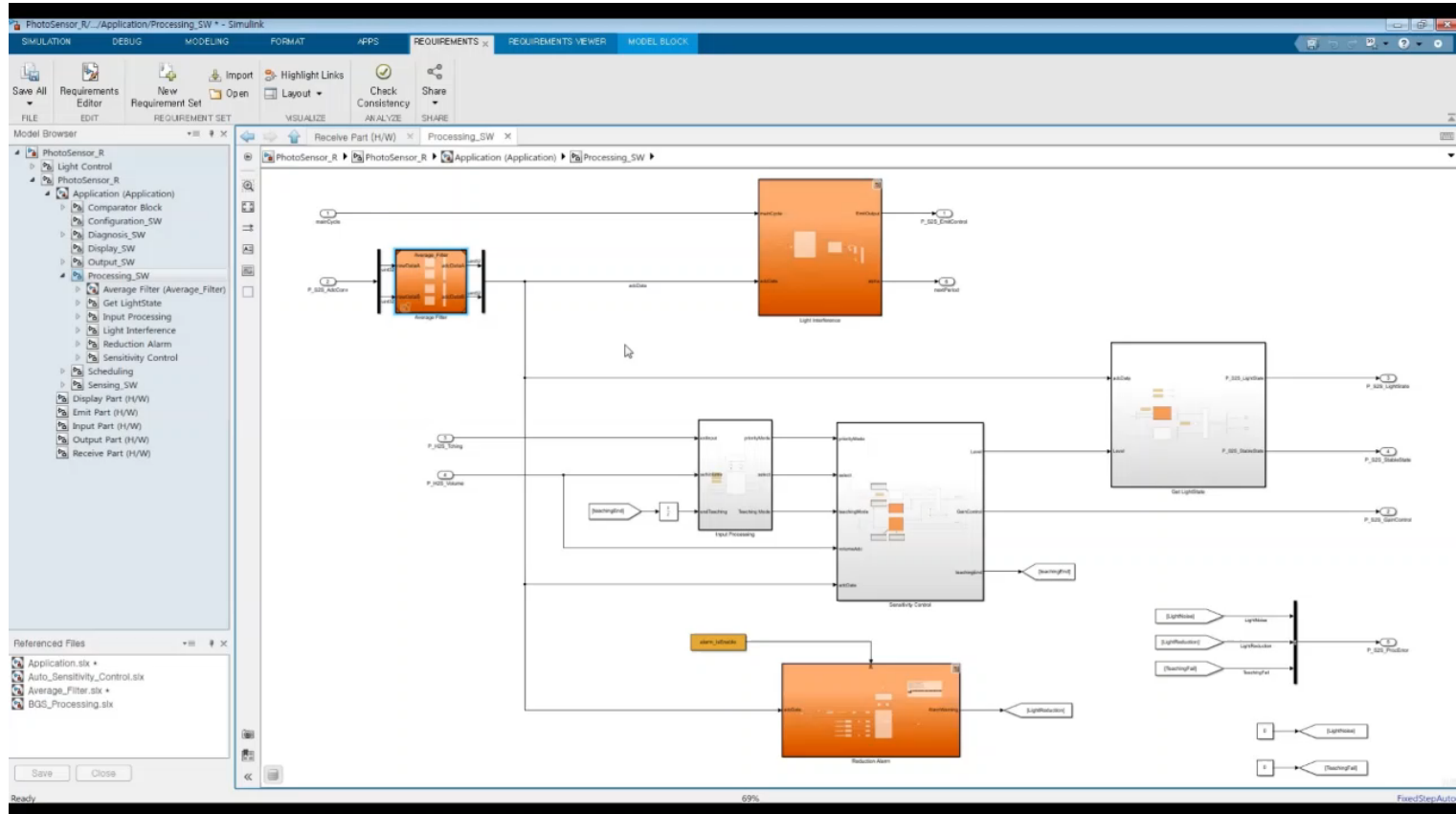
Expression	Value
bDataHalfD...	<array>""
testOutput	<array>""
[0]	0
[1]	246
[2]	497
[3]	749
[4]	1'002
[5]	1'004
[6]	1'003
[7]	1'004
[8]	997
[9]	995

<Debugging 출력 결과>

<Simulink 시뮬레이션 결과>

[Appendix] Action Example 5

◆ Simulink - Code Generation



CONTENTS

I Introduction

1. About Autonics

2. Optical Sensors?

3. Optical Sensor Element

4. Summary

II Review Purpose

1. Introduction Background

- Conventional Development

2. Purpose

3. MBD Adaptation

III Detail Review

1. Requirements Management

2. Design

3. Implementation

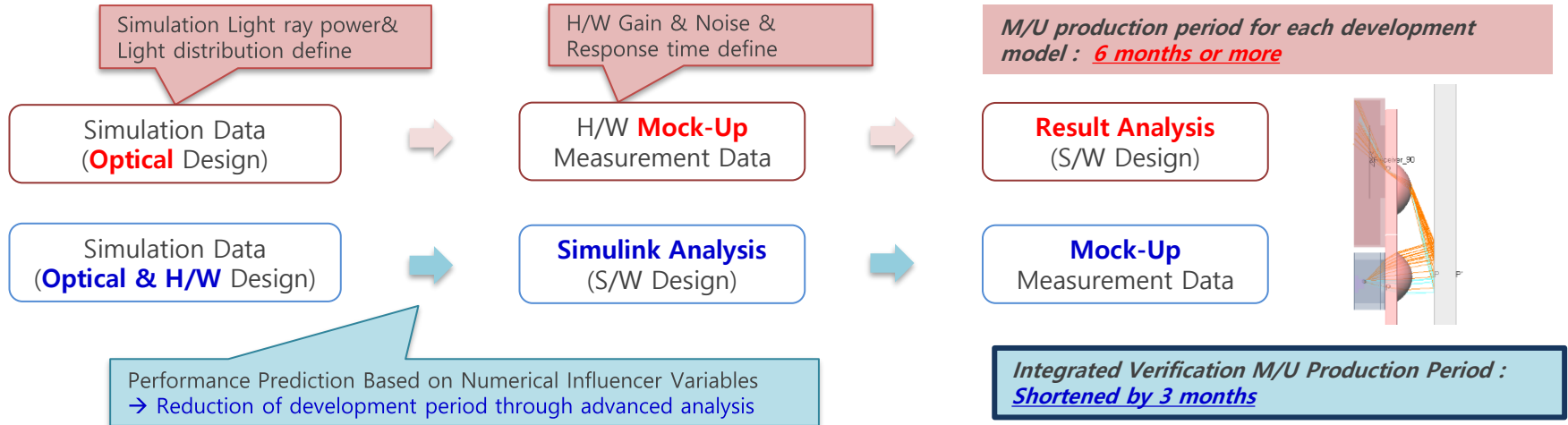
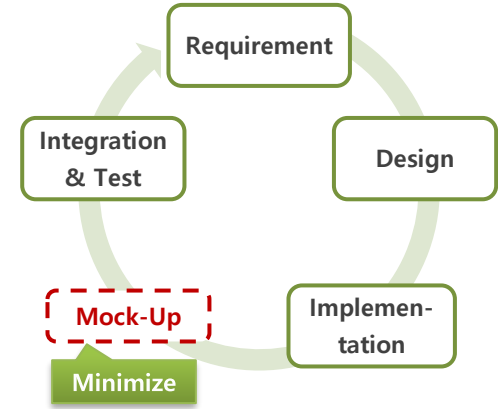
4. Integration and Verification

IV Summary



Summary

- **Advanced data analytics** by matching analysis data
- **Easy and Fast Performance Estimation**
- **Reduction** of pre-verification period and sample production cost
- **Improved Reusability of the performance prediction model**



MATLAB EXPO

Thank you



© 2022 The MathWorks, Inc. MATLAB and Simulink are registered trademarks of The MathWorks, Inc. See [mathworks.com/trademarks](https://www.mathworks.com/trademarks) for a list of additional trademarks. Other product or brand names may be trademarks or registered trademarks of their respective holders.